

SCHOOL OF ELECTRICAL ENGINEERING

B. Tech Electronics and Instrumentation Engineering

(B.Tech EIE)

Curriculum (2019-2020 admitted students)



VISION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

Transforming life through excellence in education and research

MISSION STATEMENT OF VELLORE INSTITUTE OF TECHNOLOGY

World class Education: Excellence in education, grounded in ethics and critical thinking, for improvement of life.

Cutting edge Research: An innovation ecosystem to extend knowledge and solve critical problems.

Impactful People: Happy, accountable, caring and effective workforce and students.

Rewarding Co-creations: Active collaboration with national & international industries & universities for productivity and economic development

Service to Society: Service to the region and world through knowledge and compassion.

VISION STATEMENT OF THE SCHOOL OF ELECTRICAL ENGINEERING

To be a leader for academic excellence in the field of electrical, instrumentation and control engineering imparting high quality education and research leading to global competence for the societal and industrial developments.

MISSION STATEMENT OF THE SCHOOL OF ELECTRICAL ENGINEERING

M1: Impart high quality education and interdisciplinary research by providing conducive teaching learning environment and team spirit resulting in innovation and product development.

M2: Enhance the core competency of the students to cater to the needs of the industries and society by providing solutions in the field of electrical, electronics, instrumentation, and automation engineering.

M3: Develop interpersonal skills, leadership quality and societal responsibility through ethical value-added education.



PROGRAMME EDUCATIONAL OBJECTIVES (PEOs)

The school of Electrical Engineering has established and sustained a welldefined set of educational objectives and preferred program outcomes. Educational objectives of the program satisfy to the requirements of the stakeholders such as students, parents, employers, alumni, faculty etc. The Program Educational Objectives (PEOs) are as follows.

PEO-1: Graduates will be engineering practitioners and leaders, who would help solve industry's technological problems in electrical engineering and allied disciplines.

PEO-2: Graduates will be engineering professionals, innovators or entrepreneurs engaged in technology development, technology deployment, or engineering system implementation in industry.

PEO-3: Graduates will function in their profession with social awareness and responsibility.

PEO-4: Graduates will interact with their peers in other disciplines in industry and society and contribute to the economic growth of the country.

PEO-5: Graduates will be successful in pursuing higher studies leading to careers in engineering, management, teaching, and research.



PROGRAMME OUTCOMES (POs)

POs are statements that describe what students are expected to know and be able to do upon graduating from the program. These relate to the skills, knowledge, analytical ability attitude and behaviour that students acquire through the program.

NBA has defined the following twelve POs for an engineering graduate. These are in line with the Graduate Attributes as defined by the Washington Accord:

PO_01: Engineering Knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.

PO_02: Problem Analysis: Identify, formulate, review research literature, and analyse complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences and engineering sciences.

PO_03: Design / Development of Solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.

PO_04: Conduct Investigations of Complex Problems: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions for complex problems:

• that cannot be solved by straightforward application of knowledge, theories and techniques applicable to the engineering discipline as against problems given at the end of chapters in a typical text book that can be solved using simple engineering theories and techniques

• that may not have a unique solution. For example, a design problem can be solved in many ways and lead to multiple possible solutions that require consideration of appropriate constraints / requirements not explicitly given in



the problem statement such as cost, power requirement, durability, product life, etc.

• which need to be defined (modelled) within appropriate mathematical framework

• that often require use of modern computational concepts and tools, for example, in the design of an antenna or a DSP filter.

PO_05: Modern Tool Usage: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modelling to complex engineering activities with an understanding of the limitations.

PO_06: The Engineer and Society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.

PO_07: Environment and Sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.

PO_08: Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.

PO_09: Individual and Team Work: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.

PO_10: Communication: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.

PO_11: Project Management and Finance: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.

PO_12: Life-long Learning: Recognize the need for, and have the preparation and ability to engage in independent and lifelong learning in the broadest context of technological change.



PROGRAMME SPECIFIC OUTCOMES (PSOs)

On completion of B. Tech. (Electronics and Instrumentation Engineering) programme, graduates will be able to

- PSO1: Design and develop electronics and instrumentation systems for fulfilling socio-economic and environmental requirements.
- PSO2: Analyze and design signal conditioning circuits for sensors, measurement, instrumentation system, process control and automation techniques by considering economic and environmental constraints.
- PSO3: Apply and implement intelligent systems using modern tools for instrumentation engineering.



CREDIT STRUCTURE

Distribution	Credits
University Core (UC)	53
University Elective (UE)	12
Programme Core (PC)	59
Programme Elective (PE)	36
Total	160

Category-wise Credit distribution



DETAILED CURRICULUM

University Core

University Core (53 Credits)							
S. No.	Course Code	Course Title	L	Т	Р	J	С
1.	CHY1701	Engineering Chemistry	3	0	2	0	4
2.	CHY1002	Environmental Sciences	3	0	0	0	3
3.	CSE1001	Problem Solving and Programming	0	0	6	0	3
4.	CSE1002	Problem Solving and Object Oriented Programming	0	0	6	0	3
5.	EEE1901	Technical Answers for Real World Problems (TARP)	1	0	0	4	2
б.	EEE4098	Comprehensive Examination	0	0	0	0	1
7.	EEE4099	Co-op /Capstone Project	0	0	0	0	12
8.	ENG1901/	Technical English I					
	ENG1902/	Technical English II	0/0/0	0/0/0	4/4/2	0/0/4	2
	ENG1903	Advanced Technical English					
9.	ENG 1000/	Foundation English I	0	0	4	0	2
	ENG 2000	Foundation English II					
10.	HUM1021	Ethics and Values	2	0	0	0	2
11.	MAT1011	Calculus for Engineers	3	0	2	0	4
12.	MAT2001	Statistics for Engineers	3	0	2	0	4
13.	MGT1022	Lean Start-up Management	1	0	0	4	2
14.	PHY1701	Engineering Physics	3	0	2	0	4
15.	PHY1901	Introduction to Innovative Projects	1	0	0	0	1
16.	EXC4097	Extra & Co- Curricular Activities	0	0	0	0	2
17.	EEE1902	Industrial Internship	0	0	0	0	1
18.	FLC4097	Foreign Language Courses Basket	2	0	0	0	2
19.	STS4097	Soft Skills		_	_	_	6



Programme Core

	Programme Core (59 Credits)							
S. No.	Course Code	Course Title	L	Т	Р	J	C	
1.	EEE1002	Electric Circuits	3	0	0	0	3	
2.	EEE1004	Engineering Electromagnetics	3	0	2	0	4	
3.	EEE1005	Signals and Systems	3	0	0	0	3	
4.	EEE2001	Network Theory	3	0	0	0	3	
5.	EEE2002	Semiconductor Devices and Circuits	2	0	2	4	4	
6.	EEE2005	Digital Signal Processing	2	0	2	0	3	
7.	EEE3001	Control Systems	3	0	2	0	4	
8.	EEE3002	Analog and Digital Circuits	3	0	2	0	4	
9.	EEE4001	Microprocessor and Microcontroller	2	0	2	0	3	
10.	EEE4021	Sensors and Signal Conditioning	3	0	2	0	4	
11.	EEE4031	Electrical and Electronic Instrumentation	3	0	2	0	4	
12.	EEE4032	Process Automation and Control	3	0	2	0	4	
13.	EEE4033	Industrial Instrumentation	3	0	0	4	4	
14.	MAT2002	Applications of Differential and Difference Equations	3	0	2	0	4	
15.	MAT3003	Complex Variables and Partial Differential Equations	3	1	0	0	4	
16.	MAT3005	Applied Numerical Methods	3	1	0	0	4	



Programme Elective

S. No.	Course Code	Course Title	L	Т	Р	J	C
1.	EEE1007	Neural Network and Fuzzy Control	2	0	0	4	3
2.	EEE1008	Bio-Medical Instrumentation	3	0	0	4	4
3.	EEE1011	Automated Test Engineering	2	0	2	0	3
4.	EEE1012	Optoelectronic Instrumentation	3	0	0	0	3
5.	EEE1013	Analytical Instrumentation	3	0	0	0	3
6.	EEE1014	Fiber Optic Sensors	3	0	0	0	3
7.	EEE1015	Micro Electromechanical Systems	3	0	0	4	4
8.	EEE1016	Non-Destructive Testing	3	0	0	0	3
9.	EEE1018	Nanotechnology Fundamentals and its Applications	3	0	0	0	3
10.	EEE1020	Engineering Optimization	2	1	0	4	4
11.	EEE2006	Communication Engineering	3	0	2	0	4
12.	EEE2008	Electrical Technology	3	0	2	0	4
13.	EEE3008	Data Communication Network	3	0	0	0	3
14.	EEE3009	Digital Image Processing	3	0	0	4	4
15.	EEE4018	Advanced Control Theory	3	0	0	4	4
16.	EEE4019	Advanced Digital System Design With FPGAs	2	0	0	4	3
17.	EEE4020	Embedded System Design	2	0	0	4	3
18.	EEE4022	Analog VLSI Design	3	0	0	0	3
19.	EEE4024	Computer Architecture and Organization	3	0	0	0	3
20.	EEE4026	Digital Control Systems	2	0	0	4	3
21.	EEE4027	Robotics and Control	2	0	0	4	3
22.	EEE4028	VLSI Design	3	0	2	0	4
23.	EEE4029	Advanced Microcontrollers	2	0	0	4	3



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24.	EEE4030	System on Chip Design	3	0	0	4	4
25.	EEE4034	Wireless Sensor Networks	3	0	0	4	4
26.	EEE4035	Virtual Instrumentation	0	0	2	4	2
27.	EEE4037	Rapid Prototyping with FPGAs	0	0	4	0	2
28.	EEE4038	Testing and Calibration Systems	0	0	2	0	1
29.	MEE1006	Applied Mechanics and Thermal Engineering	2	0	2	0	3
30.	ECE3501	IoT Fundamentals	2	0	2	4	4
31.	ECE3502	IoT Domain Analyst	2	0	2	4	4

University Elective Baskets

Management courses

Sl.No	Code	Title	L	T	Р	J	C
1	MGT1001	Basic Accounting	3	0	0	0	3
2	MGT1002	Principles of Management	2	0	0	4	3
3	MGT1003	Economics for Engineers	2	0	0	4	3
4	MGT1004	Resource Management	2	0	0	4	3
5	MGT1005	Design, Systems and Society	2	0	0	4	3
6	MGT1006	Environmental and Sustainability Assessment	2	0	0	4	3
7	MGT1007	Gender, Culture and Technology	2	0	0	4	3
8	MGT1008	Impact of Information Systems on Society	2	0	0	4	3
9	MGT1009	Technological Change and Entrepreneurship	2	0	0	4	3
10	MGT1010	Total Quality Management	2	2	0	0	3
11	MGT1014	Supply Chain Management	3	0	0	0	3
12	MGT1015	Business Mathematics	3	0	0	0	3
13	MGT1016	Intellectual Property Rights	3	0	0	0	3
14	MGT1017	Business Regulatory Framework For Start- ups	3	0	0	0	3
15	MGT1018	Consumer Behaviour	3	0	0	0	3



		(Deemed to be University under section 3 of UGC Act, 1956)					
16	MGT1019	Services Marketing	3	0	0	0	3
17	MGT1020	Marketing Analytics	2	0	2	0	3
18	MGT1021	Digital and Social Media Marketing	3	0	0	0	3
19	MGT1022	Lean Start-up Management	1	0	0	4	2
20	MGT1023	Fundamentals of Human Resource Management	3	0	0	4	4
21	MGT1024	Organizational Behaviour	3	0	0	4	4
22	MGT1025	Foundations of Management And Organizational Behaviour	3	0	0	4	4
23	MGT1026	Information Assurance and Auditing	2	0	0	4	3
24	MGT1028	Accounting and Financial Management	2	2	0	4	4
25	MGT1029	Financial Management	2	1	0	4	4
26	MGT1030	Entrepreneurship Development	3	0	0	4	4
27	MGT1031	International Business	3	0	0	4	4
28	MGT1032	Managing Asian Business	3	0	0	4	4
29	MGT1033	Research Methods in Management	2	1	0	4	4
30	MGT1034	Project Management	3	0	0	4	4
31	MGT1035	Operations Management	3	0	0	0	3
32	MGT1036	Principles of Marketing	3	0	0	4	4
33	MGT1037	Financial Accounting and Analysis	2	1	0	4	4
34	MGT1038	Financial Econometrics	2	0	0	4	3
35	MGT1039	Financial Markets and Institutions	2	0	0	4	3
36	MGT1040	Personal Financial Planning	2	0	0	4	3
37	MGT1041	Financial Derivatives	2	1	0	4	4
38	MGT1042	Investment Analysis and Portfolio Management	2	0	0	4	3
39	MGT1043	Applications in Neuro Marketing	3	0	0	4	4
40	MGT1044	Global Brand Marketing Strategies	3	0	0	4	4
41	MGT1045	Industrial Marketing	3	0	0	4	4
42	MGT1046	Sales and Distribution Management	3	0	0	4	4



43	MGT1047	Social Marketing	3	0	0	4	4
44	MGT1048	Political Economy of Globalization	3	0	0	4	4
45	MGT1049	Sustainable Business Models	3	0	0	4	4
46	MGT1050	Software Engineering Management	2	0	0	4	3
47	MGT1051	Business Analytics for Engineers	2	2	0	0	3
48	MGT1052	Bottom of the Pyramid Operations	3	0	0	0	3
49	MGT1053	Entrepreneurship Development, Business Communication and IPR	1	0	2	0	2
50	MGT1054	Product Planning and Strategy	2	2	0	0	3
51	MGT1055	Design Management	2	2	0	0	3
52	MGT1056	Accounting and Financial Management	3	0	0	4	4
53	MGT6001	Organizational Behaviour	2	0	0	4	3

Humanities courses

Sl.No	Code	Title	L	T	P	J	C
1	HUM1001	Fundamentals of Cyber Laws	3	0	0	0	3
2	HUM1002	Business Laws	3	0	0	0	3
3	HUM1003	Basic Taxation for Engineers	3	0	0	0	3
4	HUM1004	Corporate Law for Engineers	3	0	0	0	3
5	HUM1005	Cost Accounting for Engineers	3	0	0	0	3
6	HUM1006	Business Accounting for Engineers	3	0	0	0	3
7	HUM1007	Contemporary Legal Framework for Business	3	0	0	0	3
8	HUM1009	International Business	3	0	0	0	3
9	HUM1010	Foreign Trade Environment	3	0	0	0	3
10	HUM1011	Export Business	3	0	0	0	3
11	HUM1012	Introduction to Sociology	3	0	0	0	3
12	HUM1013	Population Studies	3	0	0	0	3
13	HUM1021	Ethics and Values	2	0	0	0	2



HUM1022	Psychology in Everyday Life	2	0	0	4	2
HUM1023	Indian Heritage and Culture	2	0	0	4	2
HUM1024	India and Contemporary World	2	0	0	4	2
HUM1025	Indian Classical Music	1	0	2	4	1
HUM1033	Micro Economics	3	0	0	0	3
HUM1034	Macro Economics	3	0	0	0	3
HUM1035	Introductory Econometrics	2	0	2	0	2
HUM1036	Engineering Economics and Decision Analysis	2	0	0	4	2
HUM1037	Applied Game Theory	2	0	0	4	2
HUM1038	International Economics	3	0	0	0	3
HUM1039	Community Development in India	2	0	0	4	2
HUM1040	Indian Social Problems	3	0	0	0	3
HUM1041	Indian Society Structure and Change	3	0	0	0	3
HUM1042	Industrial Relations and Labour Welfare in India	3	0	0	0	3
HUM1043	Mass Media and Society	2	0	0	4	2
HUM1044	Network Society	3	0	0	0	3
HUM1045	Introduction to Psychology	2	0	2	0	2
HUM1706	Business Accounting for Engineers	3	0	0	0	3
	HUM1023 HUM1024 HUM1025 HUM1033 HUM1034 HUM1035 HUM1036 HUM1037 HUM1038 HUM1039 HUM1040 HUM1041 HUM1043 HUM1044 HUM1045	HUM1023Indian Heritage and CultureHUM1024India and Contemporary WorldHUM1025Indian Classical MusicHUM1033Micro EconomicsHUM1034Macro EconomicsHUM1035Introductory EconometricsHUM1036Engineering Economics and Decision AnalysisHUM1037Applied Game TheoryHUM1038International EconomicsHUM1039Community Development in IndiaHUM1040Indian Social ProblemsHUM1041Indian Society Structure and ChangeHUM1042Industrial Relations and Labour Welfare in IndiaHUM1043Mass Media and SocietyHUM1044Network SocietyHUM1045Introduction to Psychology	HUM1023Indian Heritage and Culture2HUM1024India and Contemporary World2HUM1025Indian Classical Music1HUM1033Micro Economics3HUM1034Macro Economics3HUM1035Introductory Econometrics2HUM1036Engineering Economics and Decision Analysis2HUM1037Applied Game Theory2HUM1038International Economics3HUM1040Indian Social Problems3HUM1041Indian Society Structure and Change3HUM1042Industrial Relations and Labour Welfare in India3HUM1043Mass Media and Society2HUM1044Network Society3HUM1045Introduction to Psychology2	HUM1023Indian Heritage and Culture20HUM1024India and Contemporary World20HUM1025Indian Classical Music10HUM1033Micro Economics30HUM1034Macro Economics30HUM1035Introductory Econometrics20HUM1036Engineering Economics and Decision Analysis20HUM1037Applied Game Theory20HUM1038International Economics30HUM1039Community Development in India20HUM1040Indian Social Problems30HUM1041Industrial Relations and Labour Welfare in India30HUM1043Mass Media and Society20HUM1044Network Society30HUM1045Introduction to Psychology20	HUM1023Indian Heritage and Culture200HUM1024India and Contemporary World200HUM1025Indian Classical Music102HUM1033Micro Economics300HUM1034Macro Economics300HUM1035Introductory Econometrics202HUM1036Engineering Economics and Decision Analysis200HUM1037Applied Game Theory200HUM1038International Economics300HUM1040Indian Social Problems300HUM1041Indian Society Structure and Change300HUM1042Industrial Relations and Labour Welfare in India300HUM1043Mass Media and Society200HUM1044Network Society300	HUM1023Indian Heritage and Culture2004HUM1024India and Contemporary World2004HUM1025Indian Classical Music1024HUM1033Micro Economics3000HUM1034Macro Economics3000HUM1035Introductory Econometrics2020HUM1036Engineering Economics and Decision Analysis2004HUM1037Applied Game Theory2004HUM1038International Economics3000HUM1039Community Development in India2004HUM1041Indian Society Structure and Change3000HUM1042Industrial Relations and Labour Welfare in India3000HUM1043Mass Media and Society2004HUM1044Network Society3000



	(Deemed to be University under section 3 of UGC A	et, 1956)				
CHY1002	Environmental Sciences	L	Т	P	J	С
		3	0	0	0	3
Pre-requisite	NIL	Sy	llabu	s versi	ion	
						v:1.1
Course Objectives:						
1. To make students	understand and appreciate the unity of life	e in all i	its for	ms, the	•	
	style on the environment.					
	e various causes for environmental degrada					
	lividuals contribution in the environmental	-				
	impact of pollution at the global level and	d also ii	n the l	ocal		
environment.						
Expected Course O						
1. Students will be						
	cognize the environmental issues in a pro-	blem of	rienteo	1		
interdisciplinar						
	nderstand the key environmental issues, t	the scien	nce be	hind th	nose	
	otential solutions.					
	emonstrate the significance of biodiversi	ty and 1	ts pre	servati	on	
	lentify various environmental hazards	f				
	esign various methods for the conservation					
	rmulate action plans for sustainable alternative and social aspects	nauves	that h	icorpo	rate	
	ity, and social aspects ave foundational knowledge enabling them	n to mo	ka sa	ind life	. daa	iciona
	a career in an environmental profession or					.1510115
as well as enter	a career in an environmental profession of	i inglici	cuuc	ation.		
Module:1	Environment and Ecosystem	7	' hour	s		
				2		
Key environmental	problems, their basic causes and sustainal	ble solu	tions.	IPAT	equ	ation.
Ecosystem, earth –	life support system and ecosystem compo	nents; l	Food o	chain, :	food	web,
Energy flow in ecos	ystem; Ecological succession- stages invo	olved, F	° rimar	y and a	seco	ndary
succession, Hydrarc	h, mesarch, xerarch; Nutrient, water, carbo	on, nitro	ogen,	cycles	; Eff	ect of
human activities						
on these cycles.						
Module:2	Biodiversity	61	nours			
Importance, types, n	nega-biodiversity; Species interaction - Ex	tinct, e	ndemi	c, enda	ange	red
	t-spots; GM crops- Advantages and disadv					
biodiversity and Aqu		U				
	icance, Threats due to natural and anthrop	ogenic	activi	ties an	d	
Conservation metho	de					



Module:3	Sustaining Natural Resources and Environmental Quality	7 hours
Chemical hazards- of hazards. Water f its conservation. So	ards – causes and solutions. Biological BPA, PCB, Phthalates, Mercury, Nuclear ootprint; virtual water, blue revolution. W lid and ypes and waste management methods.	hazards- Risk and evaluation
Module:4	Energy Resources	6 hours
gas, Coal, Nuclear e Hydroelectric	enewable energy resources- Advantages an energy. Energy efficiency and renewable en nal energy, Wind and geothermal energy. En n.	nergy. Solar energy,
Module:5	Environmental Impact Assessme	ent 6 hours
assessment	ental Protection Act – Air, water, forest and olic awareness. Environmental priorities in	
Module:6	Human Population Change and Environment	6 hours
development – Impa	al problems; Consumerism and waste prod act of population age structure – Women a taining human societies: Economics, enviro	nd child welfare, Women
Module:7	Global Climatic Change and Mitigation	5 hours
protocol, Carbon credits, Carl	Green house effect, Ozone layer depletion bon sequestration methods and Montreal P onment-Case Studies.	-
Module:8	Contemporary issues	2 hours
Lecture by Indust		
	Total Lecture hours:	45 hours
Text Books 1.	G. Tyler Miller and Scott E. Spoolr Science, 15 th Edition, Cengage lear	
	Science, 15 Euliton, Cengage lear	



Reference Books							
1.	David M.Has	senzahl, Mary	Catherine	Hager, Linda			
	R.Berg (2011), Visualizing Environmental Science,						
	4thEdition, John Wiley & Sons, USA.						
Mode of evaluation: Intern	Mode of evaluation: Internal Assessment (CAT, Quizzes, Digital Assignments) & FAT						
Recommended by Board							
of Studies	of Studies						
Approved by Academic	46 th AC	Date		24.08.2017			
Council							



	(Deemed to be University under section 3 of UGC Act, 1956)	
CHY1701	Engineering Chemistry	
D • • •		
Pre-requisite	NIL	Syllabus version
Correct Objection		v.1
Course Objective		
	echnological aspects of applied chemistry	
	ndation for practical application of chemistry in engineering a	aspects
•	Outcomes (CO): Students will be able to	
	analyze the issues related to impurities in water and their ren	
	nt methodologies in water treatment for domestic and industri	0
2. Evaluate t of metals	he causes of metallic corrosion and apply the methods for c	orrosion protection
	he electrochemical energy storage systems such as lithium	battarias fuel cells
	ells, and design for usage in electrical and electronic application	
	quality of different fossil fuels and create an awarenes	
alternative		ss to ucvelop the
	e properties of different polymers and distinguish the polymers	mers which can be
•	nd demonstrate their usefulness	iners which can be
	theoretical aspects: (a) in assessing the water quality; (b) u	understanding the
	n and working of electrochemical cells; (c) analyzing meta	
	imental methods; (d) evaluating the viscosity and water abso	-
polymeric		
Module:1 Wate	r Technology	5 hours
Characteristics of h	ard water - hardness, DO, TDS in water and their determined	nation – numerical
problems in hardne	ss determination by EDTA; Modern techniques of water ana	alysis for industrial
use - Disadvantages	of hard water in industries.	
	r Treatment	8 hours
	thods: - Lime-soda, Zeolite and ion exchange processes and t	
-	vater for domestic use (ICMR and WHO); Unit processes	
	ipal supply - Sedimentation with coagulant- Sand Filtration -	
±	ification – Candle filtration- activated carbon filtration; Dis	sinfection methods-
	reatment, Ozonolysis, Reverse Osmosis; Electro dialysis.	
	osion	<u>6 hours</u>
•	ion - detrimental effects to buildings, machines, devices & de	
1 0	rential aeration, Pitting, Galvanic and Stress corrosion crac	cking; Factors that
ennance corrosion a	and choice of parameters to mitigate corrosion.	
Module:4 Corr	osion Control	4 hours
Corrosion protection	n - cathodic protection - sacrificial anodic and impressed	
	protective coatings: electroplating and electroless plating, PV	
	on protection – Basic concepts of Eutectic composition and	Eutectic mixtures -
Alloying for corros	- Ferrous and non-ferrous alloys.	Eutectic mixtures -
Alloying for corros Selected examples -	· · · ·	6 hours
Alloying for corros Selected examples - Module:5 Elec Brief introduction	- Ferrous and non-ferrous alloys. trochemical Energy Systems to conventional primary and secondary batteries; High energy	6 hours gy electrochemical
Alloying for corros Selected examples - Module:5 Elec Brief introduction energy systems: L	- Ferrous and non-ferrous alloys. trochemical Energy Systems	6 hours gy electrochemical
Alloying for corros Selected examples - Module:5 Elec Brief introduction energy systems: L applications.	- Ferrous and non-ferrous alloys. trochemical Energy Systems to conventional primary and secondary batteries; High energiation in the secondary, its Chemistry to batteries – Primary and secondary, its Chemistry	6 hours gy electrochemical y, advantages and
Alloying for corros Selected examples - Module:5 Elec Brief introduction energy systems: I applications.	- Ferrous and non-ferrous alloys. trochemical Energy Systems to conventional primary and secondary batteries; High energy	6 hours gy electrochemical y, advantages and



		(Deemed to be University under section 3 of UGC Ad		
		Types - Importance of silicon single crystal, poly	•	-
		e sensitized solar cells - working principles, charac	teristics and ap	
		Fuels and Combustion		8 hours
		e - Definition of LCV, HCV. Measurement of calo	orific value usi	ng bomb calorimeter
	•	lorimeter including numerical problems.		
		ombustion of fuels - Air fuel ratio – minimum c		
-		erical problems-three way catalytic converter- sele	•	c reduction of NO_X ;
	U	IC engines-Octane and Cetane number - Antiknocki	ing agents.	
		Polymers		6 hours
		etween thermoplastics and thermosetting plastics; E		
		TFE and Bakelite; Compounding of plastics: mould		
-	-	n moulding), Pipes, Hoses (Extrusion moulding), N		
	-	n moulding), Fibre reinforced polymers, Composite	s (Transfer mo	oulding), PET bottles
	v mouldi			
		polymers- Polyacetylene- Mechanism of conduc	tion – applic	ations (polymers in
		cleaning windows)		
	dule:8	Contemporary issues:		2 hours
Lec	ture by I	ndustry Experts		
		Total Lecture hours:	45 hours	
Tex	t Book(S)		
1.		hawla, A Text book of Engineering Chemistry, Dha	-	ishing Co., Pvt. Ltd.,
		onal and Technical Publishers, New Delhi, 3rd Edit		
2.	O.G. Pa	lanna, McGraw Hill Education (India) Private Limi	ited, 9 th Reprin	ıt, 2015.
3.	B. Siva	sankar, Engineering Chemistry 1 st Edition, Mc Gra	aw Hill Educat	ion (India), 2008
4.	"Photov	voltaic solar energy : From fundamentals to Ap	plications", A	ngà le Reinders,
	Pierre V	Verlinden, Wilfried van Sark, Alexandre Freundlich,	, Wiley publish	ners, 2017.
Ref	erence I	Books		
1.		Roussak and H.D. Gesser, Applied Chemistry-A	Text Book	for Engineers and
	Techno	logists, Springer Science Business Media, New Yo	ork. 2 nd Edition	n. 2013.
2.	S. S. D	ara, A Text book of Engineering Chemistry, S. C	Chand & Co L	td., New Delhi, 20 th
	Edition			,
Mo		aluation: Internal Assessment (CAT, Quizzes, Digit	al Assignment	s) & FAT
		eriments	ai Assignment	s) & I'AI
LISU	or Exp	erments		
	Evnor	ment title		Hours
1	-		A masthe ad and a	
1.		Purification: Estimation of water hardness by EDTA	A method and	its 3 Hours
		al by ion-exchange resin		
		Quality Monitoring: Assessment of total dissolved oxyge	en in different	3 Hours
2.	water s	amples by Winkler's method		
	Estima	tion of sulphate/chloride in drinking water by condu	uctivity metho	d 3 Hours
3.		r in States		
4/5	Motori	al Analysis: Quantitative colorimetric determina	ation of dive	lent 6 Hours
4/5				
1		ons of Ni/Fe/Cu using conventional and smart phot	ne orgitai-imag	ging
		1		
	metho			
6.	metho Analys	ds sis of Iron in carbon steel by potentiometry uction and working of an Zn-Cu electrochemical ce		3 Hours



8. Determination of viscosity-average molecular weight of different					3 Hours	
	natural/synthetic polymers					
9.	9. Arduino microcontroller based sensor for monitoring					
	pH/temperature/conductivity in samples.					
Total Laboratory Hours					30 hours	
Mode of Evaluation: Viva-voce and Lab performance & FAT						
Recommended by Board of Studies 31-05-2019						
Rec	5	54 th AC				



CSE1	001	Problem Solving and Programming	L 0	Т 0	Р	JC
					6	0 3
Pre-re	equisite	NIL	Sy	llab	is v	ersion
						v.1
Cours	e Objectiv					
		evelop broad understanding of computers, programming la	angu	ages	anc	1 their
	genera					
		uce the essential skills for a logical thinking for problem solving	0	1		
	-	ain expertise in essential skills in programming for prob	lem	SOIV	ing	using
Euno	compu					
Expec		e Outcome: stand the working principle of a computer and identify the put	rnog	a of (montor
		mming language.	rpos		1 00	mputer
		various problem solving approaches and ability to ident	tify,	010 0	nnr	oprioto
		ach to solve the problem	ury	all c	ippi	opriate
		entiate the programming Language constructs appropriately to	دماء	ie ani	7 nr	ohlem
		various engineering problems using different data structures	501		y pr	JUICIII
		o modulate the given problem using structural approach of pro	arar	nmin	a	
		ently handle data using flat files to process and store data for the	-		-	lem
	0. Linck	intry handle data using that thes to process and store data for the	ic gi	ven p	100	
Listo	f Challong	ing Experiments (Indicative)				
1		Problem Solving Drawing flowchart using yEd tool/Raptor To	പ		1	Hours
2	-	tion to Python, Demo on IDE, Keywords, Identifiers, I/O	01			Hours
2	Statemen				-	nouis
3		rogram to display Hello world in Python.			1	Hours
4	-	s and Expressions in Python				Hours
5		nic Approach 1: Sequential				Hours
6	<u> </u>	nic Approach 2: Selection (if, elif, if else, nested if else				Hours
7	-	mic Approach 3: Iteration (while and for)				Hours
8		and its Operations				Hours
9		Expressions				Hours
10		its operations.				Hours
11		ries: operations		1		Hours
12		nd its operations			6	Hours
13	Set and i	its operations			6	Hours
14		s, Recursions				Hours
15		Cechniques (Bubble/Selection/Insertion)		1		Hours
16	Ŭ	g Techniques : Sequential Search and Binary Search			6	Hours
17	Files and	its Operations			6	Hours
	Total Leo	cture hours:			45	5 hours



Text Book(s)					
1.	John V. Guttag., 2016.	Introduction to co	omputation and		
	programming using py	thon: with applica	tions to understanding data.		
	PHI Publisher.				
Reference Books					
1.	Charles Severance.2016.Python for everybody: exploring data in				
	Python 3, Charles Severance.				
2.	Charles Dierbach.2013.Introduction to computer science using				
	python: a computational problem-solving focus. Wiley Publishers.				
Mode of Evaluation:	PAT/CAT/FAT				
Recommended by	04-04-2014				
Board of Studies					
Approved by	38 th AC	Date	23-10-2015		
Academic Council					



CS	E1002	Coenced to be University under section 3 of UGC Act, 1956) Problem Solving and Object Oriented Programming	L T P J C
CB	E1002	Troblem Solving and Object Oriented Trogramming	
Dro	-requisite	NIL	Syllabus version
rre	-requisite		
Car			v.1.0
	urse Objective		
1.	-	the benefits of object oriented concepts	. 1 .
2.		students to solve the real time applications using object orien	ted programming
2	features.	a skille of a locical thinking and to ask the machlema using	
3.	-	e skills of a logical thinking and to solve the problems using	any processing
	elements		
F		0	
	pected Course		1
1.		ics of procedural programming and to represent the real world	d entities as
2	programming		4 1 - 1 1
Ζ.		ect oriented concepts and translate real-world applications in	to graphical
2	representation		mliastions
		he usage of classes and objects of the real world entities in ap he reusability and multiple interfaces with same functionality	
4.		computing problems	based realures to
5.	1	ble error-handling constructs for unanticipated states/inputs a	nd to use generic
5.		constructs to accommodate different datatypes	nu to use generie
6.		rogram against file inputs towards solving the problem	
0.	vandate the p	togram against the inputs towards solving the problem	
I ist	t of Challengir	g Experiments (Indicative)	
1.	Postman Pro		
1.		eds to walk down every street in his area in order to delive	r the mail Assume
	-	ces between the streets along the roads are given. The postm	
		turns back to the post office after delivering all the ma	
		elp the post man to walk minimum distance for the purpose.	
2.	-	ation for Marketing Campaign	
	0	ufacturing company has got several marketing options such a	as Radio
		campaign, TV non peak hours campaign, City top par	
		npaign, Web advertising. From their previous experience	
	-	t paybacks for each marketing option. Given the marketing	
	crores) for the	e current year and details of paybacks for each option, imple	ement an algorithm
		he amount that shall spent on each marketing option so that t	
	the maximum	profit.	
3.	Missionaries	and Cannibals	
	Three mission	aries and three cannibals are on one side of a river, along v	with a boat that can
	hold one or ty	vo people. Implement an algorithm to find a way to get evo	eryone to the other
	side of the riv	ver, without ever leaving a group of missionaries in one place	ce outnumbered by
	the cannibals	in that place.	
4.	0	cation Problem	
	-	component of a computer processor that can hold any type o	
		r. As registers are faster to access, it is desirable to use them	
		execution is faster. For each code submitted to the pro-	
	-	raph (RIG) is constructed. In a RIG, a node represents a temp	-
	0	ded between two nodes (variables) t1 and t2 if they are live	•
	some point in	the program. During register allocation, two temporaries can	be allocated to the



		eemed to be University under section	1501000 Ad, 1950	5				
	same register if there is no edge co	-						
	between variables in a code, implement an algorithm to determine the number of registers							
	required to store the variables and speed up the code execution.							
5.	Selective Job Scheduling Problem							
	A server is a machine that waits fo	-		-				
	purpose of a server is to share hard							
	submit the jobs to the server for ex		-					
	In such a situation, the server sch	•						
	logic. Each job contains two value	•	•	*				
	that there are two servers that sch normad as Time, Schedule, Server			•				
	named as Time_Schedule_Server a model and implement the time_Scl							
	Time_Schedule_Server arranges jo		-					
	whereas memory_Schedule_Server		-	-				
	ascending order.	r arranges jobs ba		mory required for exceduton in				
6.	Fragment Assembly in DNA Seq	uencing						
5.	DNA, or deoxyribonucleic acid, is		terial in h	umans and almost all other				
	organisms. The information in DN							
	adenine (A), guanine (G), cytosine							
	sheared into millions of small frag	•						
	sequence ("superstring"). Each rea							
	of reads, the objective is to determ							
	example, given a set of strings,	{000, 001, 010,	011, 100	0, 101, 110, 111} the shortest				
	superstring is 0001110100. Given		plement a	n algorithm to find the shortest				
	superstring that contains all the giv	ven reads.						
7.	House Wiring		.					
	An electrician is wiring a house wh							
	different locations. Given a set of		d the dista	nces between them, implement				
	an algorithm to find the minimum	cable required.		tal Laboratoria Ilanona OO Ilanona				
T	Total Laboratory Hours: 90 Hours Text Book(s)							
1 ex		Dauhana E. Maa	"C main	an? Fifth adition Addison				
1.	Stanley B Lippman, Josee Lajoie, Wesley, 2012.	Barbara E, MOO,	C++ prin	ler, Filth edition, Addison-				
2.	Ali Bahrami, Object oriented Syste	ms development	Tata McG	Fraw - Hill Education 1000				
2. 3.	Brian W. Kernighan, Dennis M. I	<u> </u>						
5.	Prentice Hall Inc., 1988.	, 110 , C	Programm	ining Danguage, 2nd Catton,				
Ref	Gerence Books							
1.	Bjarne stroustrup, The C++ progra	mming Language	. Addison	Wesley, 4th edition, 2013				
2.	Harvey M. Deitel and Paul J. Deite	<u> </u>						
3.	Maureen Sprankle and Jim Hub		-					
	edition, Pearson Eduction, 2014	,	8	6				
Mo	de of Evaluation: CAT / Assignmen	t / Quiz / FAT / P	Project / Se	minar				
		-	v					
	commended by Board of Studies	29-10-2015	D	15 10 0015				
App	proved by Academic Council	39 th AC	Date	17-12-2015				



	ampine and age (De	eemed to be University under section 3 of UGC Act, 1956)	
EEE1901	Technical Ansv	vers for Real World Problems (TARP)	
			1 0 0 4 2
Pre-requisite	PHY1901 and 115	5 Credits Earned	Syllabus version
			v. 1.0
Course Objectives			
-	ts to identify the need	d for developing newer technologies for	industrial / societal
needs			
		plement relevant technology for the deve	elopment of the
prototypes / pro			
		se the methodologies available to assess	the developed
prototypes / pro	oducts		
Expected Course			
	e course, the student		
	ife problems related		
		to address the identified problems using	g engineering
principles and	arrive at innovative	solutions	
 6 – 10 stude Minimum of Appropriate Solution shidesign/releve Consolidate Participation will be used Project outo political and Contributio 	ents can form a team of eight hours on self e scientific methodol ould be in the form of vant scientific metho ed report to be submin, involvement and of a s the modalities for come to be evaluated d demographic feasilin of each group men	itted for assessment contribution in group discussions during or the continuous assessment of the theor l in terms of technical, economical, socia bility	lesign/process the contact hours ry component ll, environmental,
Mode of Evaluation	n: (No FAT) Contini	ous Assessment the project done – Mar	k weightage of
		ed, presentation and project reviews	
Recommended by 2	Board of Studies	05/03/2016	
1 1 1 1	· a · 1	anth a D doubairead	

Recommended by Board of Studies	05/03/2016		
Approved by Academic Council	40 th AC	Date	18/03/2016



EEE4098	Comprehensive Examination	ΙΤΡΙ	C			
			$\frac{\tilde{1}}{1}$			
Pre-requisite	NIL	Syllabus versi	ion			
		V.	1.0			
	ectrical Circuits	1 17 1 1 1				
-	arrent sources: independent, dependent, ideal and practic or, mutual inductor and capacitor; transient analysis of	-				
	chhoff's laws, mesh and nodal analysis, superposition					
	er transfer and reciprocity theorems. Peak, average and rms					
apparent, active	e and reactive powers; phasor analysis, impedance and	admittance; series a	and			
-	nce, locus diagrams, realization of basic filters with R, L and	-				
-	networks, driving point impedance and admittance, o	pen-, and short circ	cuit			
parameters						
Module:2 Sig	gnals and Systems					
	odic and impulse signals; Laplace, Fourier and z-transf	orms; transfer functi	on,			
	onse of first and second order linear time invariant system					
	lution, correlation. Discrete time system: impulse respondent of the system of the sys	ise, frequency respon	ise,			
puise transfer fo	inction, DFT and FTT, basics of fix and FTR inters					
Module:3 Co	ontrol Systems					
Mathematical r	nodelling and representation of systems, Feedback prin	ciple, transfer function	on,			
	s and Signal flow graphs, Transient and Steady-state					
	ns, Routh-Hurwitz and Nyquist criteria, Bode plots, Root					
transition matri	Lead-Lag compensators; P, PI and PID controllers; S	tate space model, St	ate			
	Δ					
Module:4 Ar	nalog and Digital Circuits					
	and applications of diode, Zener diode, BJT and MOSFET					
	its, feedback amplifiers. Characteristics of operational an					
	rence amplifier, adder, sub tractor, integrator, differe					
	sion rectifier, active filters and other circuits. Oscillators, s llators and phase locked loop. Combinational logic ci		-			
	ons. IC families: TTL and CMOS. Arithmetic circuits					
	ibrators, sequential circuits, flip-flops, shift registers, time	· •				
	t, multiplexer, analog-to-digital (successive approximatio					
Ū į	sigma-delta) and digital-to-analog converters (weighted R, R-2R ladder and current steering					
•	logic). Characteristics of ADC and DAC (resolution, quantization, significant bits,					
conversion/settling time); basics of number systems, microcontroller: applications, memory and input-output interfacing; basics of data acquisition systems.						
	ectrical and Electronic Instrumentation					
	matic and random errors in measurement, expression of un	ncertainty - accuracy a	and			
	ex, propagation of errors. PMMC, MI and dynamometer					
	bridges for measurement of R, L and C, Q-meter. Measure single and three phase circuits; ac and dc current probes;					
	scaling, instrument transformers, timer/counter, time,					
	, digital voltmeter, digital multimeter; oscilloscope, shieldin		- 5			



Resistive-, capacitive-, inductive-, piezoelectric-, Hall effect sensors and associated signal conditioning circuits; transducers for industrial instrumentation: displacement (linear and angular), velocity, acceleration, force, torque, vibration, shock, pressure (including low pressure), flow (differential pressure, variable area, electromagnetic, ultrasonic, turbine and open channel flow meters) temperature (thermocouple, bolometer, RTD (3/4 wire), thermistor, pyrometer and semiconductor); liquid level, pH, conductivity and viscosity measurement

Module:7 Optoelectronic Instrumentation

Optical sources and detectors: LED, laser, photo-diode, light dependent resistor and their characteristics; interferometer: applications in metrology; basics of fiber optic sensing.

Module:8 Communication Engineering

Amplitude- and frequency modulation and demodulation; Shannon's sampling theorem, pulse code modulation; frequency and time division multiplexing, amplitude-, phase-, frequency-, pulse shift keying for digital modulation.

Mode of Evaluation: Witten Exam

Recommended by Board of Studies	05.06.2015		
Approved by Academic Council	37 th AC	Date	16.06.2015



	(Deemed to be University under section 3 of UGC Act, 1956)	Ŧ		D	T	~
ENG1901	Technical English - I		T	P 4	J	<u>C</u>
Duo	Foundation English U	0	0	4	0	2
Pre-requisite	Foundation English-II	S	yllał	JUS		101 1.1
Course Objectiv					۷.	1.1
-	es. estudents' knowledge of grammar and vocabulary to read and	dwr	ita ar	ror f	raa	
	n real life situations.	u WI		101-1	100	
	he students' practice the most common areas of written and sp	oke	n			
	cations skills.	JUKCI	1			
	ve students' communicative competency through listening and	sne	akino	racti	vitie	•6
in the clas		spea	ıkiiig	, acti	vitic	3
Expected Course						
	op a better understanding of advanced grammar rules and writ	e gra	mm	atica	llv	
	t sentences.	~ 510		ca		
	re wide vocabulary and learn strategies for error-free commun	icati	on.			
1	rehend language and improve speaking skills in academic and			ntex	ts.	
4. Impro	ve listening skills so as to understand complex business comm	unic	ation	in a	l	
variety	of global English accents through proper pronunciation.					
	ret texts, diagrams and improve both reading and writing skills	s whi	ich w	ould	l hel	р
them i	n their academic as well as professional career.					
	1.0					
	vanced Grammar			4	hou	irs
	Voice and Prepositions					
Activity: Worksh	eets on Impersonal Passive Voice, Exercises from the prescrib	ed te	ext			
					4.1	
	cabulary Building I			4	4 ho	ars
	es, Homonyms, Homophones and Homographs					
Activity: Jigsaw l	Puzzles; Vocabulary Activities through Web tools					
					4.5	
	tening for Specific Purposes			4	4 ho	urs
	, short conversations, announcements, briefings and discussion	ns				
Activity: Gap IIII	ng; Interpretations					
Module:4 Sp	eaking for Expression			6	ho	iire
	elf and others, Making Requests & responses, Inviting and Acc	centi	no/D			u15
Invitations	and succes, making requests & responses, inviting and rec	pu		2011	5	
	roductions; Role-Play; Skit.					
i tea (ity: Brief III						
Module:5 Re	ading for Information			4	4 ho	urs
	ssages, News Articles, Technical Papers and Short Stories				- 110	U
U	specific news paper articles; blogs					
Module:6 Wi	iting Strategies			Δ	ho	nrs
	ices, word order, sequencing the ideas, introduction and conclu	usior	1		100	
U U	aragraphs; Describing familiar events; story writing		-			
	cabulary Building II			4	ho	urs
· I	• •					

	VIT VIT VIT VIT VIT VIT VIT VIT Vellore Institute of Technology (Deemed to be University under section 3 of UGC Act, 1956)	
Employment	omain specific vocabulary by describing Objects, Charts, Food, Sports and t. scribing Objects, Charts, Food, Sports and Employment	
•		
Module:8	Listening for Daily Life	4 hours
Listening for	statistical information, Short extracts, Radio broadcasts and TV interviews	
Activity: Ta	king notes and Summarizing	
Module:9	Expressing Ideas and Opinions	6 hours
	Expressing Ideas and Opinions	
-	conversations, Interpretation of Visuals and describing products and processes le-Play (Telephonic); Describing Products and Processes	
Module: 10	Comprehensive Reading	4 hours
	nprehension, Making inferences, Reading Graphics, Note-making, and Critica	
Reading.	aprenetation, making interences, reading Graphies, rote making, and entited	~ .
-	ntence Completion; Cloze Tests	
Activity. Sci	ience completion, cloze resis	
Module: 11	Narration	4 hours
	ative short story, Personal milestones, official letters and E-mails.	4 110015
•	riting an E-mail; Improving vocabulary and writing skills.	
Activity. w	fitting an E-mail, improving vocabulary and writing skins.	
Module:12	Pronunciation	4 hours
	ads, Word Stress, Intonation, Various accents	4 110015
1	ecticing Pronunciation through web tools; Listening to various accents of Englished	lish
Module:13	Editing	4 hours
	pplex & Compound Sentences, Direct & Indirect Speech, Correction of Errors	
Punctuations		,
	.cticing Grammar	
Terry. The		
Module 14	Short Story Analysis	4 hours
	ary" by Jhumpa Lahiri	4 nours
	ading and analyzing the theme of the short story.	
Tetrvity. Re	adding and analyzing the theme of the short story.	
	Total Lecture hours	60 hours
Text Book /		
1. Wre	en, P.C.; Martin, H.; Prasada Rao, N.D.V. (1973–2010). High School English composition. New Delhi: Sultan Chand Publishers.	Grammar
2 Kur	nar, Sanjay,; Pushp Latha. (2018) English Language and Communication Skil ineers, India: Oxford University Press.	ls for
Reference B	Books	
1. Gup	tha S C, (2012) Practical English Grammar & Composition, 1st Edition, India: Ari	hant
-	ishers	
	ven Brown, (2011) Dorolyn Smith, Active Listening 3, 3rd Edition, UK: Cam	oridge
	versity Press.	J
	-	



Lamber Math	Deemed to be University unde	r section 3 of UGC Act, 1956)				
3. Liz Hamp-Lyons, Ben Heasle University Pres.						
	Kenneth Anderson, Joan Maclean, (2013) Tony Lynch, Study Speaking, 2nd Edition, UK: Cambridge, University Press.					
5. Eric H. Glendinning, Beverly Cambridge University Press.	Holmstrom, (2	2012) Study Reading, 2nd Edi	tion, UK:			
6. Michael Swan, (2017) Practic Oxford University Press.	al English Usa	ge (Practical English Usage),	4th edition, UK:			
7. Michael McCarthy, Felicity (Asian Edition), UK: Cambrid			vanced (South			
8. Michael Swan, Catherine Wa 4th Edition, UK: Oxford Univ		ford English Grammar Course	e Advanced, Feb,			
	Watkins, Peter. (2018) Teaching and Developing Reading Skills: Cambridge Handbooks for Language teachers, UK: Cambridge University Press.					
10. (The Boundary by Jhumpa La https://www.newyorker.com/n	,	01/29/the-boundary?intcid=inlir	ne_amp			
Mode of evaluation: Quizzes, Presen	tation, Discuss	ion, Role play, Assignments a	nd FAT			
List of Challenging Experiments (In	dicative)					
1. Self-Introduction			12 hours			
2. Sequencing Ideas and Writing a	Paragraph		12 hours			
3. Reading and Analyzing Technic	al Articles		8 hours			
4. Listening for Specificity in Inter	views (Content	t Specific)	12 hours			
	dentifying Errors in a Sentence or Paragraph					
6. Writing an E-mail by narrating l	Vriting an E-mail by narrating life events					
	60 hours					
Mode of evaluation: Quizzes, Presentation, Discussion, Role play, Assignments and FAT						
Recommended by Board of Studies	08.06.2019					
Approved by Academic Council	55 th AC	Date: 13-06-2019				



	(Deemed to be University under section 3 of UGC Act, 1956)	-				~
ENG 1902	Technical English - II	Ĺ	T		-	C
		0	0			2
Pre-requisite	71% to 90% EPT score	S	ylla	bus	Vers	
					v.	1.1
Course Objective		0				
	proficiency levels in LSRW skills on par with the requirement	s fo	or pl	acer	nent	
	of high-end companies / competitive exams.		~~ ~	£ 4.5	- 1	1
2. To evaluat and genera	e complex arguments and to articulate their own positions on a	ran	ge () te	cnnic	al
•	n grammatical and acceptable English with minimal MTI, as w	، الم	ne d	امىرما	00.0	
	tive vocabulary.		15 U	ever	opa	
Expected Course	•					
	cate proficiently in high-end interviews and exam situations and	l all	SOC	rial		
situations	are pronotenery in high one interviews and exam situations and	a an	500	/1 u 1		
	nd academic articles and draw inferences					
-	ifferent perspectives on a topic					
	rly and convincingly in academic as well as general contexts					
	complex concepts and present them in speech and writing					
-						
Module:1 List	tening for Clear Pronunciation				4 ho	urs
	oduction to vowels, consonants, diphthongs.				4 110	uis
	al conversations in British and American accents (BBC and CN	N)	as u	vell :	as oth	ıer
'native' accents	in conversations in Diffusion and American accents (DDC and Civ	1)	us v		us ou	
	and interpretive exercises; note-making in a variety of global E	nali	ch a	CCAI	nte	
	roducing Oneself	ngn	511 a		4 ho	1180
Speaking: Individ					4 110	urs
	oductions, Extempore speech					
-	ective Writing				6 ho	ure
	letters and Emails, Minutes and Memos				0 110	ui s
	e of common business letters and emails: inquiry/ complaint/ pl	laci	no a	n or	·der·	
Formats of Minute		luci	15 0		uer,	
	write a business letter and Minutes/ Memo					
	nprehensive Reading				4 ho	urs
	Comprehension Passages, Sentence Completion (Technical an	d G	ene	ral I	ntere	st),
Vocabulary and W	Vord Analogy					
Activities: Cloze t	ests, Logical reasoning, Advanced grammar exercises					
	tening to Narratives				4 ho	urs
	ng to audio files of short stories, News, TV Clips/ Documentar	ies,	Mo	otiva	tiona	1
	JS/ global English accents.	,				
Activity: Note-ma	king and Interpretive exercises					
	demic Writing and Editing				6 ho	urs
	Proofreading symbols				-	
Citation Formats						
Structure of an Ab	stract and Research Paper					
Activity: Writing	Abstracts and research paper; Work with Editing/ Proofreading	g ex	erci	se		
Module:7 Tea	m Communication				4 ho	urs
		_	-	-		



	(Deemed to be University under section 3 of UGC Act, 1956)	
-	king: Group Discussions and Debates on complex/ contemporary topics	
	ssion evaluation parameters, using logic in debates	
	ity: Group Discussions on general topics	
Modu	8	4 hours
	ing: Resumes and Job Application Letters, SOP	
	ity: Writing resumes and SOPs	
Modu		4 hours
	ing: Reading short stories	
	ity: Classroom discussion and note-making, critical appreciation of the short story	
	ule: 10 Creative Writing	4 hours
	ing: Imaginative, narrative and descriptive prose	
	ity: Writing about personal experiences, unforgettable incidents, travelogues	
	ule: 11 Academic Listening	4 hours
	ning: Listening in academic contexts	
	ity: Listening to lectures, Academic Discussions, Debates, Review Presentations, R	esearch
	, Project Review Meetings	
	ule:12 Reading Nature-based Narratives	4 hours
Narra	atives on Climate Change, Nature and Environment	
Activ	ity: Classroom discussions, student presentations	
Mod	ule:13 Technical Proposals	4 hours
Writ	ing: Technical Proposals	
Activ	ities: Writing a technical proposal	
Mod	ule:14 Presentation Skills	4 hours
Persu	asive and Content-Specific Presentations	
	ity: Technical Presentations	
	Total Lecture hours:	60 hours
Text	Book / Workbook	
1.	Oxenden, Clive and Christina Latham-Koenig. New English File: Advanced Stude	ents Book.
	Paperback. Oxford University Press, UK, 2017.	
2	Rizvi, Ashraf. Effective Technical Communication. McGraw-Hill India, 2017.	
Refer	rence Books	
1.	Oxenden, Clive and Christina Latham-Koenig, New English File: Advanced: Teac with Test and Assessment. CD-ROM: Six-level General English Course for Adult Paperback. Oxford University Press, UK, 2013.	
2.	Balasubramanian, T. English Phonetics for the Indian Students: A Workbook. Lax Publications, 2016.	xmi
3.	Philip Seargeant and Bill Greenwell, From Language to Creative Writing. Blooms Academic, 2013.	sbury
4.	Krishnaswamy, N. Eco-English. Bloomsbury India, 2015.	
5.	Manto, Saadat Hasan. Selected Short Stories. Trans. Aatish Taseer. Random Hous 2012.	se India,
6.	Ghosh, Amitav. The Hungry Tide. Harper Collins, 2016.	
7.	Ghosh, Amitav. The Great Derangement: Climate Change and the Unthinkable. P Books, 2016.	enguin
8.	The MLA Handbook for Writers of Research Papers, 8th ed. 2016.	
	Online Sources:	



 https://americanliterature.com/short-short-stories. (75 short short stories)

 http://www.eco-ction.org/dt/thinking.html (Leopold, Aldo."Thinking like a Mountain")

 /www.esl-lab.com/;

 www.bbc.co.uk/learningenglish/;

 /www.bbc.com/news;

 /learningenglish.voanews.com/a/using-voa-learning-english-to-improve-listening

 skills/3815547.html

Mode of evaluation: Quizzes, Presentation, Discussion, Role play, Assignments and FAT

	List of Challenging I	Experiments (Indi	icative)			
1.	1. Self-Introduction using SWOT					
2.	Writing minutes of meetings			10 hours		
3.	3. Writing an abstract					
4. Listening to motivational speeches and interpretation				10 hours		
5. Cloze Test				6 hours		
6. Writing a proposal				12 hours		
	I	Т	otal Laboratory Hours	60 hours		
Mod	le of evaluation: Quizzes, Presentat	tion, Discussion, R	ole play, Assignments and H	FAT		
Reco	ommended by Board of Studies	08.06.2019				
App	roved by Academic Council	55 th AC	Date: 13-06-2019			



ENG1903		Advanced Technical English	L	Т	Р	J	С
		~	0	0	2	4	2
Pre-requisite		Greater than 90 % EPT score	S	Sylla	bus '	Vers	ion
						v.	1.1
Course Obje	ectives	:					
		terature in any form or any technical article					
		itent in social media and respond accordingly					
		icate with people across the globe overcoming trans-cultura	l bar	riers	and		
negot	tiate su	ccessfully					
Expected Co	ourse (Outcome:					
1. Analy	yze crit	tically and write good reviews					
2. Artic	ulate re	esearch papers, project proposals and reports					
3. Com	munica	te effectively in a trans-cultural environment					
-		nd lead teams towards success					
5. Prese	nt idea	s in an effective manner using web tools					
Module:1	Nego	tiation and Decision Making Skills through Literary An	alysi	is		5 ho	urs
Concepts of I	_	ation and Decision Making Skills					
Activity: Ana	alysis o	of excerpts from Shakespeare's "The Merchant of Venice" (cour	t scei	ne) a	nd	
discussion or					-		
Critical evalu	uation	of excerpts from Shakespeare's "Hamlet"(Monologue by Ha	ımle	t) and	d dis	cussi	ion
on decision r				,			
Module:2		ing reviews and abstracts through movie interpretations			5	hou	rs
		abstract writing with competency					
	-	Charles Dickens "Great Expectations" and writing a movie	revi	ew			
		F. Nolan's "Logan's Run" and analyzing it in tune with the			cenar	io oi	f
		ces and writing an abstract				10 01	-
Module:3		nical Writing				4 ho	urs
Stimulate eff		linguistics for writing: content and style					
Activity: Pro		· ·					
Statement of	Purpo	se					
Module:4	Tran	s-Cultural Communication			4	ho	urs
Nuances of 7	Frans-c	ultural communication					
Activity:Gro	up disc	cussion and case studies on trans-cultural communication.					
Debate on tra	ans-cul	tural communication.					
Module:5	Repo	ort Writing and Content Writing				4 ho	urs
Enhancing re	eportag	e on relevant audio-visuals	_				_
Activity: Wa	tch a d	ocumentary on social issues and draft a report					
Identify a vic	leo on	any social issue and interpret					
Module:6		ting project proposals and article writing			4	ho	urs
•		ng project proposals and research articles					
-	_	project proposal., Writing a research article.					
Module:7		nical Presentations			4	ho	urs
-		ation skills and strategies					
Activity: Tec	chnical	presentations using PPT and Web tools					
		Total Lectu	ıre h	ours	s 3	0 ho	urs
Text Book /	Work	hook					

Text Book / Workbook



1.	_		l Communication: Principles and I	Practice,		
Dof	3rd edition, Oxford University Pr Ference Books	ess, 2015.				
1	Basu B.N. Technical Writing, 201	1 Kindle edition				
2	=		Venice (Text with Paraphrase), Ev	ergreen		
3	Kumar, Sanjay and Pushp Lata. English Language and Communication Skills for Engineers, Oxford University Press, India, 2018.					
4	Publishing, UK.		on, 2015, LAP Lambert Academic			
5	Reprint 2012 The Foundation Cer	nter, USA.	to Proposal Writing, 5th Edition, 20			
6	2014 Kindle Edition.		ose: A Concise Guide to Writing Y	our SOP,		
7	Ray, Ratri, William Shakespeare'	s Hamlet, The A	tlantic Publishers, 2011.			
8	C Muralikrishna & Sunitha Mishr Pearson, 2011.	a, Communicati	on Skills for Engineers, 2nd edition	n, NY:		
Mo	de of Evaluation: Quizzes, Present	ation, Discussio	n, Role Play, Assignments			
Lis	t of Challenging Experiments (Inc	licative)				
1.	Enacting a court scene - Speakin	g		6 hours		
2.	Watching a movie and writing a r	eview		4 hours		
3.	Trans-cultural – case studies			2 hours		
4.	Drafting a report on any social iss	sue		6 hours		
5.	Technical Presentation using web	tools		6 hours		
6.	Writing a research paper			6 hours		
J- (Component Sample Projects			L		
	1. Short Films					
	2. Field Visits and Reporting					
	3. Case studies					
	4. Writing blogs					
	5. Vlogging					
			Total Hours (J-Component)	60 hours		
Mo	de of evaluation: Quizzes, Presenta	tion, Discussion,	Role play, Assignments and FAT	I		
	commended by Board of Studies	08.06.2019				
Ap	proved by Academic Council	55 th AC	Date: 13-06-2019			



ENG1000	(Deemed to be University under section 3 of UGC Act, 1956) Foundation English - I	L	Т	P J	С
LINGIOU	i oundation English - 1	0	0	4 0	0
Pre-requisite	Less than 50% EPT score			s Vers	
		~ 5			1.1
Course Object	ives:				
· · · · ·	o learners with English grammar and its application.				
2. To enab	le learners to comprehend simple text and train them to speak a	and w	rite		
flawless	ly.				
3. To fami	liarize learners with MTI and ways to overcome them.				
Expected Cou	rse Outcome:				
1. Develop	the skills to communicate clearly through effective grammar,	pron	uncia	ation a	nd
writing.		1			
e	and everyday conversations in English				
	nicate and respond to simple questions about oneself.				
	e vocabulary and expressions.				
-	MTI (Mother Tongue Influence) during usual conversation.				
Module:1 I	Essentials of grammar			3 Ho	urs
	ic grammar-Parts of Speech				
Activity: Gram	mar worksheets on parts of speech				
Module:2	ocabulary Building			3 H o	urs
Vocabulary dev	elopment; One word substitution				
-	entary vocabulary exercises				
	Applied grammar and usage			4 Ho	urs
Types of senter					
Activity: Gram	mar worksheets on types of sentences; tenses				
Module:4	Rectifying common errors in everyday conversation			4 Ho	urs
Detect and rect	fy common mistakes in everyday conversation				
•	non errors in prepositions, tenses, punctuation, spelling and oth	er pa	rts o	f speed	ch;
Colloquialism					
Module :5	Jumbled sentences			2 Ho	urs
Sentence struct	are; Jumbled words to form sentences; Jumbled sentences to fo	rm p	aragi	:aph/	
short story					
	amble a paragraph / short story				
Module:6	Text-based Analysis			4 Ho	urs
0 5	Autobiography of APJ Abdul Kalam (Excerpts)				
	n vocabulary by reading and analyzing the text				
Module:7	Correspondence			3 Ho	urs
	Application Writing				
	ose letters; Emails, Leave applications			<u> </u>	
Module:8	Listening for Understanding			4 Ho	urs
-	uple conversations & gap fill exercises e conversations in Received Pronunciation using audio-visual i	nater	iale		
Activity. Shilpi	e conversations in Acceived i fonunciation using audio-visual i	mait	1415.		



Self-introduction; role-plays; Everyday conversations Activity: Identify and communicate characteristic attitudes, values, and talents; Working and interacting within groups Module:10 Reading for developing pronunciation 6 Hours Loud reading with focus on pronunciation by watching relevant video materials 6 Hours Activity: Practice pronunciation by reading aloud simple texts; Detecting syllables; Visually connecting to the words shown in relevant videos 4 Hours Reading short stories and passages 4 Hours Reading short stories and passages 6 Hours Activity: Reading and analyzing the author's point of view; Identifying the central idea. 6 Hours Module:12 Writing to Communicate 6 Hours Paragraph Writing; Essay Writing; Short Story Writing 6 Hours Describing graphical illustrations; interpreting basic charts, tables, and formats 6 Hours Module:14 Overcoming Mother Tongue Influence (MTI) in Pronunciation 5 Hours Practicing common variants in pronunciation 60 Hours 60 Hours Activity: Identifying and overcoming mother tongue influence. 60 Hours 60 Hours Text Book / Workbook 10 Wren, P.C., & Martin, H. (2018).High School English Grammar & Composition N.D.V. PrasadaRao (Ed.). NewDelhi: S. Chand & Company Ltd. 60 Hours	Modu	10.0	Speaking to Convey	6 Hours
Activity: Identify and communicate characteristic attitudes, values, and talents; Working and interacting within groups 6 Hours Module:10 Reading for developing pronunciation 6 Hours Loud reading with focus on pronunciation by watching relevant video materials Activity: Practice pronunciation by reading aloud simple texts; Detecting syllables; Visually connecting to the words shown in relevant videos 4 Hours Reading short stories and passages 4 Hours 8 Activity: Reading and analyzing the author's point of view; Identifying the central idea. 6 Hours Module:12 Writing; Communicate 6 Hours Paragraph Writing; Essay Writing; Short Story Writing 6 Hours Describing graphical illustrations; interpreting basic charts, tables, and formats 6 Hours Describing graphical illustrations; interpreting basic charts, tables, and formats 5 Hours Module:14 Overcoming Mother Tongue Influence (MTI) in Pronunciation 5 Hours Practicing common variants in pronunciation Activity: Identifying and overcoming mother tongue influence. 60 Hours 1. Wren, P.C., & Martin, H. (2018). High School English Grammar & Composition N.D.V. PrasadaRao (Ed.). NewDelhi: S. Chand & Company Ltd. 60 Hours 2. McCarthy, M. O'Dell, F.,& Bunting, J.D. (2010). Vocabulary in Use(High Intermediate students book with answers). Cambridge Unive				0 110015
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Describing graphical illustrations; interpreting basic charts, tables, and formats Activity: Interpreting and presenting simple graphical representations/charts in the form of PPTs Module:14 Overcoming Mother Tongue Influence (MTI) in Pronunciation Practicing common variants in pronunciation Activity: Identifying and overcoming mother tongue influence. 60 Hours Text Book / Workbook 60 Hours 1. Wren, P.C., & Martin, H. (2018).High School English Grammar & Composition N.D.V. PrasadaRao (Ed.). NewDelhi: S. Chand & Company Ltd. 2. McCarthy, M. O'Dell, F.,& Bunting, J.D. (2010).Vocabulary in Use(High Intermediate students book with answers). Cambridge University Press Reference Books 1. Watkins, P.(2018).Teaching and Developing Reading Skills: Cambridge Handbooks for Language teachers. Cambridge University Press. 2. Mishra, S., &Muralikrishna, C. (2014).Communication Skills for Engineers. Pearson Education India 3 Lewis, N. (2011).Word Power Made Easy. Goyal Publisher 4 https:/americanliterature.com/short-short-stories 5 Tiwari, A., &Kalam, A. (1999).Wings of Fire - An Autobiography of Abdul Kalam. Universities Press (India) Private Limited.	Activi	ty: Writing	paragraphs, essays and short- stories	
Activity: Interpreting and presenting simple graphical representations/charts in the form of PPTs Module:14 Overcoming Mother Tongue Influence (MTI) in Pronunciation 5 Hours Practicing common variants in pronunciation Activity: Identifying and overcoming mother tongue influence. 60 Hours Text Book / Workbook 60 Hours 1. Wren, P.C., & Martin, H. (2018).High School English Grammar & Composition N.D.V. PrasadaRao (Ed.). NewDelhi: S. Chand & Company Ltd. 2. McCarthy, M. O'Dell, F.,& Bunting, J.D. (2010).Vocabulary in Use(High Intermediate students book with answers). Cambridge University Press Reference Books 1. Watkins, P.(2018).Teaching and Developing Reading Skills: Cambridge Handbooks for Language teachers. Cambridge University Press. 2. Mishra, S., &Muralikrishna, C. (2014).Communication Skills for Engineers. Pearson Education India 3 Lewis, N. (2011).Word Power Made Easy. Goyal Publisher 4 https:/americanliterature.com/short-short-stories 5 Tiwari, A., &Kalam, A. (1999).Wings of Fire - An Autobiography of Abdul Kalam. Universities Press (India) Private Limited.	Modu	le:13	Interpreting Graphical Data	6 Hours
Module:14 Overcoming Mother Tongue Influence (MTI) in Pronunciation 5 Hours Practicing common variants in pronunciation Activity: Identifying and overcoming mother tongue influence. 60 Hours Text Book / Workbook 60 Hours 1. Wren, P.C., & Martin, H. (2018).High School English Grammar & Composition N.D.V. PrasadaRao (Ed.). NewDelhi: S. Chand & Company Ltd. 2. McCarthy, M. O'Dell, F.,& Bunting, J.D. (2010).Vocabulary in Use(High Intermediate students book with answers). Cambridge University Press Reference Books 1. 1. Watkins, P.(2018).Teaching and Developing Reading Skills: Cambridge Handbooks for Language teachers. Cambridge University Press. 2. Mishra, S., &Muralikrishna, C. (2014).Communication Skills for Engineers. Pearson Education India 3 Lewis, N. (2011).Word Power Made Easy. Goyal Publisher 4 https:/americanliterature.com/short-short-stories 5 Tiwari, A., &Kalam, A. (1999).Wings of Fire - An Autobiography of Abdul Kalam. Universities Press (India) Private Limited.	Descri	ibing graph	ical illustrations; interpreting basic charts, tables, and formats	
Module:14 Overcoming Mother Tongue Influence (MTI) in Pronunciation Practicing common variants in pronunciation Activity: Identifying and overcoming mother tongue influence. Total Laboratory Hours 60 Hours Total Laboratory Hours Composition N.D.V. PrasadaRao (Ed.). NewDelhi: S. Chand & Company Ltd. 2. McCarthy, M. O'Dell, F.,& Bunting, J.D. (2010).Vocabulary in Use(High Intermediate students book with answers). Cambridge University Press Reference Books 1. Watkins, P.(2018).Teaching and Developing Reading Skills: Cambridge Handbooks for Language teachers. Cambridge University Press. 2. Mishra, S., &Muralikrishna, C. (2014).Communication Skills for Engineers. Pearson Education India 3 Lewis, N. (2011).Word Power Made Easy. Goyal Publisher 4 https:/americanliterature.com/short-short-stories 5 Tiwari, A., &Kalam, A. (1999).Wings of Fire - An Autobiography of Abdul Kalam. Universities Press (India) Private Limited.	Activi	ty: Interpre	eting and presenting simple graphical representations/charts in the for	m of PPTs
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⁵ Universities Press (India) Private Limited.		1		alam
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	Mode			



List of	Challenging Experiments (Ind	licative)				
1.	Rearranging scrambled sentend	ces			8 hours	
2.	2. Identifying errors in oral and written communication					
3.	3. Critically analyzing the text					
4.	Developing passages from hint	t words			8 hours	
5.	Role-plays				12 hours	
6.	Listening to a short story and a	nalyzing it			12 hours	
	-	Tota	al Laborato	ry Hours	60 hours	
Mode of	of Evaluation: Quizzes, Presentat	tion, Discussion, R	ole Play, As	signments		
Recom	mended by Board of Studies	08-06-2019				
Approv	ed by Academic Council	55 th AC	Date	13-06-2019		



ENG2000	Foundation English - II	L T P J C
	Foundation English - H	
Pre-requisite	51% - 70% EPT Score / Foundation English I	Syllabus version
		v.1.1
Course Objecti	ves:	
	ce grammar and vocabulary effectively	
2. To acqui	re proficiency levels in LSRW skills in diverse social situations.	
3. To analy	ze information and converse effectively in technical communicatio	n.
Expected Cours	se Outcome:	
1. Accompl	ish a deliberate reading and writing process with proper grammar a	and vocabulary.
2. Compreh	end sentence structures while Listening and Reading.	
3. Commun	icate effectively and share ideas in formal and informal situations.	
4. Understa	nd specialized articles and technical instructions and write clear tec	chnical
correspon	ndence.	
5. Critically	think and analyze with verbal ability.	
Module:1	Grammatical Aspects	4 hours
Sentence Pattern	, Modal Verbs, Concord (SVA), Conditionals, Connectives	
Activity : Works		
Module:2	Vocabulary Enrichment	4 hours
Active & Passiv	e Vocabulary, Prefix and Suffix, High Frequency Words	
Activity : Works		
•		
Module:3	Phonics in English	4 Hours
	•	
Speech Sounds -	- Vowels and Consonants - Minimal Pairs- Consonant Clusters- P	
Module:3 Speech Sounds - and Plural Mark Activity : Works	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er	
Speech Sounds - and Plural Mark	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er	
Speech Sounds - and Plural Mark Activity : Works Module:4	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors	ast Tense Marker
Speech Sounds - and Plural Mark Activity : Works Module:4	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary	ast Tense Marker
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary	Past Tense Marker
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors	Past Tense Marker 2 Hours 2 Hours 2 Hours
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brev	Past Tense Marker 2 Hours 2 Hours 2 Hours
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brev sheets, Exercises	Past Tense Marker 2 Hours 2 Hours 2 Hours
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brev	Past Tense Marker 2 Hours 2 Hours ity 6 Hours
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Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ver	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brev sheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Co	Past Tense Marker 2 Hours 2 Hours ity 6 Hours ourt scene in The
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ver scene in Julius C	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brev sheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Con nice, Disguise Scene in The Twelfth Night, Death of Desdemona	Past Tense Marker 2 Hours 2 Hours ity 6 Hours ourt scene in The
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ver scene in Julius C Activity : Summ	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brev sheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Conice, Disguise Scene in The Twelfth Night, Death of Desdemona caesar and Balcony scene from Romeo and Juliet)	Past Tense Marker 2 Hours 2 Hours ity 6 Hours ourt scene in The in Othello, Death
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ven scene in Julius C Activity : Summ Module:7	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brev sheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Con nice, Disguise Scene in The Twelfth Night, Death of Desdemona caesar and Balcony scene from Romeo and Juliet) arizing; Note-making and drawing inferences from Short videos	Past Tense Marker 2 Hours 2 Hours ity 6 Hours ourt scene in The in Othello, Death 6 Hours
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ver scene in Julius C Activity : Summ Module:7 Impromptu, Imp	 Vowels and Consonants – Minimal Pairs- Consonant Clusters- Per Syntactic and Semantic Errors Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brev sheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Conice, Disguise Scene in The Twelfth Night, Death of Desdemona Caesar and Balcony scene from Romeo and Juliet) arizing; Note-making and drawing inferences from Short videos Art of Public Speaking 	Past Tense Marker 2 Hours 2 Hours ity 6 Hours ourt scene in The in Othello, Death 6 Hours
Speech Sounds - and Plural Mark Activity : Works Module:4 Tenses /SVA/Ar Activity : Works Module:5 Dangling Modif Activity : Work Module:6 Intensive and E Merchant of Ver scene in Julius C Activity : Summ Module:7 Impromptu, Imp Presentations – I	- Vowels and Consonants – Minimal Pairs- Consonant Clusters- P er sheets, Exercises Syntactic and Semantic Errors ticles/ Prepositions/ Punctuation & Right Choice of Vocabulary sheets, Exercises Stylistic errors Fiers, Parallelism, Standard English, Ambiguity, Redundancy, Brev sheets, Exercises Listening and Note making xtensive Listening - Scenes from plays of Shakespeare (Eg: Co nice, Disguise Scene in The Twelfth Night, Death of Desdemona Caesar and Balcony scene from Romeo and Juliet) arizing; Note-making and drawing inferences from Short videos Art of Public Speaking ortance of Non-verbal Communication, Technical Talks, Dynamic	Past Tense Marker 2 Hours 2 Hours 2 Hours ity 6 Hours ourt scene in The in Othello, Death 6 Hours s of Professional



		(Deemed to be University under section 3 of UGC Act, 1956)	
Skir	nming, scan	ning, comprehensive reading, guessing words from context, underst	anding text
orga	anization, rec	cognizing argument and counter-argument; distinguishing between main	information
and	supporting of	detail, fact and opinion, hypothesis versus evidence; summarizing and	note-taking,
Crit	ical Reasoni	ng Questions – Reading and Discussion	
Acti	ivity: Readin	g of Newspapers Articles and Worksheets on Critical Reasoning from w	eb
reso	ources		
Mo	dule: 9	Creative Writing	4 Hours
Stru	cture of an e	ssay, Developing ideas on analytical/ abstract topics	
Acti	ivity: Movie	Review, Essay Writing on suggested Topics, Picture Descriptions	
Mo	dule: 10	Verbal Aptitude	6 hours
Wo	rd Analogy,	Sentence Completion using Appropriate words, Sentence Correction	
		ing the use of appropriate words and sentences through web tools.	
	dule: 11	Business Correspondence	4 hours
For	nal Letters-	Format and purpose: Business Letters - Sales and complaint letter	
		writing- request for Internship, Industrial Visit and Recommendation	
	dule: 12	Career Development	6 hours
Tele	phone Etiqu	ette, Resume Preparation, Video Profile	
		ration of Video Profile	
	dule: 13	Art of Technical Writing - I	4 hours
		ctions, Process and Functional Description	• • • •
		g Technical Instructions	
	dule: 14	Art of Technical Writing – II	4 hours
For	nat of a Rep	ort and Proposal	
		nical Report Writing, Technical Proposal	
1100			
		Total Lecture hours:	60 hours
Tex	t Book / Wa		
1.	Sanjay Ku	mar & Pushp Lata, Communication Skills, 2nd Edition, OUP, 2015	
2	Wren & M	artin, High School English Grammar & Composition, Regular ed., ND:]	Blackie
	ELT Book	s, 2018	
Ref	erence Book	ί S	
1	Peter Watk	ins, Teaching and Developing Reading Skills: Cambridge Handbooks fo	r Language
	Teachers,	Cambridge, 2018	
2	Aruna Kon	eru, Professional Speaking Skills, OUP, 2015.	
3	J.C.Nesfiel	d, English Grammar English Grammar Composition and Usage, Macmil	lan. 2019.
4	Richard Jo	hnson-Sheehan, Technical Communication Today, 6th edition, ND: Pear	rson, 2017.
5		naniam, Textbook of English Phonetics For Indian Students, 3rd Edition	, S. Chand
	Publishers,	2013.	



Web Resources

1. https://www.hitbullseye.com/Sentence-Correction-Practice.php

2. https://hitbullseye.com/Critical-Reasoning-Practice-Questions.php

Mode of Evaluation: Presentation, Discussion, Role Play, Assignments , FAT

List of C	Challenging Experiments (Ind	licative)				
1.	Reading and Analyzing Critic	cal Reasoning ques	stions		8 hours	
2.	2. Listening and Interpretation of Videos					
3.	Letter to the Editor				6 hours	
4.	4. Developing structured Technical Talk					
5.	Drafting SOP (Statement of H	Purpose)			10 hours	
6.	Video Profile				12 hours	
		7	Fotal Laborat	tory Hours	60 hours	
Mode of	Evaluation: Presentation, Disc	cussion, Role Play,	Assignments	, FAT		
Recomm	nended by Board of Studies	08.06.2019				
Approve	d by Academic Council	55 th AC	Date	13-06-2019		



	4000		eemed to be University under section			
EEE4	4099		Capstone Pro	ject		L T P J C
						0 0 0 12
Pre-r	requisite	As per the acaden	nic regulations			Syllabus version
						v. 1.0
	se Objectiv					_
	-	ficient hands-on learni	•		-	-
ana	alysis of suit	able product / process	so as to enhance t	the technic	cal skill sets in	the chosen field.
		e Outcome:				
		course the student wil				
1.		e specific problem stat	ements for ill-defi	ned real li	fe problems w	ith reasonable
•		ons and constraints.				
2.		iterature search and / o	1			
3.		experiments / Design a		ition iterat	ions and docu	ment the results.
4.		rror analysis / benchm	0 0	,		
5.	•	e the results and arrive		-		tion
6.	Documen	t the results in the form	n of technical repo	ort / preser	ntation	
0 1						
Conte		Due's st us see 1 a. a. (1 a. a.		- 1-1: 0		
1.	-	Project may be a theo	•	-		-
	• •	prototype design, fabr	-	-		1 analysis of data,
		levelopment, applied 1	•			
2.		n be for one or two se		the comple	etion of require	ed number of
		per the academic regu				
3.		dividual work or a gro				
4.		group projects, the in	1 0	port of ea	ch student sho	uld specify the
~		's contribution to the			• • •	.
5.		at inside or outside the				
6.		ons in the peer reviewe	ed journals / Intern	ational Co	onterences will	I be an added
N <i>T</i> 1	advantage			1 1 '	D (1	· ·
Mode	e of Evaluati	on: Periodic reviews,	Presentation, Fina	l oral viva	, Poster subm	15510n
Recor	mmended by	y Board of Studies	10.06.2015			
		demic Council	37 th AC	Date	16.06.2015	



EEE1902	Indu	ustrial Intern	ship			L	Т	P	J	С
						0	0	0	0	1
Pre-requisite	Completion of mi	nimum of Two	o semeste	ers		S	yllab	us v	ersi	on
									v.	1.0
Course Object										
1. The course is	designed so as to e	xpose the stud	lents to in	ndus	try env	viron	ment	and	to	
take up on-si	te assignment as tra	ainees or inter	ns.							
Expected Cour										
At the end of th	is internship the stu	dent should be	e able to:							
1. Have an	exposure to industr	rial practices a	and to wo	ork in	ı team	3				
	nicate effectively	inal practices a			i touiii	,				
	2									
J. Underst	and the impact of ei	ngineering sol	utions in	a glo	obal, e	cono	mic.			
	and the impact of einertal and societal	ngineering sol	utions in	a glo	obal, e	cono	mic,			
environ		context		_				rnin	g	
environ 4. Develop 5. Compre	nental and societal the ability to engage hend contemporary	context ge in research issues	and to in	_				rnin	g	
environ 4. Develop 5. Compre	nental and societal the ability to engage	context ge in research issues	and to in	_				rnin	g	
environ 4. Develop 5. Compre	nental and societal the ability to engage hend contemporary	context ge in research issues	and to in	_				rnin	g	
environi 4. Develop 5. Compre 6. Engage	nental and societal the ability to engage hend contemporary	context ge in research issues	and to in	_		e-loi	ng lea			
environ 4. Develop 5. Compre	nental and societal the ability to engage hend contemporary	context ge in research issues	and to in	_			ng lea		g Wee	eks
 environi 4. Develop 5. Compresent 6. Engage Contents	nental and societal the ability to engage hend contemporary	context ge in research issues her digital foot	and to in	_		e-loi	ng lea			<u>eks</u>
environ 4. Develop 5. Compre 6. Engage Contents Four weeks of v	nental and societal the ability to engag hend contemporary in establishing his/h	context ge in research issues her digital foot	and to in	_		e-loi	ng lea			eks
environ 4. Develop 5. Compre 6. Engage Contents Four weeks of v	nental and societal the ability to engag hend contemporary in establishing his/h	context ge in research issues her digital foot	and to in	_		e-loi	ng lea			eks
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environ 4. Develop 5. Compre 6. Engage Contents Four weeks of w Supervised by a	nental and societal the ability to engag hend contemporary in establishing his/h	context ge in research issues her digital foot	and to in	volv	e in li	e-loi	ng lea			eks
environ 4. Develop 5. Compre 6. Engage Contents Four weeks of v Supervised by a Mode of Evalua	nental and societal the ability to engag hend contemporary in establishing his/h vork at industry site n expert at the indu	context ge in research issues ner digital foot e. e. stry.	and to in	volv	e in li	e-loi	ng lea			•ks
environ 4. Develop 5. Compre 6. Engage Contents Four weeks of w Supervised by a	nental and societal the ability to engag hend contemporary in establishing his/h vork at industry site n expert at the indu	context ge in research issues her digital foot	and to in	volv	e in li	e-loi	ng lea			<u>eks</u>



MAT1011	Calculus for Engineers	L	Δ T	P	J	С
	<u> </u>	3	0	2	0	4
Pre-requisite	MAT1001	Syl	labus	s Vo	ersio	on
		V.	1.0			
Course Objectiv	es :					
1. To provid	e the requisite and relevant background need	cessary to understa	and th	ne ot	her	
important	engineering mathematics courses offered f	for Engineers and	Scien	tists		
2. To introdu	uce important topics of applied mathematic	s, namely Single a	nd			
Multivaria	able Calculus and Vector Calculus etc.					
3. To impart	the knowledge of Laplace transform, an in	nportant transform	ı tech	niau	ie fo	or
	which requires knowledge of integration	1		1		
Expected Course						
	course the students should be able to					
	gle variable differentiation and integrating and find the maxima and minima of fund		icu p	1001		5 111
2. understan	d basic concepts of Laplace Transforms	and solve problem	ns w	ith p	perio	odic
functions,	step functions, impulse functions and conv	volution				
3. evaluate	partial derivatives, limits, total differenti	als, Jacobians, T	aylor	ser	ies	and
optimizati	ion problems involving several variables w	ith or without con	etrain	to		
			stram	us		
4. evaluate r	nultiple integrals in Cartesian, Polar, Cylin				inate	es.
	nultiple integrals in Cartesian, Polar, Cylin	drical and Spheric	cal co	ordi		
	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver	drical and Spheric	cal co	ordi		
5. understan Gauss the	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver	drical and Spheric gence, curl and	cal co	ordi		
5. understan Gauss the	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems	drical and Spheric gence, curl and	cal co	ordi		
 5. understan Gauss the 6. demonstration 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems	drical and Spheric gence, curl and	cal co Greei	ordi		
5. understan Gauss the 6. demonstra Module:1 Apj	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem	drical and Spheric gence, curl and ns in engineering 9 hor	cal co Green	oordi ns',	Sto	
5. understan Gauss the 6. demonstra Module:1 Apj Differentiation- E	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value	cal co Green Irs Theo	oordi ns',	Sto	kes,
 5. understan Gauss the 6. demonstration Module:1 App Differentiation - E Increasing and D 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ	cal co Green Irs Theo re test	oordi ns', prem t-Ma	Sto 	kes,
 understan Gauss the demonstration Module:1 App Differentiation- E Increasing and De and Minima-Con 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative tes	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c	cal co Green Irs Theo re test	oordi ns', prem t-Ma	Sto 	kes,
 understan Gauss the demonstration Module:1 App Differentiation- E Increasing and De and Minima-Con of solids of revolution 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative test cavity. Integration-Average function value ution - Beta and Gamma functions–interrel	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c ation	cal co Green Irs Theo re test urves	oordi ns', prem t-Ma	Sto 	kes,
 understan Gauss the demonstration Module:1 App Differentiation- E Increasing and De and Minima-Consolids of revolution Module:2 Lapp 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative tess cavity. Integration-Average function value ution - Beta and Gamma functions–interrel place transforms	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c ation 7 ho	cal co Green Irs Theo re test urves	oordi ns', prem t-Ma s - V	Sto - axim olur	kes,
 5. understan Gauss the 6. demonstration- E Differentiation- E Increasing and De and Minima-Consof solids of revolution Module:2 Lag Definition of Lag 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative test cavity. Integration-Average function value ution - Beta and Gamma functions–interrel place transforms place transform-Properties-Laplace transfor	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c ation 7 ho prm of periodic f	al co Green Irs Theo re test urves urves	oordi ns', prem t-Ma t - V	Sto 	kes,
 5. understan Gauss the 6. demonstration-E Differentiation-E Increasing and De and Minima-Con of solids of revolution Module:2 Lag Definition of Lag 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative tess cavity. Integration-Average function value ution - Beta and Gamma functions–interrel place transforms	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c ation 7 ho prm of periodic f	al co Green Irs Theo re test urves urves	oordi ns', prem t-Ma t - V	Sto 	kes,
 understan Gauss the demonstration demonstration- E Increasing and De and Minima-Con of solids of revolution Module:2 Lap Definition of Lap transform of unit 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative test cavity. Integration-Average function value ution - Beta and Gamma functions—interrel place transforms place transform-Properties-Laplace transfor step function, Impulse function-Inverse La	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c ation 7 ho prm of periodic fu	al co Green Irs Theo re test urves urves	oordi ns', prem t-Ma t - V	Sto 	kes,
 5. understan Gauss the 6. demonstration Module:1 App Differentiation Increasing and Definition of Lap Module:2 Lap Definition of Lap transform of unit Module:3 Mu 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative tess cavity. Integration-Average function value ution - Beta and Gamma functions—interrel place transforms place transform-Properties-Laplace transfor step function, Impulse function-Inverse La Itivariable Calculus	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c ation 7 ho orm of periodic fi place transform-C 4 ho	al co Green Irs Theo re test urves urves urves unctio	oordi ns', prem t-Ma t-V ons-: lutic	Sto 	kes,
 5. understan Gauss the 6. demonstration- E Differentiation- E Increasing and De and Minima-Con of solids of revolution Module:2 Lap Definition of Lap transform of unit Module:3 Mu Functions of two 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative test cavity. Integration-Average function value ution - Beta and Gamma functions—interrel place transforms place transform-Properties-Laplace transfor step function, Impulse function-Inverse La Itivariable Calculus variables-limits and continuity-partial deri	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c ation 7 ho orm of periodic fi place transform-C 4 ho	al co Green Irs Theo re test urves urves urves unctio	oordi ns', prem t-Ma t-V ons-: lutic	Sto 	kes,
 understan Gauss the demonstration demonstration Increasing and De and Minima-Con of solids of revolution Module:2 Lap Definition of Lap transform of unit Module:3 Mu 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative test cavity. Integration-Average function value ution - Beta and Gamma functions—interrel place transforms place transform-Properties-Laplace transfor step function, Impulse function-Inverse La Itivariable Calculus variables-limits and continuity-partial deri	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c ation 7 ho orm of periodic fi place transform-C 4 ho	al co Green Irs Theo re test urves urves urves unctio	oordi ns', prem t-Ma t-V ons-: lutic	Sto 	kes na nes
 understan Gauss the demonstration demonstration Increasing and De and Minima-Con- of solids of revolution Module:2 Lap Definition of Lap transform of unit Module:3 Mu Functions of two and its properties 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative tess cavity. Integration-Average function value ution - Beta and Gamma functions—interrel place transforms place transforms place transform.Properties-Laplace transfor step function, Impulse function-Inverse La Itivariable Calculus variables-limits and continuity-partial deri	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivativ e - Area between c ation 7 ho form of periodic fr place transform-C 4 ho watives –total diff	al co Green Irs Theo re test urves urves urves urves urves	oordi ns', prem t-Ma t-V ons-: lutic	Sto 	hes na nes
5. understan Gauss the 6. demonstration- E Module:1 App Differentiation- E Increasing and De and Minima-Com of solids of revolution Module:2 Lap Definition of Lap transform of unit Module:3 Mu Functions of two and its properties Module:4 App	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative test cavity. Integration-Average function value ution - Beta and Gamma functions—interrel place transforms place transform-Properties-Laplace transfor step function, Impulse function-Inverse La Itivariable Calculus variables-limits and continuity-partial deri	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivative e - Area between c ation 7 ho form of periodic ful place transform-C 4 ho vatives –total diff	al co Green Irs Theo re test urves urves urves urves urves urves urves	oordi ns', prem t-Ma t-V onsV	Stol	kes na nes lace
5. understan Gauss the 6. demonstration- Differentiation- E Increasing and De and Minima-Con of solids of revolution Module:2 Lap Definition of Lay transform of unit Module:3 Mu Functions of two and its properties Module:4 Ap	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative tess cavity. Integration-Average function value ution - Beta and Gamma functions—interrel place transforms place transforms place transform-Properties-Laplace transfor step function, Impulse function-Inverse La Itivariable Calculus variables-limits and continuity-partial deri	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivative e - Area between c ation 7 ho form of periodic ful place transform-C 4 ho vatives –total diff	al co Green Irs Theo re test urves urves urves urves urves urves urves	oordi ns', prem t-Ma t-V onsV	Stol	kes,
 understan Gauss the demonstration demonstration demonstration Module:1 App Differentiation Encreasing and Definition of solids of revolutions Module:2 Lap Definition of Lap transform of unit Module:3 Mu Functions of two and its properties Module:4 App Taylor's expansion Lagrange's multipoint 	nultiple integrals in Cartesian, Polar, Cylin d gradient, directional derivatives, diver orems ate MATLAB code for challenging problem plication of Single Variable Calculus Extrema on an Interval-Rolle's Theorem an ecreasing functions and First derivative tess cavity. Integration-Average function value ution - Beta and Gamma functions—interrel place transforms place transforms place transform-Properties-Laplace transfor step function, Impulse function-Inverse La Itivariable Calculus variables-limits and continuity-partial deri	drical and Spheric gence, curl and ns in engineering 9 hou d the Mean Value t-Second derivative e - Area between c ation 7 ho form of periodic ful place transform-C 4 ho vatives –total diff	al co Green Irs Theo re test urves	oordi ns', prem t-Ma t-V onsV	Stol	kes na nes lace



Cartesian and polar co-ordinates - Evaluation of triple integrals-change of variables between Cartesian and cylindrical and spherical co-ordinates- evaluation of multiple integrals using gamma and beta functions.

	ule:6	Vector Differentiation		5 hours
		ector valued functions - gradient, tangent plan		
and c	curl–sca	lar and vector potentials-Statement of vector ic	lentities-Simp	le problems
Mod	ule:7	Vector Integration		5 hours
		and volume integrals - Statement of Green	's, Stoke's a	
		erification and evaluation of vector integrals usi		8
		C .		
Mad		Containing and the second		2 h avera
	ule:8	Contemporary Issues:		2 hours
Ind	iusiry E	xpert Lecture		
		Total Lecture hours:		45 hours
		Total Lecture nours:		45 nours
Tevt	Book(s	2)		
ТСЛІ	DOOR	»)		
1.	Tho	mas' Calculus, George B.Thomas, D.Weir and	J. Hass. 13 th e	dition. Pearson. 2014.
2.		anced Engineering Mathematics, Erwin Kreyszi		
-	rence E		8,10 20100	,
1010	101100 1			
1.	High	er Engineering Mathematics, B.S. Grewal, 43 rd	Edition ,Kha	nna Publishers, 2015
2.		er Engineering Mathematics, John Bird, 6 th Ed		
3.	-	ulus: Early Transcendentals, James Stewart, 8 th		
4.		neering Mathematics, K.A.Stroud and Dexter J		
		millan (2013)	. Dootii, 7 E	antion, i algiuve
Mod		aluation: Digital Assignments, Quiz, Continuo	us Assessmen	ts. Final Assessment
Test				
	of Chal	llenging Experiments (Indicative)		
1.		uction to MATLAB through matrices, and gene		2 hours
2		ng and visualizing curves and surfaces in MATI	LAB -	2 hours
		olic computations using MATLAB		
3.		ating Extremum of a single variable function		2 hours
4.		standing integration as Area under the curve		2 hours
5.		ation of Volume by Integrals (Solids of Revolut		2 hours
6.		ating maxima and minima of functions of sever	al variables	2 hours
7.		ing Lagrange multiplier optimization method		2 hours
8.		ating Volume under surfaces		2 hours
9.		ating triple integrals		2 hours
10.		ating gradient, curl and divergence		2 hours
11.		ating line integrals in vectors		2 hours
12.	Apply	ing Green's theorem to real world problems		2 hours



	Total Labor	atory Hours	24 hours			
Mode of Assessment: Weekly assessme	Mode of Assessment: Weekly assessment, Final Assessment Test					
Recommended by Board of Studies	12-06-2015					
Approved by Academic Council	37 th AC	Date	16-06-2015			



MAT2001	Statistics for Engineers	L	Т	Р	J	C
		3	0	2	0	4
Prerequisites	MAT1011	Syll	abus `	Versi	on:	v.1.0
Course Objective	s :	I				
descriptive 2. To analyse 3. To apply e for decision Expected Course At the end of the c 1. Compute a 2. Understand distribution 3. Apply sta interpreting 4. Make app experiment 5. Use statisti		ons. ne data. inference an numerical an ariables and ment. egression a inference th	d mod d grap l find analysi hat is	hical an s in the	g tech techi appr ana	niques. opriate
Module: 1	Introduction to Statistics		6 ha	ours		
	tatistics and data analysis-Measures of tatistics and data analysis-Measures of tatistics and tata analysis (Concepts only)		endend	cy –N	Aeası	ires of
Module: 2	Random variables].	8 ho	ours		
- joint Probability and density funct	om variables-Probability mass Function distribution and joint density functions ions- Mathematical expectation, and it n – characteristic function.	- Marginal,	condit	ional	distr	ibutior
Module: 3	Correlation and regression		4 ho	ours		
Correlation and R regression.	egression – Rank Correlation- Partial	and Multip	le corr	elatic	on- N	Iultiple
Module: 4	Probability Distributions		7 ho	ours		
	son distributions – Normal distribution - oution – Weibull distribution.	– Gamma di	stribut	tion –		
Module: 5	Hypothesis Testing I		4 ho	ours		
	esis – Introduction-Types of errors, cr sample tests- Z test for Single Proportion	-	-			



Modu	e. 6	Hypothesis Testing II	9 ho	urs
attribu		sts- Student's t-test, F-test- chi-square tes n of Experiments - Analysis of variance).		
Modu	le: 7	Reliability	5 ho	urs
	-	Hazard function-Reliabilities of seri ntainability-Preventive and repair mainter	-	• •
Modu	le: 8	Contemporary Issues	2 ho	urs
Industr	y Expert 1	Lecture	1	
		Total Lecture hours	45 ho	ours
Text b	ook(s)		1	
	S.L.Maye Applied S	ty and Statistics for engineers and scientisters and K.Ye, 9 th Edition, Pearson Educate Statistics and Probability for Engineers, D 5 th Edition, John Wiley & Sons (2016).	ion (2012).	
Refere	nce book	•		
1.	Reliabilit	y Engineering, E.Balagurusamy, Tata Mo	Graw Hill, Tenth re	eprint 2017.
2.	Probabili (2012).	ty and Statistics, J.L.Devore, 8 th Edition,	Brooks/Cole, Cenga	age Learning
3.		ty and Statistics for Engineers, R.A.Johns	son, Miller Freund's	s, 8th edition,
4.		Hall India (2011). ty, Statistics and Reliability for Engineers	and Scientista Dil	al M. Annub
5.		ard H. McCuen, 3 rd edition, CRC press (2		ai wi. Ayyuu
		ion: Digital Assignments, Continuous As	ssessment Tests, Qu	iz, Final
	ment Test	ents (Indicative)		
1.	-	ction: Understanding Data types; importin	ng/exporting data	2 hours
2.	-	ting Summary Statistics /plotting and visu ion and Graphical Representations.	ializing data using	2 hours
3.		ng correlation and simple linear regression computing and interpreting the coefficient nation.		2 hours
4.		ng multiple linear regression model to reating and interpreting the multiple coefficient nation.		2 hours
5.	Fitting	the following probability distributions: Bi	inomial	2 hours



	distribution				
б.	Normal distribution, Poisson d		2 hours		
7.	Testing of hypothesis for One real-time problems.	2 hours			
8.	Testing of hypothesis for Two real-time problems	sample means a	nd proport	ion from	2 hours
9.	Applying the t test for indepen	dent and depend	lent sample	es	2 hours
10.	Applying Chi-square test for g test to real dataset	oodness of fit te	st and Cor	tingency	2 hours
11.	Performing ANOVA for real d design, Randomized Block des	-	•	lomized	2 hours
		Tota	al laborat	ory hours	22 hours
Mode o	f Evaluation: Weekly Assessme	ent, Final Assess	ment Test		
Recom	mended by Board of Studies	25-02-2017			
-	ed by Academic Council	47 th AC	Date:	05-10-2017	



MGT1022	Lean Start up Managem	ent	L T P J C				
December 1944	NII						
Pre-requisite	NIL		Syllabus version				
			v.1.0				
	s: To develop the ability to						
	ods of company formation and management cal skills in and experience of stating of b		re-set collection of				
business ide		usiness using p	ie set concetion of				
3. Learn basic	s of entrepreneurial skills.						
Expected Course	Outcome: On the completion of this course	the student will	be able to:				
1. Understand	developing business models and growth dri	vers					
	iness model canvas to map out key compone	1	2				
•	arket size, cost structure, revenue streams, an	d value chain					
	build-measure-learn principles and quantifying business and financial risks						
Torescentg	and quantifying business and intanetar risks						
Module:1			2 Hours				
Creativity and Des	sign Thinking (identify the vertical for busi	ness opportunit	y, understand your				
customers, accurate	ely assess market opportunity)						
		Γ					
Module:2		· D 11	3 Hours				
Minimum Viable F	Product (Value Proposition, Customer Segme	ents, Build- meas	sure-learn process)				
Module:3			3 Hours				
	Development(Channels and Partners, Re	venue Model					
	ies and Costs, Customer Relationships and	Customer Deve	lopment Processes,				
Business model car	nvas –the lean model- templates)						
Module:4			3 Hours				
	Access to Funding(visioning your ventu	re taking the					
	an including Digital & Viral Marketing,	· · ·					
	Angel/VC,/Bank Loans and Key elements of						
Module:5			3 Hours				
Legal, Regulatory,	CSR, Standards, Taxes						
Module:6			2 Hours				
Lectures by Entrep	reneurs						
	Total Lecture		15 hours				
Text Book(s)							
-	wner's Manual: The Step-By-Step Guide for B	uilding a Great C	Company, Steve				
-	Ranch; 1 st edition (March 1, 2012)	1					
2 The Four Step	² The Four Steps to the Epiphany, Steve Blank, K&S Ranch; 2 nd edition (July 17, 2013)						



3	The Lean Startup: How Today's Ent Successful Businesses, Eric Ries, O	1			eate Radically
Ref	Ference Books	ciowii Dusiness, (15 Septen		
1.	Holding a Cat by the Tail, Steve Bl	ank, K&S Ranch	Publishing	DUC (August 1	4, 2014)
2	Product Design and Development,				
3	Zero to One: Notes on Startups, or I	How to Build the F	Future, Pet	er Thiel, Crown	Business(2014)
4	Lean Analytics: Use Data to Build a				
	Benjamin Yoskovitz, O'Reilly Med	dia; 1 st Edition (N	Iarch 21, 2	2013)	
5	Inspired: How To Create Products			,	1st edition
	(June 18, 2008)				
6	Website References:				
	1. http://theleanstartup.com/				
	2. https://www.kickstarter.com/pr	ojects/881308232	/only-on-l	kickstarter-the-le	eaders-guide-
	by-eric-ries				
	3. http://businessmodelgeneratio				
	4. https://www.leanstartupmachin				
	5. https://www.youtube.com/watc	1			
	 http://thenextweb.com/entrepre methodology/#gref 	neur/2015/07/05/v	whats-wro	ong-with-the-lear	n-startup-
	7. http://www.businessinsider.in/V	Whats-Lean-about	-I ean-Sta	rtun/articleshow	2/53615661 cms
	8. https://steveblank.com/tools-an			intup, untrefessio w	//////////////////////////////////////
	9. https://hbr.org/2013/05/why-the			rvthing	
	10. chventures.blogspot.in/ platform				nl
Mo	de of Evaluation: Assignments; l	Field Trips, Case	e Studies;	; e-learning; Le	earning through
	earch, TED Talks	1			0 0
Pro	ject				
1.	Project				60 hours
				Total Project	60 hours
Rec	commended by Board of Studies	08-06-2015		•	
Ap	proved by Academic Council	37 th AC	Date	16-06-2015	



PHY1701		Engineering Physics	Ι		PJ	С
			3	0	2 0	4
Pre-requisit	e	NIL	Syllabus version			
					V	.1.(
Course Obj						
		ility to apply mathematics and science in engineering applic				
	0	ar understanding of the subject related concepts and of conte	-	•		
		e-Making Skills of creating unique insights in what is being	seen of	obse	erve	1
(High	her level	thinking skills which cannot be codified)				
wheeled C		ntaomai				
Expected Co		the necessary knowledge about modern physics and its app	lication	ne in		
		and technology disciplines. This course meets the following s			ome	•6
		apply knowledge of physics in engineering problems	studem	oun		20
		design and conduct experiments, as well as to analyze and in	nterpre	t dat	a	
3. an a	bility to	identify, formulate, and solve engineering problems	1			
Aodule:1		luction to Modern Physics			hou	rs
		pothesis), Compton Effect, Particle properties of wave: Mat			1.	
		periment, Heisenberg Uncertainty Principle, Wave function	, and S	chro	ling	er
quation (tin	ne depen	dent & independent).				
Aodule:2	Applic	cations of Quantum Physics		5	1011	•6
		(Eigen Value and Eigen Function), 3-D Analysis (Qualitati				3
			vc), ru	mici	ing	
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Sources-LED & Laser Diode, Detectors-Photodetectors- PN & PIN - Applications of fiber optics in communication- Endoscopy.

Special Theory of Relativity:

Frame of reference, Galilean relativity, Postulate of special theory of relativity, Simultaneity, length contraction and time dilation.

Contemporary issues: Module:8 2 hours Lecture by Industry Experts **Total Lecture hours:** 45 hours Text Book(s) Arthur Beiser et al., Concepts of Modern Physics, 2013, Sixth Edition, Tata McGraw Hill. 1. William Silfvast, Laser Fundamentals, 2008, Cambridge University Press. 3. D. J. Griffith, Introduction to Electrodynamics, 2014, 4th Edition, Pearson. Djafar K. Mynbaev and Lowell L.Scheiner, Fiber Optic Communication Technology, 2011, 4. Pearson. **Reference Books** Raymond A. Serway, Clement J. Mosses, Curt A. Moyer Modern Physics, 2010, 3rd Indian Edition Cengage learning. 2. John R. Taylor, Chris D. Zafiratos and Michael A. Dubson, Modern Physics for Scientists and Engineers, 2011, PHI Learning Private Ltd. Kenneth Krane Modern Physics, 2010, Wiley Indian Edition. 3. 4. Nityanand Choudhary and Richa Verma, Laser Systems and Applications, 2011, PHI Learning Private Ltd. 6. S. Nagabhushana and B. Sathyanarayana, Lasers and Optical Instrumentation, 2010, I.K. International Publishing House Pvt. Ltd., R. Shevgaonkar, Electromagnetic Waves, 2005, 1st Edition, Tata McGraw Hill 7. Principles of Electromagnetics, Matthew N.O. Sadiku, 2010, Fourth Edition, Oxford. 8. Ajoy Ghatak and K. Thyagarajan, Introduction to Fiber Optics, 2010, Cambridge University 9. Press. Mode of Evaluation: Quizzes, Digital Assignments, CAT-I and II and FAT List of Challenging Experiments (Indicative) Determination of Planck's constant using electroluminescence process 2 hours 1. (Module 1) Electron diffraction (Module 1) 2 hours 2. 2 hours Determination of wavelength of laser source (He -Ne laser and diode lasers 3. of different wavelengths) using diffraction technique (Module 4) 4. Dispersive power of prism (Module 6) 2 hours 5. Optical Fiber communication (source + optical fiber + detector) (Modules 2 hours 7+8)6. Determination of size of fine particle using laser diffraction (Module 3) 2 hours Determination of the track width (periodicity) in a written CD (Module 4) 2 hours 7.



8.	PIN diode characteristics (Module 8)	2 hours
9.	Black body Radiation (Module 1+2)	2 hours
10.	Optical Fiber communication (source + optical fiber + detector) (Modules 7 + 8)	7 2 hours
11.	Analysis of crystallite size and strain in a nano -crystalline film using X-ray diffraction (Module 3)	2 hours
12.	Numerical solutions of Schrödinger equation (e.g. particle in a box problen (Module 2) (can be given as an assignment)	a) 2 hours
13.	Laser coherence length measurement (Module 4)	2 hours
14.	Proof for transverse nature of E.M. waves (Module 6)	2 hours
15.	Quantum confinement and Heisenberg's uncertainty principle (Module 1 + 3)	2 hours
	Total Laboratory Hour	s 30 hours
Reco	by Board of Studies 11.08.2017	·
Appr	coved by Academic Council46 th ACDate24.08.2017	



	(Deemed to be University under section 3 of UGC)		
PHY1901	Introduction to Innovative P	rojects	L T P J C
			1 0 0 4 2
Pre-requisite	NIL	S	yllabus version
			v.1.0
Course Objective	25:		
	ered to the students in the 1 st Year of B.Tech	. in order to orient th	em towards
independent, syste	mic thinking and be innovative.		
1. To make stude	nts confident enough to handle the day to day	y issues.	
2. To develop the	e "Thinking Skill" of the students, especially	Creative Thinking S	kills
3. To train the stu	idents to be innovative in all their activities		
	roject report on a socially relevant theme as a	a solution to the exis	ting issues
Expected Course	Outcome: Students will be able to		
1. Understand the	ne various types of thinking skills.		
2. Enhance the i	nnovative and creative ideas.		
3. Find out a suit	table solution for socially relevant issues- J of	component	
	f Confidence	1 ho	
Understanding se	elf – Johari Window –SWOT Analysis – Self	Esteem – Being a co	ontributor –
Case Study			
• 1	ing self, understanding surrounding, thinking		
	e society, Creating a big picture of being an i		
•••	ography of self – Topic "Mr X – the great inr	ovator of 2015" and	upload. (4
non- contact hou	rs)		
		1	
Module:1 B Th		1 ho	
-	haviour – Types of thinking– Concrete – Abs	-	-
	cal, Sequential and Holistic thinking – Chun	king Triangle – Cont	text Grid –
Examples – Case		to of life and talls to	tham / males
0	g at least 50 people belonging to various stra ntify a min of 100 society related issues, prob		
	em and upload along with details of people n	-	
contact hours)	eni and upload along with details of people in		l. (4 11011-
contact nours)			
Module:1 C La	teral Thinking Skill	1 ho	
	ny - HOTS - Outof the box thinking - deBox		
Examples	ing file is outer the box thinking debor	io interni tilliking in	
1	eeks - incomplete portion to be done and uplo	baded	
Module:2 A Cr	eativity	1 ho	ur
	s – Walla – Barrons – Koberg & Begnall –		
	ing 5 out of 100 issues identified for futu		ased approach
for prioritisation	n, use of statistical tools & upload . (4 non-	contact hours)	
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Module:2 B Bra	ainstorming	1 ho	ur
25 brainstorming	techniques and examples		
Project : Brainst	torm and come out with as many solutions a	s possible for the top	o 5 issues
	ad . (4 non- contact hours)	- ·	
	nd Mapping	1 ho	ur
Mind Mapping	techniques and guidelines. Drawing a mind	map	



(Deemed to be University under section 3 of UGC	Act, 1956)
Project : Using Mind Maps get another set of solutions for	orthe next 5 issues (issue $6 - 10$). (4)
non- contact hours)	
Module:4 A Systems thinking	1 hour
Systems Thinking essentials – examples – Counter Intuitive of	
Project : Select 1 issue / problem for which the possib	•
Apply Systems Thinking process and pick up one solution [e.	
other possible solutions have been left out]. Go back acceptability and upload (4 non- contact hours)	to the customer and assess the
acceptability and upload (4 non- contact nours)	
Module:4 B Design Thinking	1 hour
Design thinking process – Human element of design thinking	
Project : Apply design thinking to the selected solution, appl	
to it. Participate in "design week" celebrations upload the week	
Module:5 A Innovation	1 hour
Difference between Creativity and Innovation - Examples of	
Project: A literature searches on prototyping of your solution	
model or process and upload (4 non- contact hours)	
Module:5 B Blocks for Innovation	1 hour
Identify Blocks for creativity and innovation - overcoming	
Project : Project presentation on problem identification	
results – Interim review with PPT presentation (4 non- co	ontact hours)
Module:5 C Innovation Process	1 h
Module:5 C Innovation Process Steps for Innovation – right climate for innovation	1 hour
Project: Refining the project, based on the review report an	d unloading the text (4 non-
contact hours)	a uproduling the text (4 non
Module:6 A Innovation in India	1 hour
	1 llour
Stories of 10 Indian innovations	
Stories of 10 Indian innovations Project: Making the project better with add ons (4 non- con)	
Stories of 10 Indian innovations Project: Making the project better with add ons (4 non- cont Module:6 B JUGAAD Innovation	tact hours)
Stories of 10 Indian innovations Project: Making the project better with add ons (4 non- cont Module:6 B JUGAAD Innovation Frugal and flexible approach to innovation - doing more w	tact hours) 1 hour with less Indian Examples
Stories of 10 Indian innovationsProject: Making the project better with add ons (4 non- contModule:6 BJUGAAD InnovationFrugal and flexible approach to innovation - doing more vProject: Fine tuning the innovation project with JUGAAI	tact hours) <u>1 hour</u> with less Indian Examples D principles and uploading
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B.TECH (EIE)



2. The Art of Innovation, Tom Kelley & Jonathan Littman, Profile Books Ltd, UK, 2008

Reference Books

- 1. Creating Confidence, Meribeth Bonct, Kogan Page India Ltd, New Delhi, 2000
- 2. Lateral Thinking Skills, Paul Sloane, Keogan Page India Ltd, New Delhi, 2008
- 3. Indian Innovators, Akhat Agrawal, Jaico Books, Mumbai, 2015
- 4. JUGAAD Innovation, Navi Radjou, Jaideep Prabhu, Simone Ahuja Random house India, Noida, 2012.

Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar

Three reviews with weightage of 25:25:50 along with reports

Recommended by Board of Studies	15-12-2015		
Approved by Academic Council	39 th AC	Date	17-12-2015



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Pre-requisit	e	NIL									ibus v		_
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Course Obj													
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Expected Co	ourso A	uteomo											
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5. Identif	y the ma	ain typolo	gies, ch	aracteri	istics, a	activitie	es, acto	rs and fo	orms of	fcyber	crime		
Module:1	Being (Good and	Respo	nsible							4	5 ho	ır
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Module:2 Harassment Module:3 Corruption: 1 White collar	Social I = Type: Social I Ethical v crimes - Addicti e - Alcol of Suici	erving the Issues 1 s - Prever Issues 2 values, ca - Tax eva ion and 1 holism: E	society ntion of uses, im sions – Iealth thical v	harassn npact, la Unfair t alues, ca	nent, V aws, pre trade pr causes, i	violence eventio ractices impact	e and T on – Ele s , laws,	ectoral m	nalprac	tices;		1 ho 1 ho 5 ho mok	ur in
Module:2 Harassment Module:3 Corruption: 1 White collar Module:4 Peer pressure Prevention Sexual Healt	Social I - Type: Social I Ethical v crimes - Addicti e - Alcol of Suici th: Preve Drug A lifferent	erving the Issues 1 s - Prever Issues 2 values, ca - Tax eva ion and 1 holism: E des; ention and	society ntion of uses, im sions – Iealth thical v l impact	harassm pact, la Unfair t alues, ca t of pre-	nent, V aws, pre trade pr causes, i -marital	iolence eventio ractices impact	e and T on – Eles , laws, ancy a	ectoral m	n nalprac on – I ally Tr	etices;	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	4 hor 4 hor 5 hor mok iseas 3 hor	ur in es
Viodule:2 Harassment Module:3 Corruption: 1 White collar White collar Peer pressure Prevention Sexual Healt Module:5 Abuse of coprevention	Social I Type: Social I Ethical v crimes Addicti e - Alcol of Suici h: Preve Drug A lifferent	erving the Issues 1 s - Prever Issues 2 values, ca - Tax eva ion and 1 holism: E des; ention and types of	society ntion of uses, im sions – Iealth thical v l impact	harassm pact, la Unfair t alues, ca t of pre- d illega	nent, V aws, pre trade pr auses, i -marital	iolence eventio ractices impact	e and T on – Eles , laws, ancy a	ectoral m	n nalprac on – I ally Tr	etices;	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	4 ho 4 ho 5 ho mok iseas 3 ho d	
Module:2 Harassment Module:3 Corruption: 1 White collar Module:4 Peer pressure Prevention Sexual Healt Module:5 Abuse of c prevention	Social I - Type: Social I Ethical v crimes - Addicti e - Alcol of Suici th: Preve Drug A lifferent Persona	erving the Issues 1 s - Prever Issues 2 values, ca - Tax eva ion and 1 holism: F des; ention and buse types of al and P	society ntion of uses, im sions – Iealth thical v l impact legal an	harassn npact, la Unfair t alues, ca t of pre- d illegal nal Eth	nent, V aws, pre trade pr auses, i -marital d drugs: hics	iolence eventio ractices impact l pregn	e and T on – Ele s , laws, ancy a al valu	ectoral m preventi nd Sexua es, cause	n nalprac on – I ally Tr	etices;	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	4 hor 4 hor 5 hor mok iseas 3 hor	ir in es
Viodule:2 Harassment Viodule:3 Corruption: 1 White collar Vidule:4 Peer pressure Prevention Sexual Healt Viodule:5 Abuse of c prevention Viodule:6 Dishonest	Social I Type: Social I Ethical v crimes - Addicti e - Alcol of Suici th: Preve Drug A lifferent Persona y - Steal:	erving the Issues 1 s - Prever Issues 2 values, ca - Tax eva ion and 1 holism: E des; ention and types of al and P ing - Mal	society ntion of uses, im sions – Health thical v l impact legal an practice	harassn npact, la Unfair t alues, ca t of pre- d illegal nal Eth	nent, V aws, pre trade pr auses, i -marital d drugs: hics	iolence eventio ractices impact l pregn	e and T on – Ele s , laws, ancy a al valu	ectoral m preventi nd Sexua es, cause	n nalprac on – I ally Tr	etices;	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	4 hor 4 hor 5 hor mok iseas 3 hor d 4 hor	ir in es ir
Viodule:2 Harassment Viodule:3 Corruption: 1 White collar View collar Peer pressure Prevention Sexual Healt Viodule:5 Abuse of c prevention Viodule:6 Dishonest Viodule:7 Hacking and	Social I = Type: Social I Ethical v crimes - Addicti e - Alcol of Suici th: Preve Drug A lifferent Persona y - Steal	erving the Issues 1 s - Prever Issues 2 values, ca - Tax eva ion and 1 holism: F des; ention and buse types of al and Pr ing - Mal of Techn	society ation of uses, im sions – Iealth thical v l impaction legal an ofession practice	harassn npact, la Unfair t alues, ca t of pre- d illegal nal Eth s in Exa	nent, V aws, pre trade pr auses, i -marital aninati	/iolence eventio ractices impact l pregn : Ethic ions – l	e and T on – Ele s , laws, ancy a al valu Plagiar	ectoral m preventi nd Sexua es, cause	n nalprac on – Il ally Tr es, imp	etices;	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	4 ho 4 ho 5 ho mok iseas 3 ho d	
Aodule:2 Harassment Aodule:3 Corruption: 1 Vhite collar Aodule:4 Peer pressure Prevention Eexual Healt Abuse of correvention Aodule:5 Dishonesty Aodule:7	Social I - Type: Social I Ethical v crimes - Addicti e - Alcol of Suici h: Preve Drug A lifferent Persona y - Steal Abuse o other cy	erving the Issues 1 s - Prever Issues 2 values, ca - Tax eva ion and 1 holism: F des; ention and buse types of al and Pr ing - Mal of Techn	society ntion of uses, im sions – Iealth thical v l impact legal an rofessio practice ologies es, Add	harassn pact, la Unfair t alues, ca t of pre- d illega nal Eth s in Exa iction to	nent, V aws, pre trade pr auses, i -marital aninati	/iolence eventio ractices impact l pregn : Ethic ions – l	e and T on – Ele s , laws, ancy a al valu Plagiar	ectoral m preventi nd Sexua es, cause	n nalprac on – Il ally Tr es, imp	etices;	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	4 hor 4 hor 5 hor mok iseas 3 hor d 4 hor	ır in ir



e Books		
Dhaliwal, K.K, "Gandhian Philosophy of Ethics: A St	udy of Relation	ship between his
Presupposition and Precepts, 2016, Writers Choice, New	v Delhi, India.	
Vittal, N, "Ending Corruption? - How to Clean up Indi	a?", 2012, Peng	guin Publishers,
UK. Pagliaro, L.A. and Pagliaro, A.M, "Handbook of G	Child and Adol	escent Drug and
Substance		
Abuse: Pharmacological, Developmental and Clinical	Considerations	s", 2012Wiley
	ndia", 2012, L	ambert Publishers,
Germany.		
Evaluation: CAT, Assignment, Quiz, FAT and Semina	r	
l by Academic Council 46 th AC Date	24-08-20)17
	Presupposition and Precepts,2016, Writers Choice, New Vittal, N, "Ending Corruption? - How to Clean up India UK. Pagliaro, L.A. and Pagliaro, A.M, "Handbook of C SubstanceAbuse: Pharmacological , Developmental and Clinical Publishers, U.S.A.Pandey, P. K (2012), "Sexual Harassment and Law in I Germany.Evaluation: CAT, Assignment, Quiz, FAT and Seminar ended by Board of Studies 26-07-2017	Abuse: Pharmacological , Developmental and Clinical ConsiderationsPublishers, U.S.A.Pandey, P. K (2012), "Sexual Harassment and Law in India", 2012, LGermany.Evaluation: CAT, Assignment, Quiz, FAT and Seminarended by Board of Studies 26-07-2017



	(Deemed to be University under section 3 of UGC Act,	1956)	
EEE1002	Electric circuits		L T P J C
-			
Pre-requisite	NIL		Syllabus version
Anti-requisite	NIL		v. 1.0
Course Objective			
	mathematical model of the electric circuits using	ng basic laws	
	network theorems to solve the electric circuits		· ·,
	nalyze the steady state and transient responses	of DC and AC c	circuits
Expected Course			
-	of this course the student will be able to:		
	equations of the electric circuits using basic la		
	response of DC circuits using basic analysis m		
1	esponse of DC circuits using network theorems		
	nsient behavior of electric circuits with differe ements of AC circuits and the phasor concept	in types of source	
	ace circuits, and solve three phase ac circuits		
	agnetic circuits		
7. Borve simple in			
Module:1 Fun	damentals of Electric Circuits		5 Hours
	rcuit Elements, Ohms Law and Kirchhoff's	Laws. Voltage	and Current Division,
Star-Delta Transfo	rmation and Source Transformation.		
Module:2 Line	ar Circuit Analysis		5 Hours
	nalysis of Linear Network with Independent a	nd Dependent D	
	· · · ·		
	vork Theorems		7 Hours
	em, Norton's Theorem, Maximum Power ts with independent and dependent sources.	Transfer Theore	m and Superposition
Module:4 Trai	nsient Circuit Analysis		7 Hours
	Elements – L and C. Analysis of Source Free	RC. RL and RL	
-	sponse of RC, RL and RLC Circuits.		e enealts, singularly
· •			
	oduction to Phasors		7 Hours
	usoids and Phasors, Impedance and Admittan		1
	es of Sinusoids, Instantaneous and Average		omplex Power - Real
Power, Reactive Po	ower and Apparent Power Calculations and Po	ower Factor.	
Madular	Cincuita and Degrade		7 11
	Circuits and Resonance	dant ann T	7 Hours
•	State Analysis for AC circuits with independent and C Combinations. Resonance in Series		1 1 1
,			
Three Fhase Circu	its, Power in a Balanced System, Three Phase	i owei wieasuien	
Module:7 Mag	netic Circuits		Hours 5
	pled Circuits, Self and Mutual Inductance,	Dot Convention	
č	alysis of Magnetically Coupled Circuits.		., <u>Liter</u> _b , in coupled
	ntemporary issues:		2 hours
	Total Lecture hours:		45 Hours
			4 5 1 000 8



Text Be	ook(s)						
1.	Charles K Alexander, Mathew N	VO Sadiku, 'Fune	lamentals	of Electric Circuits, Tata McGraw			
	Hill, 2012.						
Referen	Reference Books						
1.	Allan R. Hambley, 'Electrical	Engineering-Prin	ciples &	Applications', Pearson Education			
	Limited, 7/e, 2017.						
2.	Robert L Boylestad, 'Introductor	y Circuit Analysi	s', Pearson	n Education Limited, 13/e, 2016.			
3.	W. H. Hayt, J.E. Kemmerly and	S. M. Durbin, 'I	Engineerin	g Circuit Analysis', McGraw Hill,			
	New York, 8/e, 2012.		-	-			
4.	Abhijit Chakrabarti, 'Circuit Tl	heory : Analysis	and Synt	hesis', Dhanpat Rai & Co., New			
	Delhi, 6/e, 2014						
5.	Mahmood Nahvi; Joseph A Edm	inister, 'Electric (Circuits', I	McGraw Hill Education, 6/e, 2015.			
Mode o	Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar						
Recom	mended by Board of Studies	29/05/2015					
Approv	ved by Academic Council	37 th AC	Date	16/06/2015			



EEE1004 Engineering Electromagnetics				Т	P J	C C
			3	0	2 () 4
Pre-requisite	MAT1011	S	Sylla	abu	is ve	rsio
Anti-requisite	NIL					v. 1.
Course Objectives:						
1 0 .1 1	• • • • • • • • • • • • • • • • • • • •	•	.1	•		

1. To convey the basic physical concepts that lie behind all electrical engineering, the interactions between charged particles, whether stationary or in motion.

2. To examine the electric and magnetic forces between stationary and steadily moving charged particles.

3. To study the various electric & magnetic field concepts both in static and time varying condition.

Expected Course Outcome:

On the completion of this course the student will be able to:

- 1. Explore different coordinate systems related to magnetic fields.
- 2. Define the electric flux density, field intensity and different charge distributions.
- 3. Demonstrate the boundary conditions and method of images.
- 4. Compare the electric and magnetic boundary conditions, calculate the capacitance and inductance.
- 5. Analyze Maxwell equations.
- 6. Summarise the electric magnetic waves and wave propagation in different medium.
- 7. Apply the electric and magnetic field concepts
- 8. Design and Conduct experiments, as well as analyze and interpret data

Module:1 **Review of Scalar and Vector Fields**

Different Co-ordinate Systems: Cartesian, Cylindrical and Spherical –Differential elements in different coordinate systems - Del Operator: Divergence, Curl and Gradient, Divergence Theorem -Stoke's Theorem - Helmholtz's Decomposition.

Module:2 **Electrostatics: Charges**

Coulomb's law - Electric Field Intensity - Electric Flux - Gauss's Law - Potential due to Point, Line and Surface Charge Distributions.

Electric Fields in Dielectrics and Conductors 8 Hours Module:3 Different current flow mechanisms - Continuity equation and relaxation time - Boundary conditions - Laplace and Poisson's equations - Solutions - Analytical Methods - Variables separable methods -Method of images - Numerical Techniques - Finite Difference Method - Electrostatic Energy -**Capacitance Calculations**

Module:4 **Magneto statics**

Magnetic Fields - Magnetic Flux - Biot Savart's Law - Ampere's Law - Magnetic Torque and Moment - Forces due to Magnetic Fields - Vector Potential - Magnetic Boundary Conditions -Inductors and Inductances – Calculations - Magnetic Energy

Module:5 **Electromagnetic Fields**

Faraday's law - Lenz's Law - Maxwell's equations - Displacement current - Maxwell's Equations in Final Forms - Time Varying Fields - Relation between field theory and circuit theory

5 Hours

8 Hours

8 Hours

6 Hours



		(Deemed to be University under section 3 of UGC Act, 1956)						
Mod	ule:6	Electromagnetic Waves Generation	8 Hours					
Prop	agation	of waves in lossy dielectrics, conductors and free space - Skin e	effect – Complex					
Perm	nittivity-	Power and Poynting Vector.						
N / 1		A						
	ule: 7	Application	2 hours					
Sour	ces, Effe	cts and application of Electromagnetic fields						
Mod	ule:8	Contemporary issues:	2 Hours					
11100	uitto	Total Lecture hours:	45 Hours					
Mod	e of Eva	luation: CAT / Assignment / Quiz / FAT / Project / Seminar						
1.		enging Experiments (Indicative) magnetic concepts using Matlab tool functions	2 hours					
1. 2.		Representation ,Coordinate Systems and conversion	2 hours					
2. 3.	Vector Representation (Conversion)2 hoursVolume and surface integration (Vectorial)2 hours							
<i>3</i> . 4.		ining electric field distribution for an infinite sheet charges and line	2 hours					
4.	charge	ining electric field distribution for an infinite sheet charges and fine	2 110015					
5.	0	ining voltage due to line charge or surface or volume charge	2 hours					
6.		stored in a region due to electric field	2 hours					
7.		dielectric(\Box r1) - dielectric (\Box r2) boundary condition problem	2 hours					
8.	-	ination of electrical field and potential inside the parallel plate	2 hours					
	capacito							
9.	Determ	ination of voltage and electric field distribution inside the co-axial	2 hours					
		Laplace equation).						
10.		ining and plotting the magnetic field due to infinite sheet current	2 hours					
11.		ination of an inductance of a solenoid	2 hours					
12.		ination of the mutual inductance between an infinite line current and gular coil	2 hours					
13.	Electro	magnetic wave propagation in good conductors.	2 hours					
14.		ination of Electric field and Voltage profile for a single core cable s ruptured by the presents of a needle inclusion on the outer sheath.	2 hours					
15.	Determ	ination of static magnetic field induced by the stator windings in a electric motor.	2 hours					
		Total Laboratory Hours	30 hours					
Mod	e of Eva	luation: Assignment / FAT	·					
	Book(s)							
1.		hew N. O. Sadiku & S. V. Kulkarni, 'Principles of Electroma versity Press, New York, Sixth Edition, 2015.	agnetics', Oxford					
Refe	rence B	ooks						
1.	Hart 2012	Hayt, John A. Buck, 'Engineering Electromagnetics', McGraw-Hill	l, Eighth Edition,					
2.		dminister, 'Schaum's Outline of Electromagnetics', McGraw-Hill Pro	ofessional, Fourth					
			,					
	Edition, 2013.							
3.		E. Lonngren, Sava Savov, Randy J. Jost, 'Fundamental of Electronic Sava Savov, Randy J. Jost, 'Fundamental of Electronic Sava Savava, Sava	ctomagnetic with					



Recommended by Board of Studies	30/11/2015		
Approved by Academic Council	39 th AC	Date	17/12/2015



EEE1005		(Deemed to be University under section 3 of UGC Act, Signals and systems		L	T	P J	C
				3	0	0 0	3
Pre-requisite	e	MAT2002		Sylla	bus	s ver	sion
Anti-requisit		NIL		J			. 1.0
Course Obje							
•		e mathematical representations of signals and	l systems in cont	inuous	and	disc	rete
domain.							
2. Analyse an	d perfo	orm various operations with the signals.					
3. Analyse th	e respo	nse of linear time invariant (LTI) systems in	continuous and d	iscrete	don	nain.	
4. Understand	d sampl	ing theorem and represent signals in the freq	uency domain.				
Expected Co							
On the comp	letion o	f this course the student will be able to:					
1. Define the	e term s	signals and systems, apply translation techni	ques and classif	y differ	ent	type	s of
systems base	d on the	eir properties					
2. Analyse L'	ΓI syste	ems					
3. Apply Fou	rier Sei	ies techniques for dealing with periodic cont	inuous and discre	ete syste	ems		
4. Differenti	ate the	behaviour of LTI systems as periodic an	nd aperiodic sig	nals us	sing	Fou	ırier
Transforms							
5. Construct	the orig	inal signal from samples.					
6. Extend the	analys	is to unstable systems using the Laplace Tran	sforms				
7. Develop an	nd form	ulate techniques of dealing with discrete syst	ems using the z-t	transfor	m.		
Module:1		amentals of Signals				5 Ho	ours
Representatio	on of (Continuous and Discrete-time Signals, Uni	t Step, Unit Ra	mp, U	nit	Impı	ılse,
Sinusoidal a	nd Con	plex Exponentials. Classification of signal	s – Periodic and	l Aperi	odi	e Sig	gnal,
Even and Od	d Signa	l, Energy and Power Signal, Deterministic a	nd Random sign	als. Tra	nsf	orma	tion
of Independe	nt Vari	ables –Time Shifting, Time Scaling and Time	e Reversal.				
Module:2	Funda	amentals of Systems				5 Ho	urs
Representatio	on of C	Continuous and Discrete Time Systems. Cla	assification of sy	/stems	- S	tatic	and
-		d Nonlinear, Time variant and Time Invaria	-				
•		ertible and non- invertible systems. Blo					
Interconnecti		-	U	1			
Module:3		sis of LTI System				6 Ho	ours
Impulse Resp	ť	f Continuous and Discrete Time LTI Systems	. Convolution, B	asic pro	oper		
systems using			,	I	T		
	- 1	*					
Module:4	Fouri	er Representation of Periodic Signals	6 Hours				
	and L	TI Systems					
	-	sentation of Continuous Time and Discrete-	1 0		ope	rties	of
Fourier Serie	s, Pars	eval's relation, Response of LTI Systems to (Complex Expone	ntials.			
Module:5	and L	er Representation of Aperiodic Signals TI Systems	7 Hours				
		d Discrete Time Fourier Transforms, Propert					
		of LTI system. Applications: Modulation for	communications	, Filteri	ng,	Tim	e–
Frequency re	present	ation and uncertainty principle.					



Modul	e:6	Representation of Continuous time signals by its samples	5 Hours
Sampli	ng Th	eorem, Effects of Sampling and Aliasing. Sampling	of Continuous Time Signals with
		Hold, Reconstruction of Signal from Samples – Inte	
<u></u>			
Module:7		Analysis of Continuous and Discrete LTI	9 Hours
		Systems with Laplace Transform and Z-	
		Transform	
		aplace Transform, Region of Convergence, Character	•
		sforms, transfer functions. Mapping of s-plane to z-	
-		onvergence, Power series expansion, and partial frac	tion expansion. Characterization of
LTI sys	stems	using Z -Transforms.	
Modul	e:8	Lecture by industry experts.	2 Hours
Modul	e:8	Lecture by industry experts. Total Lecture hours:	2 Hours 45 Hours
Module Text Be		Total Lecture hours:	
	ook(s)	Total Lecture hours:	45 Hours
Text B	ook(s) Sign	Total Lecture hours:) als and Systems by Alan V. Oppenhein, Alan S. W	45 Hours
Text Bo	ook(s) Sign nce B	Total Lecture hours:) als and Systems by Alan V. Oppenhein, Alan S. W	45 Hours Allsky and S. Hamid, Pearson 2016.
Text B 1. Referen 1.	ook(s) Sign nce Be Sign	Total Lecture hours:) hals and Systems by Alan V. Oppenhein, Alan S. W ooks hals and systems by Simon Haykin, John Wiley, 201	45 Hours illsky and S. Hamid, Pearson 2016. 6.
Text Bold 1.	ook(s) Sign nce B Sign Fund	Total Lecture hours:) als and Systems by Alan V. Oppenhein, Alan S. W ooks	45 Hours illsky and S. Hamid, Pearson 2016. 6.
Text B 1. Referen 1. 2.	ook(s) Sign nce B Sign Func S. H	Total Lecture hours:) als and Systems by Alan V. Oppenhein, Alan S. W ooks als and systems by Simon Haykin, John Wiley, 201 damentals of Signals and Systems Usin Web and N	45 Hours illsky and S. Hamid, Pearson 2016. 6. ATLAB, Edward W Kamen, Bonnie
Text B 1. Referent 1. 2. Mode of	ook(s) Sign nce Bo Sign Fund S. H of Eva	Total Lecture hours:) mals and Systems by Alan V. Oppenhein, Alan S. W ooks mals and systems by Simon Haykin, John Wiley, 201 damentals of Signals and Systems Usin Web and M leck, Pearson, 2014.	45 Hours illsky and S. Hamid, Pearson 2016. 6. ATLAB, Edward W Kamen, Bonnie



EEE2001		Network theory	L	T	P J	C
			3	0	0 0	3
Pre-requisit	e	EEE1002, MAT1011	Svlla	bus	s ver	sion
Anti-requisi		NIL				. 1.0
Course Obj						
		y state response of circuits and discuss various theorems and their	: ap	plic	catio	ns
2. Apply Lap response	-	nsform and Fourier transform techniques to circuits and obtain th	e cor	npl	ete	
-		ters and analyse its frequency response.				
Expected C	ourso A	utcomo:				
A		f this course the student will be able to:				
1		ge and mesh current methods to analyse circuits in steady state.				
		nsform techniques for solving problems and discuss the complete	resp	ons	e of	
3. Derive the	e transfe	r function and identify its poles and zeros				
		onics in nonsinusoidal inputs to circuits using Fourier series.				
		nsform to circuits with nonsinusoidal inputs				
01		ters and analyse the frequency response.				
7. Evaluate a	ind relat	e two-port network parameters.				
Module:1	Sinus	oidal Steady State Analysis			6 Ho	ours
		Nodal Analysis, Mesh Analysis, Thevenin's Theorem, Norton's T	Theo	rem		
		ansfer Theorem and Superposition Theorem for circuits with inde				
dependent si			I · ·			
•						
Module:2		ling of Network in s-Domain			6 Ho	
		, L and C in s-Domain. Application of Laplace Transforms to inte				
		and RLC circuits. Transfer Function. Impulse Response of RL a	ind R	C (Lircu	its
and Respons	e to any	other sources using convolution integral.				
Module:3	Comr	lete Response of Networks			6 Ho	
	-	h zero and non zero initial conditions in s-domain. Pole-Zero Ma	ans	Net		
Stability.	y515 W10	The set of the first set of the s	чр з. 1	1011	NOIK	
Module:4	Netwo Excita				7 Ho	ours
Trigonometr	ic Four	ier Series for Non-Sinusoidal Functions. Circuit Analysis. Ave	rage	Pc	wer	and
RMS Values	s using F	Fourier Coefficients. Exponential Fourier Series.				
Module:5	Netwo	ork Analysis using Fourier Transform			7 Ho	ours
Fourier Tran	sform fo	or commonly used periodic and aperiodic functions. Circuit Analy	ysis i	in fr	reque	ency
domain. Ene	rgy in th	ne signal using Parseval's Theorem.				
Module:6	Desig	n of Filters			4 Ho	ours
	<u> </u>	cy Response of RL, RC and RLC circuits. Passive Filters– Low P	ass,			
	-	d Stop. Magnitude and Frequency Scaling.		0		
Module:7		Port Networks			6 Ho	ours
Introduction	to Tw	o-Port Networks - Impedance and Admittance parameters, T	ransi			
)		Dage			_



Hybrid	Paramete	rs. Relationship between	parameter, Interco	onnection	of Networks.
Module	:8 C	contemporary issues:			2 hours
			Total Lecture h	ours:	45 Hours
Text Bo	ok(s)				
1.	Charles	K Alexander, Mathew 1	N O Sadiku, "Fu	Indamenta	als of Electric Circuits", Tata
	McGrav	v Hill, 2012.			
Referen	ce Book	S			
1.	Allan R	. Hambley, 'Electrical En	gineering-Princip	les & Ap	plications' Pearson Education,
	First Im	pression, 6/e, 2013.			
2.	Robert	L Boylestad, 'Introductor	y Circuit Analysi	s' Pearson	n Education Ltd, 12th Edition,
	2010.				
3.	Н. Нау	rt, J.E. Kemmerly and S	. M. Durbin, 'E	ngineering	g Circuit Analysis', 6/e, Tata
	McGrav	v Hill, New Delhi, 2011.			
Mode o	f Evaluat	ion: CAT / Assignment /	Quiz / FAT / Proj	ect / Semi	inar
Recomm	nended b	y Board of Studies	29/05/2015		
Approv	ed by Ac	ademic Council	37 th AC	Date	16/06/2015



	(Deemed to be University under section 3 of UGC Act, 1956)				
EEE2002	Semiconductor Devices and Circuits	L	Τ	P	JC
		2	0	2	4 4
Pre-requisite	EEE1002	Sylla	bus	s ver	sion
Anti-requisit	e NIL	-		v	. 1.0
Course Obje	tives:				
	e knowledge of solid state devices principles to analyze electronic	circuits.			
	mplifiers under different configurations and study their responses				
0	nds on learning experience and software knowledge by doing pract	tical exer	cis	es ar	d
projects.					
1 0	irse Outcome:				
<u> </u>	etion of this course the student will be able to:				
-	the behavior of semiconductor devices				
2. Analyze die					
•	haracteristics of various transistors with DC sources				
	e various configurations of BJT				
-	the various configurations of MOSFET				
	high speed response of semiconducting devices.				
-	ad contrast the negative and positive feedback in amplifiers				
-	conduct experiments, as well as analyze and interpret data				
-	mponent or a product applying all the relevant standards with real	istic con	stra	inte	
J. Design a co	inponent of a product apprying an the relevant standards with rear		, ii a	mus.	
Module:1	Semiconductor Device Physics			2 н	ours
	ors, charge carriers, intrinsic and extrinsic semi-conductors,	carrier	σe		
	, injection of carriers, Drift and diffusion, carrier mobility, conductors,		50	nera	uon,
	Diode Circuit Analysis	cuvity.		<u>4 H</u>	ours
	iode – Formation of Junction, Junction Capacitance, characteristi	cs Diod	<u> </u>		
	s = 1 inder and 1 lamber recritiers with and without filters d	other mu	ltir	le d	inde
	s – Clipper and Clamper, rectifiers with and without filters, or	other mu	ltip	ole d	iode
encuns, Regu	ated power supplies.	other mu	ltip	ole d	iode
	lated power supplies.	other mu	ltir		
Module:3	Transistor DC Analysis			5 H	ours
Module:3 BJT Characte	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa			5 H	ours
Module:3 BJT Characte point analysis	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs.			5 H Opera	ours ating
Module:3 BJT Characte point analysis Module:4	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers	d line an	dC	5 Ho Opera 5 Ho	ours ating ours
Module:3 BJT Character point analysis Module:4 Small signal	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers analysis of BJT amplifiers, Calculation of Gain, Input Imp	d line an	dC	5 Ho Opera 5 Ho	ours ating ours
Module:3 BJT Characte point analysis Module:4 Small signal	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers	d line an	dC	5 Ho Opera 5 Ho	ours ating ours
Module:3 BJT Character point analysis Module:4 Small signal Impedance. B	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers analysis of BJT amplifiers, Calculation of Gain, Input Impasic BJT amplifier Configurations (CE, CC and CB). Power Ampl	d line an	dC	5 H Opera 5 H 1 Ou	ours ating ours atput
Module:3 BJT Characte point analysis Module:4 Small signal Impedance. B Module:5	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers analysis of BJT amplifiers, Calculation of Gain, Input Imp asic BJT amplifier Configurations (CE, CC and CB). Power Ampl MOSFET Amplifiers	d line an bedance ifiers.	d C	5 Ho Dera 5 Ho 1 Ou 4 Ho	ours ating ours atput
Module:3BJT Characterpoint analysisModule:4Small signalImpedance. BModule:5Small signal	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers analysis of BJT amplifiers, Calculation of Gain, Input Impasic BJT amplifier Configurations (CE, CC and CB). Power Ampl MOSFET Amplifiers analysis of MOSFET amplifiers. Calculation of Gain, Input Impasic BJT amplifiers	d line an bedance ifiers. pedance	d C	5 Ho Dera 5 Ho 1 Ou 4 Ho	ours ating ours atput
Module:3BJT Characterpoint analysisModule:4Small signalImpedance. BModule:5Small signal	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers analysis of BJT amplifiers, Calculation of Gain, Input Imp asic BJT amplifier Configurations (CE, CC and CB). Power Ampl MOSFET Amplifiers	d line an bedance ifiers. pedance	d C	5 Ho Dera 5 Ho 1 Ou 4 Ho	ours ating ours atput
Module:3BJT Characterpoint analysisModule:4Small signalImpedance. BModule:5Small signalImpedance. B	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers analysis of BJT amplifiers, Calculation of Gain, Input Impasic BJT amplifier Configurations (CE, CC and CB). Power Ampl MOSFET Amplifiers analysis of MOSFET amplifiers. Calculation of Gain, Input Impasic MOSFET Amplifiers analysis of MOSFET amplifiers. Calculation of Gain, Input Impasic MOSFET amplifier configurations - (CS, CD and CG) amplifier	d line an bedance ifiers. pedance	d C	5 Ho Opera 5 Ho 1 Ou 4 Ho d Ou	ours ating ours itput ours itput
Module:3BJT Characterpoint analysisModule:4Small signalImpedance. BModule:5Small signalImpedance. BModule:6	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers analysis of BJT amplifiers, Calculation of Gain, Input Impasic BJT amplifier Configurations (CE, CC and CB). Power Ampl MOSFET Amplifiers analysis of MOSFET amplifiers. Calculation of Gain, Input Impasic MOSFET Amplifiers analysis of MOSFET amplifiers. Calculation of Gain, Input Impasic MOSFET amplifier configurations - (CS, CD and CG) amplifier Frequency response	d line an wedance ifiers. pedance iers.	d C and	5 Ho Deera 5 Ho 1 Ou 4 Ho d Ou 5 Ho	ours ating ours itput ours itput
Module:3 BJT Characte point analysis Module:4 Small signal Impedance. B Module:5 Small signal Impedance. B Module:6 Amplifier Fr	lated power supplies. Transistor DC Analysis ristics, current gains, h-parameters, MOSFET Characteristics, Loa DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers analysis of BJT amplifiers, Calculation of Gain, Input Impasic BJT amplifier Configurations (CE, CC and CB). Power Ampl MOSFET Amplifiers analysis of MOSFET amplifiers. Calculation of Gain, Input Impasic MOSFET amplifiers. Calculation of Gain, Input Impasic MOSFET amplifier configurations - (CS, CD and CG) amplifier Frequency response equency Response, System Transfer Functions, Frequency Response	d line an bedance ifiers. pedance iers.	d C anc anc	5 H Opera 5 H 1 Ou 4 H d Ou 5 H ansis	ours ating ours atput ours atput
Module:3 BJT Characte point analysis Module:4 Small signal Impedance. B Module:5 Small signal Impedance. B Module:6 Amplifier Fr	lated power supplies. Transistor DC Analysis cistics, current gains, h-parameters, MOSFET Characteristics, Loa , DC analysis and biasing of BJTs and MOSFETs. BJT Amplifiers analysis of BJT amplifiers, Calculation of Gain, Input Impasic BJT amplifier Configurations (CE, CC and CB). Power Ampl MOSFET Amplifiers analysis of MOSFET amplifiers. Calculation of Gain, Input Impasic MOSFET amplifier configurations - (CS, CD and CG) amplif Frequency response equency Response, System Transfer Functions, Frequency Response of the FET, High-Frequency Response	d line an bedance ifiers. pedance iers.	d C anc anc	5 H Opera 5 H 1 Ou 4 H d Ou 5 H ansis	ours ating ours atput ours atput



Module:7	Feedback Amplifiers and Oscillators	3 Hours					
Basic concep	Basic concepts of feedback-Negative feedback advantages and types. Voltage/Current Series/Shunt,						
Positive feed	Positive feedback, Stability, Conditions for Oscillations RC and LC oscillators.						

Mod	lule:8	Contemporary issues:				2 Hours
		1 0	Total Lecture h	ours:		30 Hours
Tex	t Book(s)				
1.		A.S.Sedra, K.C. Smith, "N	Microelectronic C	irquite. Th	pory with App	lications" 6Ed
1.		Oxford University Press, 2		incuits. 11	icory with App	ileations, olea,
Refe	erence B					
1.		D.A. Neamen, Electronic C	rircuits – Analysis	and Desig	on 3Ed McGray	w Hill 2011
2.		David A. Bell, "Electronic	Devices and Circ	uits", Sed,	Oxford Univers	ity Press, 2008.
3.		Behzad Razavi, Fundamen	tals of Microelect	conics, 3Ec	l, Wiley, 2013.	
4.		Ben Streetman, Sanjay Ban	nerjee, Solid State	Electronic	Devices, 7ED,	Pearson, 2014.
Mod	le of Eva	luation: CAT / Assignment /	/ Quiz / FAT / Pro	ject / Sem	inar	
		lenging Experiments (Indic		,		
1.		tion of logic gates using dio				2 hours
2.		line and load voltage regula		Zener dio	de	2 hours
3.	-	a capacitor for a rectifier cir	-			2 hours
4.	Ŭ	various clamping circuits us				2 hours
5.	Design	various clipping circuits usi	ng diode			2 hours
6.	_	the circuit using BJT as a s		system		2 hours
7.	Obtain	the h-parameters for differ	rent configuration	ns in BJT	using input –	2 hours
	output	characteristics				
8.	Design	the circuit for a verification	on of BJT as a sw	vitch and a	amplifier using	2 hours
		gton pair				
9.	Design	the circuit to perform DC a	nalysis of a BJT			2 hours
10.		ing characteristics of MOSF				2 hours
11.	Design	the circuit for verifying UJT	T as a triggering sv	vitch		2 hours
12.	Design	a RC coupled amplifier				2 hours
13.	13. Design a common collector amplifier					2 hours
14.	Design	a common source FET amp	lifier			2 hours
			r	Fotal Lab	oratory Hours	30 hours
Mod	le of Eva	luation: Assignment /FAT				
Reco	ommende	ed by Board of Studies	29/05/2015			
App	roved by	Academic Council	37 th AC	Date	16/06/2015	



EEE2005	Digital Signal Processing		L T P J C					
			2 0 2 0 3					
Pre-requisite	EEE1005		Syllabus version					
Anti-requisite	Anti-requisite NIL v.							
Course Objectives:								
1 To magazina Lin	1. To recognize Linear Time Inversion (ITI) discrete time systems							

- 1. To recognize Linear Time-Invariant (LTI) discrete-time systems
- 2. To design IIR filters using impulse invariance & bilinear transformation techniques
- 3. To design FIR filters using various window functions
- 4. To obtain knowledge and ability to use the appropriate tools like digital signal processors to build DSP systems for real time problems

Expected Course Outcome:

On the completion of this course the student will be able to:

- 1. Understand the transform- domain signal and analyze the frequency response
- 2. Analyze and design analog filters
- 3. Design and implement IIR filtering operations with the real time constraints
- 4. Design a FIR filter for specific digital signal applications.
- 5. Compose and realize the structures of digital filters.
- 6. Estimate the adaptive filters for performance improvement.
- 7. Identify the techniques, skills and modern technical tools necessary for engineering practice to design and simulate a DSP system.

8. Design and Conduct experiments, as well as analyze and interpret data

Module:1	Frequency Analysis of Signals and Systems	6 Hours			
Review of	discrete -time signals and systems - Classific	ation, Z- transform – ROC-			
stability/causality analysis, DTFT- Frequency domain sampling - DFT-Properties-Frequency analysis					
of signals using DFT-FFT Algorithm-Radix-2 FFT algorithms-Applications of FFT.					

Module:2	Theory and Design of Analog Filters	4 Hours			
Design techniques for analog low pass filter -Butterworth and Chebyshev approximations, frequency					
transformation, Properties.					
Module:3	Design of IIR Digital Filters	4 Hours			

Module:3Design of IIR Digital Filters4 HoursIIR filter design - Bilinear and Impulse Invariant Transformation techniques - Spectral transformation
of digital filters.

36 3 3 4		4 TT
Module:4	Design of FIR Digital Filters	4 Hours

FIR Filter Design - Phase and group delay - Design characteristics of FIR filters with linear phase – Frequency response of linear phase FIR filters – Design of FIR filters using Rectangular, Hamming, Hanning, Bartlett and Blackmann window functions.

Module:5	Realization of Digital Filters	4 Hours			
Direct Forms I and II, Cascade, Parallel and Lattice structures.					

Module:6	Filters for interference	removal	of	artefacts	and	4 Hours
Optimum Filter - The Wiener Filter, Adaptive filters and their applications.						



Mod	ule:7	Digital Signal Processors	2 Hours				
Gene	ral-purp	ose digital signal processors - Fixed point and floating point DSP - I					
		AC, filter operation in different DSP architectures - typical impler	_				
algor	ithms.						
Mod	ule:8	Contemporary issues:	2 Hours				
wiou	ule:0	Total Lecture hours:	2 Hours 30 Hours				
			50 110015				
Text	Book(s)						
1.		John G. Proakis, D.G. Manolakis and D.Sharma, "Digital Sig	6				
2.		Principles, Algorithms and Applications", 4th edition, Pearson Educat	10n, 2012.				
		Sanjit K. Mitra, Digital Signal Processing, 4th edition, TMH, 2013.					
Refe	rence B	ooks					
1.		Sophocles J. Orfanidis, "Introduction to Signal Processing" 2nd e	dition, Prentice				
		Hall, Inc, 2010					
2.		Oppenhiem V.A.V and Schaffer R.W, "Discrete – time Signal P.	rocessing", 3rd				
3.		edition, Pearson new international edition, 2014. Lawrence R Rabiner and Bernard Gold, "Theory and Application of D	Jigital Signal				
5.		Processing", Pearson India Education Services, 2016.	ngitai Signai				
4.		Emmanuel C. Ifeachor, "Digital Signal Processing- A Practical	Approach" 2nd				
		edition, Prentice Hall, 2011.	11				
Mode	e of Eva	luation: CAT / Assignment / Quiz / FAT / Project / Seminar					
List	of Chall	enging Experiments (Indicative)					
1.		is of continuous time and discrete time signals.	2 hours				
2.	Consid	er a symmetric square wave with frequency 100 Hz. Plot the 4-term,	2 hours				
	10-term	n and 25-term Fourier series approximations. Compare the FS					
	approxi	mations with the actual square wave. Observe the approximation					
	behavio	or at the points of discontinuity.					
3.		program to convolve two discrete time square pulse signals. Observe	2 hours				
	the effects of repeated convolution with a square pulse.						
4.							
_	-	computed with FFT.					
5.		the frequency response and impulse response of an ideal discrete-time 2 hours					
<i>.</i>	1	bass filter.					
6.	•	nalyze the effect of the following window functions on the magnitude of 2 hours					
7		frequency response: Rectangular, Hamming and Blackman.					
7.	. Generate a sinusoidal signal which contains 50Hz, 70Hz, 100Hz and 120Hz 2 ho frequencies. Analyse the frequency components present in the signal with						
	-						
	and without AWGN for a SNR of 0.6. Obtain the plot and comment on the results.						
8.		an IIR filter to filter out noise from the sinusoidal signal for the	2 hours				
0.	-	ng specifications. Plot the spectra. Comment and infer your results.					
		Type of filter: Butterworth					
		Pass band frequency: 100 Hz; Stop band frequency: 150 Hz					
	Pass band ripple: 0.1 dB; Stop band ripple: 40 dB						



	72						
Design a FIR filter and estimate	the filter coeffic	cients for	the following	2 hours			
specifications. Plot, comment and in							
Type of filter: Band stop							
Order of the filter: 10							
Pass band frequency: 200 Hz ; Stop band frequency: 300 Hz.							
Design Chebyshev Type 1 and Typ	e 2 high pass and	band pas	s analog filters	2 hours			
for the following specifications.							
Passband ripple =0.04dB;							
Stopband attenuation= 30dB							
Passband frequency = 400 Hz ; Stopband frequency = 800 Hz							
Sampling frequency = 2000Hz							
Plot their magnitude and phase characteristics.							
Signal processing methods for Must	ic Signals using D	SP Proces	ssor	2 hours			
Signal processing mechanisms for H	Bio-Signals using	DSP proc	essor	2 hours			
Total Laboratory Hours							
Mode of Evaluation: Assignment /FAT							
ommended by Board of Studies	05/03/2016						
Approved by Academic Council40 th ACDate18/03/2016							
	specifications. Plot, comment and in Type of filter: Band stop Order of the filter: 10 Pass band frequency: 200 H Design Chebyshev Type 1 and Typ for the following specifications. Passband ripple =0.04dB ; Stopband attenuation= 30dI Passband frequency = 400H Sampling frequency = 2000 Plot their magnitude and phase chan Signal processing methods for Must Signal processing methods for Must	specifications. Plot, comment and infer your results. Type of filter: Band stop Order of the filter: 10 Pass band frequency: 200 Hz ; Stop band freq Design Chebyshev Type 1 and Type 2 high pass and for the following specifications. Passband ripple =0.04dB ; Stopband attenuation= 30dB Passband frequency = 400Hz ; Stopband freq Sampling frequency = 2000Hz Plot their magnitude and phase characteristics. Signal processing methods for Music Signals using D Signal processing mechanisms for Bio-Signals using T e of Evaluation: Assignment /FAT mmended by Board of Studies 05/03/2016	specifications. Plot, comment and infer your results. Type of filter: Band stop Order of the filter: 10 Pass band frequency: 200 Hz ; Stop band frequency: 30 Design Chebyshev Type 1 and Type 2 high pass and band pass for the following specifications. Passband ripple =0.04dB ; Stopband attenuation= 30dB Passband frequency = 400Hz ; Stopband frequency = 8 Sampling frequency = 2000Hz Plot their magnitude and phase characteristics. Signal processing methods for Music Signals using DSP Processing methods for Bio-Signals using DSP processing bio-Signals using bio-Signals using bio-Signals using	Type of filter: Band stop Order of the filter: 10 Pass band frequency: 200 Hz ; Stop band frequency: 300 Hz. Design Chebyshev Type 1 and Type 2 high pass and band pass analog filters for the following specifications. Passband ripple =0.04dB ; Stopband attenuation= 30dB Passband frequency = 400Hz ; Stopband frequency = 800Hz Sampling frequency = 2000Hz Plot their magnitude and phase characteristics. Signal processing methods for Music Signals using DSP Processor Signal processing methods for Bio-Signals using DSP processor e of Evaluation: Assignment /FAT mmended by Board of Studies			



EEE3001	Control Systems	
Pre-requisite	EEE2001, MAT2002/EEE1001	3 0 2 0 4 Syllabus version
		v. 1.0
Course Obje		
	a clear exposition of the classical methods of con	
	d basic principles of frequency and time domain des	
	e practical control system design with realistic syste	
	e knowledge of state variable models and fundar	nental notions of state feedback
design		
F (10		
	urse Outcome:	
On the comple	etion of this course the student will be able to:	
1. Formulate	he mathematical model and transfer function of phy	sical systems
	e system performance by applying various input sign	•
	the stability of linear systems in time domain	
	quency domain analysis using bode and polar plot	
	stability of linear system in the frequency domain	
	pensators and controllers for the given specification	18
7. Design and	analyze state space model	
	Conduct experiments, as well as analyze and interp	ret data
Module:1	Systems and their Representations	6 hours
Basic element	s in control systems - open loop & closed loop - Tra	insfer functions of mechanical,
electrical and	analogous systems. Block diagram reduction - signation	ll flow graphs.
	Time Response Analysis	6 hours
	signals, Time response of first and second order sys	tem, Time domain specifications,
Steady state e	rror, error constants, generalized error coefficient.	
	Stability Analysis and Root Locus	6 hours
•	ncept and definition, Characteristic equation – Lo	1
criterion - Ro	ot locus techniques: construction, properties and app	lications.
	Frequency Response Analysis	6 hours
Bode plot - Po	olar plot - Correlation between frequency domain an	d time domain specifications
	Stability in Frequency Domain	6 hours
	lity, Gain margin, Phase margin, stability analysis u	sing frequency response
methods, Nyq	uist stability criterion.	
Madula (Comparator and Controllar	7 hours
	Compensator and Controller	domain and fractionary domain
	basic compensators, cascade compensation in time pensation - Design of lag, lead, lag-lead series comp	
	ntrollers in frequency domain.	bensator (using bode prot), P,
		6 hours
	State Space Analysis	
	state variable and state model, Solution of state of a state of the st	
	ersion, Controllability, Observability, Pole placeme	
R TECH (FIF)		Dage 74



Moo	dule:8 Contemporary issues:	2 hours			
		45 hours			
	Total Lecture hours	:			
	t Book(s)	41-			
	Norman S. Nise, "Control System Engineering", John W	Viley & Sons, 6 th Edition, 2011.			
2.	Benjamin C Kuo "Automatic Control System" John Wild	ey & Sons, 8 th Edition, 2007.			
	erence Books				
1.	K. Ogata, "Modern Control Engineering", Pearson, 5 th E				
2.	R.C. Dorf & R.H. Bishop, "Modern Control Systems", P	earson Education, 11 th Edition, 2008.			
3.	M. Gopal, "Control Systems-Principles And Design", Ta	ta McGraw Hill –4 th Edition, 2012.			
4.	Graham C. Goodwin, Stefan F. Graebe, Mario E. Sagado Hall, 2003'	o, "Control System Design", Prentice			
5.	J.Nagrath and M.Gopal," Control System Engineering", 4 th Edition, 2006.	New Age International Publishers,			
Mod	de of Evaluation: CAT / Assignment / Quiz / FAT / Projec	ct / Seminar			
List	of Challenging Experiments (Indicative)				
1.	Block Diagram Reduction	2 hours			
2.	Determination of Time Domain Specifications	2 hours			
3.	Stability analysis of linear systems	2 hours			
4.	PID Controller Design using Bode Plot	2 hours			
5.	PID Controller Design using Root Locus	2 hours			
6.	Compensator Design in Frequency and Time Domains	2 hours			
7.	Transfer Function to State Space Conversion with Contr Observability Tests	rollability and 2 hours			
8.	Lag compensator design for linear servo motor for speed application	d control 2 hours			
9. Pole placement controller design for inverted pendulum 2 hours					
10.PD controller design for position control of servo plant2 hours					
11.	2 hours				
12.	2 hours				
13.	2 hours				
14.	2 hours				
15.	Study of First and Second order systems	2 hours			
		al Laboratory Hours 30 hours			
	le of evaluation: CAM/ FAT				
	ommended by Board of Studies 30/11/2015				
App	proved by Academic Council 39th AC Da	te 17/12/2015			



EEE3002	EEE3002Analog and Digital CircuitsLTPJ					C	
			3		2 0		
Pre-requisite	EEE2002		Sylla	abu		rsion	
Anti-requisite	NIL					v.2.0	
Course Objecti							
	he functional building blocks, characteristics and ap	-	0	ICs			
	l different methods for design and implementation of	f Digital circu	its				
3. To introduce	he various applications of digital and analog ICs						
Expected Cour	se Outcome:						
	on of this course the student will be able to:						
-	erformance characteristics of Op-Amp.						
• •	np based circuits for engineering applications.						
	ower supply requirements for electronic circuit appli	cations					
	c logic circuit for arithmetic operations in computers						
-	ex digital circuits for real time applications.						
	ers for memory applications in computers.						
	/digital ICs for industrial control applications.						
	onduct experiments, as well as analyze and interpret	data.					
	perational Amplifier					lours	
	e - The operational amplifier, Input resistance, Outpu		-				
	currents, Offset voltage, Common mode rejection ra	-			-		
	n, Differential amplifier.AC Performance - Frequen	ncy response,	Transie	ent	respo	onse,	
Stability, Compo	ensation, Poles and zeros cancelation						
	A 10 /0				7 11	r	
	pamp Applications	1. C.	1.			lours	
	ons of op-amp – summing, subtracting, averagi						
	ent to voltage converter, differentiator and integ	-	-	-			
· ·	ltivibrators, Schmitt Triggers, Precision Diode, Ha	all wave and	iun wa	ve i	recu.	ners,	
reak detector, w	Vave form generators and Active Filters.						
Module:3 T	mer And Power Supplies				5 H	ours	
	its applications, monostable multivibrator, Astab			near	i vo	ltage	
regulator, 78XX	and 79XX family, 723 IC voltage regulator, Switch	ing regulators	•				
	igital Techniques					ours	
•	s - Binary, octal and hexadecimal numbers. Bina	•	0	,			
•	rsion and operations. De Morgan's laws, Truth tal	-	gh's ma	p, N	/in 1	term,	
Max term, SOP,	Max term, SOP, POS, Synthesis of Boolean functions, Quine Mccluskey method.						
					(11	r .	
	ombinational Circuit Design		Decla	D		lours	
	uits, Parity generator, Seven-segment display, A	•	Design	Pro	cedu	ure -	
	coder, Encoder, Design using programmable logic D	vevices.			(11	r	
Module:6 Sy	nchronous Sequential Circuit Design				0 H	ours	



Flip Flops - SR, D, T and JK Flip-flops, Master slave Flip Flops, Counters, Registers. Design using State machines-Moore and Mealy machines, Design Examples.

Module:7	Asynchronous Sequential Circuit Design	6 Hours						
Design Procedure- Asynchronous Sequential Circuits-State Diagram-State assignment-implication								
table-Design	table-Design examples. Applications: Temperature Indicator and Controller, Speed control of DC							
Motor using	Motor using Analog/Digital ICs							

Module:8		Contemporary issues:		2 Hours
		Total Lecture hours:		45 Hours
	Book(s			
1.		Op-Amps & Linear Integrated Circuits by Rama India, New Delhi, 4th edition, 2002.		
2.		Digital Design by M. Morris Mano and Mictae Edition, 2013.	l Ciletti, Pearson	Education, 5 th
Refe	rence B			
1.		Operation Amplifiers & Linear Integrated Circuits F. Driscoll, Prentice Hall of India, New Delhi, 6 th E	• •	hlin and Frederick
2.		Design with Operational Amplifiers & Analog Ir Tata McGraw Hill Education, 4 rd Edition, 2015.		oy Sergio Franco,
3.		Digital Fundamentals by Floyd, Madrid Pearson Ed	lucation, 11 th Editio	on, 2016.
4.		Digital System Design using Verilog by Charles R Cengage Learning, 1 st Edition, 2016.	oth, Lizy John and	l Byeong Kil Lee,
5.		Electronic Principles by Albert Malvino, David.J. 8 th Edition, 2016.	Bates, Tata Mcgra	w Hill Education,
Mod	e of Eva	luation: CAT / Assignment / Quiz / FAT / Project / S	Seminar	
List	of Chal	lenging Experiments (Indicative)		
1.	Design	and implementation of inverting and non-inverting a	mplifier	2 hours
2.	Design	and implementation of precision rectifier using op-a	mp	2 hours
3.	Design	and implementation of low pass and high pass filter		2 hours
4.	Design	of implementation of integrator and differentiator us	ing op-amp	2 hours
5.	Design	and implementation of triangular wave generator using	ing op-amp	2 hours
6.	-	and implementation of summing and difference amp	olifier	2 hours
7.	Design	and implementation of astable multivibrator		2 hours
8.	Design	and implementation of half and full adder circuit		2 hours
9.	Design	and implementation of multiplexer		2 hours
10.	Design	and implementation of magnitude comparator		2 hours
11.	Design	and implementation of BCD to 7 segment display		2 hours
12.	Design	and implementation of code converters		2 hours
13.	Design	and implementation of J,K and D flip flops		2 hours
14.	Design	and implementation of shift registers		2 hours
15.	Design	and implementation of synchronous decade counter		2 hours
		Total L	aboratory Hours	30 hours



Mode of Evaluation: Assignment /FAT			
Recommended by Board of Studies	05/03/2016		
Approved by Academic Council	40 th AC	Date	18/03/2016



EEE4001 Microprocessor and Microcontroller L I T P J C 2 0 3<	[(Deemed to be University under section 3 of UGC Act, 1956)			_	
Pre-requisite EEE3002 Syllabus version Anti-requisite NL v. 2.0 Course Objectives: .1 v. 2.0 1. To emphasis on the hardware functionality of Intel 8051 and ARM .2 v. 2.0 2. To create the essential knowledge on operating modes of I/O ports ,Timers/Counters, control registers and various types of interrupts. .2 3. To analyse various interfacing techniques. Expected Course Outcome:	EEE4001		Microprocessor and Microcontroller	L	T	P J	(C
Anti-requisite NIL v. 2.0 Course Objectives: . v. 2.0 1. To emphasis on the hardware functionality of Intel 8051 and ARM . v. 2.0 2. To create the essential knowledge on operating modes of I/O ports ,Timers/Counters, control registers and various types of interrupts. . . 3. To analyse various interfacing techniques. . . . Expected Course Outcome: On the completion of this course the student will be able to: 1. Interpret the architecture of microprocessor and classify the different modes of ARM . <th></th> <th></th> <th></th> <th>2</th> <th>0</th> <th>2</th> <th>) 3</th>				2	0	2) 3
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	Programmin	g I/O p	oorts - Different modes of timer programs – Counters – Trans		lata		
				onty		7 H	ours



Interfacing of Analog to Digital Converter – Digital to Analog Converter – Sensor Interface – Keypad Interface.Display Interface: 7 segment interface – LCD.Communication Interface: GSM – Xbee – GPS – Bluetooth.

Moo	dule:8	Cont	temporar	y issues	:				2 Hours
					Tota	l Lecture hours	5:		30 Hours
Tex	t Book(s)							
1.		Desig			-	-	-		eveloper's Guide: n Publishers, 1 st
2.						e Gillispie Maz ducation, 2 nd Ed		1 Mic	crocontroller and
Refe	erence B								
1.		Kenne	eth J.Ayla	i, "The 8	051 Mici	ro controller", Tl	nomson learning	$g, 3^{rd} E$	Edition, 2010.
2.						er 8051, Oxf			
3.		P.V G	uruprasa	d, "Arm	Architec	ture System on (Chip and More "	, Apre	ess, 2013.
Mod	le of Eva	luation	: CAT / A	Assignme	ent / Quiz	z / FAT / Project	/ Seminar		
List	of Chal	lenging	g Experin	nents (Ir	ndicative				
1.	to perfe	orm the	arithmeti	ic operat	ions				2 hours
2.	Write a	n progra	m to solv	e the giv	en equat	ion.			2 hours
			+ A2B +	-	-				
	Assum	e : A, B	& C are	8 bit nui	nbers.				
3.	Write a	n progra	m to perf	form the	following	g data transfer			2 hours
		a. RA	M to RA	М					
		b. RO	M to RA	М					
		c. EX	TERNAI	to EXT	ERNAL				
		d. RA	M to EX	TERNA					
4.	to solv	e the fo	llowing E	Boolean e	expressio	n			2 hours
5.			im to perf						2 hours
	-	ption	0	1	2	3	9	7	
		ask	A + B	∼ B +1	A*B	$AB + \sim A \sim B$	~A +1	-	
	C	ption	4	5	6	7	8	-	
		ask	A A to	55H	A ^ B	~A	~B	-	
			P1	to P1					
6.	Write a	a progra	im to gene		followin	g wave forms.	1		2 hours
	a.		-			0.0. use Timer 1	in mode 1. As	sume	
	XTAL			•					
	b.		te step w	ave form	n on P0.				
7.			-			n 8051 microcor	ntroller also gen	erate	2 hours
			ing LED'				0		
8.) Hz sau	are wave on P	1.1 normally. W	When	2 hours
						wave on P1.1.			
		-	$\Gamma AL = 11$		-				
	1								1



9.	Write a program to display the fol	nt display.	2 hours				
10.	on.	2hours					
	Total Laboratory Hours						
Mode of Evaluation: Assignment / FAT							
	Recommended by Board of Studies 05/03/2016						
Reco	ommended by Board of Studies	05/03/2016					



		(Deemed to be University under section 3 of UGC Act, 1956)				
EEE4021		Sensors and Signal Conditioning		L	ГР.	JC
				3 () 2 (0 4
Pre-requisite		PHY 1001, EEE3002	e e e e e e e e e e e e e e e e e e e	Syllab	us ver	sion
Anti-requisit	e	NIL			V	<i>v</i> . 1.0
Course Obje	ctives:					
0		tanding of the general concepts and terminology of measu	rement	systen	is and	l
transducer cla						
		basics of various sensors and transducers and their constru-	ction.			
	-	rinciple of operation and function of sensors.				
		gn of signal conditioning circuits.				
Expected Con						
-		of this course the student will be able to:				
1. Promote the	e conc	epts of transducers, standards and calibration.				
2. Analyse v	arious	types of resistive sensors.				
		riation sensors in real time industrial environments.				
4. Interpret the	e conc	epts of signal conditioning circuits for resistive sensors.				
5. Illustrate th	ne wor	king principle of signal conditioning for reactance variation	on sense	ors		
		generating Sensors and its signal conditioning circuits				
		pes of Electromagnetic ,Optical and Digital Sensors				
8. Design and	Cond	uct experiments, as well as analyze and interpret data				
			[]			
Module:1						ours
		ral concepts and terminology of measurement systems, Tr				
-	-	it configuration, Static and dynamic characteristics of a			-	
		idards. Errors and statistical analysis in measurement sys	tems, le	east sq	uare 1	it of
<u> </u>		measurement systems.			5 11	
			uromon	+ Diaz		ours
		uction - Beam, column and Ring type force, torque meas mistor- models-types and applications-linearization, M				
dependent res		mistor- moders-types and appreadons-meanzation, w	lagiicio	105150	J15, 1	Jigin
· ·		ance Variation Sensors			4 H	ours
		variable-differential, Inductive sensors- variable reluctan	ce-eddy	v curre		
-		inductosyn- magnetoelastic- magnetostrictive				
-		l conditioning for resistive sensors			5 H	ours
	<u> </u>	amplifiers for voltage dividers, Wheatstone bridge-	balance	meas		
deflection me	asurer	nents- sensitivity, linearity, and analog linearization of a	resistive	e senso	or brid	lges,
Differential an	nd Inst	rumentation amplifiers. Grounding and Isolation				
Module:5	Signa	l conditioning for reactance variation sensors			5 H	ours
		tion Amplifier based inductance and capacitance mea	asuring	circui	ts, ca	ırrier
		rent detection, signal conditioners for capacitive sensors.				
	-	enerating Sensors and its signal conditioning				ours
-	-	ezoelectric sensors-effect-materials-applications, pyroele				
	-	ons, and electrochemical sensors. Signal conditioning circ				
		ctrometer and trans impedance amplifiers, charge amplifie	rs, nois	e in an		
		comagnetic ,Optical and Digital Sensors				ours
Electromagne	tic sen	sors- sensors based on Faraday's law-Hall effect sensor, U	Jltrason	1c base	d sen	sors,
B TECH (FIF)			-	Page 8	2	



Optical transducer, Photo emissive cells, Photoconductive cells, Photo diodes, Photo transistors, Photovoltaic cells – Measurement of physical quantities. Position encoders-absolute position encoder-incremental position encoder, Resonant sensors- sensors based on quartz resonators- digital quartz thermometer- quartz micro balance-quartz resonators for force and pressure sensing- quartz angular rate sensor, SAW sensors.

Modu	le:8	Contemporary issues:	2 Hours				
		Total Lecture hours:	45 Hours				
Text B	Book(s)					
1.		on Pallas-Areny, John G.Webster, "Sensors and S Ltd., NewDelhi, 2nd Edition 2013.	ignal Conditioning", Wiley India				
2.		.S.Murthy, "Transducers and Instrumentation", Prent	ice Hall of India Learning Pvt. Ltd.				
		edition 2012.					
Refere	ence B	ooks					
1.	Doe 2004	belin E.O., "Measurement System Application and I 4.	Design", McGraw Hill, 5th Edition				
2.	Patr	ranabis, "Sensors and Transducers", Prentice Hall of India, New Delhi, 2003.					
3.		.Shawney, "A course in Electrical and Electronic r npat Rai &Company, 18th Edition, 2010.	neasurement and Instrumentation",				
4.	Johr	n P. Bentley, "Principles of Measurement Systems", 31 gman Ltd, UK 2000	d edition Addison Wesley				
5.	Jaco	bb Fraden, "Handbook of Modern Sensors: Physics, D ence + Business Media, Inc, 3rd Edition, 2004.	esigns, and Application", Springer				
Mode		luation: CAT / Assignment / Quiz / FAT / Project / Se	eminar				
List of	Chal	lenging Experiments (Indicative)	Hours				
1.	S	train gauge based torque measurement					
2.	Т	emperature Measurement using RTD					
3.	Т	emperature Measurement using Thermistor					
4.	Т	emperature Measurement using J and K type Thermoo	couples				
5.	D	Displacement Measurement using LVDT					
6.	S	peed measurement using magnetic sensor					
7.	D	Displacement Measurement using Inductive Pickup					
8.	Р	ressure Measurement using Diaphragm pressure gauge	e				
9.	V	elocity measurement using Piezo-electric Transducer					
10.	A	cceleration measurement using Piezo-electric Transdu	icer				
11.		Design a signal conditioning circuit for thermocompensation using K-type thermocouple and analyse i	1 5				
12.		Design the linearization circuit for the $5K\Omega$ thermistor					
13.		Design the signal conditioning circuit using RTD PT10 $0 ^{\circ}$ C to 100 $^{\circ}$ C to get an output voltage of 0 to 4 V					



	Power dissipation = 30 mW	and test its perf	ormance.			
14.	Design signal conditioning temperature effects.	circuit for stra	in gauge sensor	to compensate		
15.	5. Design the signal conditioning circuit for the pressure cell using Piezo electric sensor having the sensitivity of 10mV/g.					
		Т	otal Laboratory	Hour		
Mode of	f Evaluation: Assignment /FAT					
Recomm	nended by Board of Studies	25/10/2017				
Approve	ed by Academic Council	37 th AC	Date	05/10/2017		



		(Deemed to be University under section 3 of UGC Ac			
EEE4031		Electrical and Electronic Instr	umentation	L	T P J
				3	0 2 0
Pre-requisit		EEE2002, EEE4021		Sylla	abus versi
Anti-requisi	ite	NIL			v. 1
Course Obj	ectives:				
1		inderstanding of electrical and electronic m	•		
2. To give a	thoroug	h knowledge of varieties of measuring instr	uments, its operatir	ng princ	ciples, and
limitations.					
3. To provid	e basic u	inderstanding of data acquisition systems an	nd virtual instrume	ntation	
Expected Co					
On the comp	oletion of	f this course the student will be able to:			
		concepts and working principle of electrical	-	ing met	ers.
•		t meters for measuring electrical parameter			
-		DC bridges to measure resistance, capacita		e	
0 1		neter to measure the unknown voltage and	resistance.		
U		or in audio and radio frequency range.			
		in both time and frequency domain.			
		pes of ADC and DAC circuits.			
8. Design an	d Condu	ict experiments, as well as analyze and inter	rpret data		
Module:1		ical Measurements - I			8 Hou
		ils, moving iron, dynamometer type, rect			
		: Hall effect Wattmeter, Thermal type watt	meter, Compensate	ed wattr	neter, Sing
		er measurement.	1		
Module:2		ical Measurements - II		<u> </u>	6 Hou
		t: energy meter - Magnetic measurement	s: Ballistic tests -	Maxim	num demai
	meter - I	High voltage measurements.			
Module:3	DCA	<u> </u>			
		AC Bridges		· D · I	6 Hou
Series and S	hunt typ	AC Bridges e ohmmeter – Megger - DC Bridges: Whea			lge - AC
Series and S Bridges: Ma	hunt typ xwell Bi	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut			lge - AC Q meter.
Series and S Bridges: Ma Module:4	hunt typ xwell Bi Poten t	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers	ty, and Schering Br	idges –	lge - AC Q meter. 5 Hou
Series and S Bridges: Ma Module:4 Transformer	hunt typ xwell Br Poten t ratio B	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement	ty, and Schering Br	idges –	lge - AC Q meter. 5 Hou
Series and S Bridges: Ma Module:4 Transformer and AC Pote	hunt typ xwell Bi Potent ratio B entiomet	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a	ty, and Schering Br	idges –	lge - AC Q meter. 5 Hou ections - D
Series and S Bridges: Ma Module:4 Transformer and AC Pote Module:5	hunt typ xwell Br Potent ratio B entiomet Electr	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements	ty, and Schering Br s - Wagner Groun applications.	idges – d conne	lge - AC Q meter. 5 Hou ections - D 6 Hou
Series and S Bridges: Mat Module:4 Transformer and AC Pote Module:5 Solid State r	hunt typ xwell Bi ratio B entiometo Electr measure	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Volti	idges – d conne meter ci	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol
Series and S Bridges: Ma Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-1	hunt typ xwell Bi ratio B entiomete Electr measuren meter, D	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Volti	idges – d conne meter ci	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol
Series and S Bridges: Mat Module:4 Transformer and AC Pote Module:5 Solid State r	hunt typ xwell Bi ratio B entiomete Electr measuren meter, D	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Volti	idges – d conne meter ci	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol
Series and S Bridges: Mat Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-r generators, F	hunt typ xwell Bi ratio B entiomete Electr neasures meter, D Function	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat generator.	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Volti	idges – d conne meter ci	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol uency sign
Series and S Bridges: Ma Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-r generators, F Module:6	hunt typ xwell Bi ratio B entiomete Electr measuren meter, D Function	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat generator.	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Voltr ion: Audio and Rac	idges – d conne meter ci dio freq	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol uency sign 5 Hou
Series and S Bridges: Mat Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-r generators, F Module:6 Wave analyz	hunt typ xwell Bi ratio B ratio B entiomete Bentiomete measures meter, D Function Signal zer - Spe	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat generator. Analyzers ctrum analyzer - Frequency Measurement -	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Voltr ion: Audio and Rac	idges – d conne meter ci dio freq	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol uency sign 5 Hou
Series and S Bridges: Ma Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-r generators, F Module:6	hunt typ xwell Bi ratio B ratio B entiomete Bentiomete measures meter, D Function Signal zer - Spe	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat generator. Analyzers ctrum analyzer - Frequency Measurement -	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Voltr ion: Audio and Rac	idges – d conne meter ci dio freq	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol uency sign 5 Hou
Series and S Bridges: Mat Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-r generators, F Module:6 Wave analyz Phase angle	hunt typ xwell Bi ratio B entiomete Electr measure meter, D Function Signal zer - Spe measure	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat generator. Analyzers ctrum analyzer - Frequency Measurement - ment.	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Voltr ion: Audio and Rac	idges – d conne meter ci dio freq	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol uency sign 5 Hou nd time -
Series and S Bridges: Mat Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-r generators, F Module:6 Wave analyz Phase angle	hunt typ xwell Bi ratio B entiomete Electr measure meter, D Function Signal zer - Spe measure	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a rigital Multi-meter – DSO - Signal Generat generator. Analyzers ctrum analyzer - Frequency Measurement - ment.	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Voltri ion: Audio and Rac	idges – d conne meter ci dio freq eriod an	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol uency sign 5 Hou nd time - 7 Hou
Series and S Bridges: Ma Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-r generators, F Module:6 Wave analyz Phase angle Module:7 A/D convert	hunt typ xwell Bi ratio B entiometa Electr measure meter, D Function Signal zer - Spe measure Mathematic Data A ers: Typ	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat generator. Analyzers ctrum analyzer - Frequency Measurement - ment. Acquisition & LABVIEW pes, resolution, dynamic range, accuracy, sa	ty, and Schering Br s - Wagner Ground applications. nd MOSFET Voltrion: Audio and Rac - Measurement of p ampling concepts a	idges – d conne meter ci dio freq eriod an	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol uency sign 5 Hou nd time - 7 Hou miques, A
Series and S Bridges: Ma Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-r generators, F Module:6 Wave analyz Phase angle Module:7 A/D convert boards - D/A	hunt typ xwell Bi ratio B entiomete Electr measure meter, D Function Signal zer - Spe measure Measure Measure	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat generator. Analyzers ctrum analyzer - Frequency Measurement - ment. Acquisition & LABVIEW bes, resolution, dynamic range, accuracy, sa ters: Types, D/A boards - Digital I/O board	ty, and Schering Br	idges – d conne meter ci dio freq eriod an eriod an and tech	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol uency sigr 5 Hou nd time - 7 Hou miques, A wards. Virtu
Series and S Bridges: Mat Module:4 Transformer and AC Pote Module:5 Solid State r State Multi-r generators, F Module:6 Wave analyz Phase angle t Module:7 A/D convert boards - D/A	hunt typ xwell Bi ratio B ratio B entiomete Electr measure meter, D Function Signal cer - Spe measure Measure Data A ers: Typ A conver	AC Bridges e ohmmeter – Megger - DC Bridges: Whea ridge, Wien Bridge, Anderson, Hay, Desaut tiometers ridges - Detectors in Bridge measurement ers: Various types, Working Principle and a onic Measurements ment Design and Instruments: BJT, FET a igital Multi-meter – DSO - Signal Generat generator. Analyzers ctrum analyzer - Frequency Measurement - ment. Acquisition & LABVIEW pes, resolution, dynamic range, accuracy, sa	ty, and Schering Br s - Wagner Groun applications. nd MOSFET Voltr ion: Audio and Rac Measurement of p Measurement of p ampling concepts a ds - Counter/Timer - LOOP Behavio	idges – d conne meter ci dio freq eriod an eriod an and tech : I/O bo our and	lge - AC Q meter. 5 Hou ections - D 6 Hou ircuits, Sol uency sign 5 Hou nd time - 7 Hou miques, A pards. Virtu

LabVIEW.



N/ - J10	C				3 II
Module:8	Contemporary issues:				2 Hours
		Total Lecture hou	irs:		45 Hours
Text Book	a(s)				
1.	David A. Bell, "Electronic Ir	strumentation and	Measure	ments", 3 rd Ed	ition, Oxford
	university press, New Delhi,				
2.	Cooper W.D and Helfrid				
	Measurement Techniques", 4	^{1^m} Edition, Pearson	n India Ec	lucation, 2015	
Reference					
1.	H.S. Kalsi, "Electronic Instru	umentation", 3 rd Ec	lition, Mo	c-Graw Hill ed	ucation, 2015.
2.	A.K. Sawhney, "A Cour	se In Electrical	And E	lectronic Me	asurements And
	Instrumentation", Dhanpat R				
3.	Jovitha Jerome, "Virtual Inst	rumentation using	LABVIE	W", Prentice I	Hall India, 2013.
Mode of E	valuation: CAT / Assignment / C	Quiz / FAT / Proiec	ct / Semir	ar	
	periments (Indicative)	- 5			
	gn a bridge circuit to measure a i	resistance in low an	nd mediu	m range.	2 hours
	gn a circuit to measure high valu				2 hours
	e meters.		8	8	
0	gn of inductance measurement b	ridge circuit.			2 hours
	gn of capacitance measurement l	0			2 hours
5. Desi	gn a circuit for calibrating the given the given a circuit for calibrating the given a circuit for calibrating the given a circuit for the calibrating	ven single phase er	nergy me	ter at unity	2 hours
powe	er factor.	• •			
6. Desi	gn a circuit for Calibrating the si	ngle phase electro	dynamor	neter type	2 hours
	neter with direct loading.				
	gn a circuit for Calibrating the gi		ammeter		2 hours
	surement of insulation resistance	0 00			2 hours
	a VI to acquire and process a re				2 hours
	lop a VI to check the amplitude	U	l for a pr	e-set value	2 hours
	ctivate the alarm if it exceeds th				
	elop a VI to read the LVDT outp	ut voltage using US	SB 6221a	and plot the	2 hours
respo			1	• 1	2.1
	elop a VI diagram to calculate the				2 hours
	a VI that reverses the order of a	in array that contai	ns 100 ra	nuom	2 hours
num		de in acce structure	malatta		2 hours
	l a VI diagram using formula no lop a VI to check the amplitude				2 hours 2 hours
	ctivate the alarm if it exceeds th		u ioi a pr	c-set value	2 110u15
			tal I aha	ratory Hours	30 hours
Mode of F	valuation: Assignment / FAT	10			
	nded by Board of Studies	05/03/2016			
кесонне	lucu by Dualu of Studies	US/US/2010			



	Process Automation and Control	L	Т	P J	C
		3	0	2 0	4
Pre-requisite	EEE3001, EEE4021	Sylla	bus	ver	sion
Anti-requisite	NIL			V	1.0
Course Objective	5:				
2. Prepare the least	rner to have successful career in process industries and motivate	e for higl	her s	studi	es.
3. Provide strong	foundation to solve control and instrumentation problems in	continuo	ous	or b	atch
problems.					
*	lge on advanced control strategies and industrial network protoc	cols.			
Expected Course					
-	of this course the student will be able to:				
-	athematical model of a process.				
U	PID controllers.				
	ecessary final control element for a given application.				
	strategy for a process involving multiple variables and constrain	ts.			
U	igure various subsystems for industrial automation.	ntomoti	on ti	- a1-a	
_	rchitecture and configure DCS to handle local and distributed a oper industrial network protocol for the given multilayer autom			ISKS	
-	nduct experiments, as well as analyze and interpret data	ation tas	SK.		
0. Design and Co.	induct experiments, as well as analyze and interpret data				
Module:1 Proc	ess Dynamics:			8 Ho	ours
Need for process c	ontrol – Mathematical model of Processes – Interacting and non	n-interac	ting	syst	ems
- Degrees of free	dom - Continuous and batch processes - Self regulation - S	ervo an	d re	gula	tory
operations - Lump	ed and Distributed parameter models.				
	trol Actions & Tuning:			8 Ho	ours
Characteristic of	on-off, proportional, integral and derivative controllers – P+				
control modes –	Electronic PID controller - Selection of control modes fo	r differ	ent	proc	ess.
control modes – Evaluation criteria	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¹ / ₄ decay ratio - Tuning:- Process rea	r differ ction cu	ent rve	proc met	ess. nod,
control modes – Evaluation criteria Continuous cycling	Electronic PID controller - Selection of control modes fo	r differ ction cu	ent rve	proc met	ess. nod,
control modes – Evaluation criteria Continuous cycling PID Controller.	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process rea g method and Damped oscillation Method. Direct Digital Contr	r differ ction cu	ent rve ital	proc met form	ess. nod, s of
control modes – Evaluation criteria Continuous cycling PID Controller. Module:3 Fina	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process rea g method and Damped oscillation Method. Direct Digital Contr I Control Elements:	r differ ction cu ol - Dig	ent rve ital	proc met form 5 H o	ess. nod, s of ours
control modes–Evaluation criteriaContinuous cyclingPID Controller.Module:3I/P converterPIn	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process rea g method and Damped oscillation Method. Direct Digital Contro I Control Elements: eumatic and electric actuators – Valve Positioner – Control Va	r differ ction cu ol - Dig lves – C	ent rve ital	proc met form 5 Ho	ess. nod, s of ours istic
control modes – Evaluation criteria Continuous cycling PID Controller. Module:3 Fina I/P converter – Pro of Control Valves	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process rea g method and Damped oscillation Method. Direct Digital Control I Control Elements: eumatic and electric actuators – Valve Positioner – Control Va - Inherent and Installed characteristics – Classification of cor	r different ction cu ol - Dig lves – C	ent rve ital ^t hara ves	proc met form 5 Ho acter – gl	ess. nod, s of ours istic
control modes – Evaluation criteria Continuous cycling PID Controller. Module:3 Fina I/P converter – Pno of Control Valves: butterfly, diaphrag	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process rea g method and Damped oscillation Method. Direct Digital Contro I Control Elements: eumatic and electric actuators – Valve Positioner – Control Va - Inherent and Installed characteristics – Classification of cor m, ball valves – Valve body – Commercial valve bodies – Co	r different ction cu ol - Dig lves – C	ent rve ital ^t hara ves	proc met form 5 Ho acter – gl	ess. nod, s of ours istic obe,
control modes – Evaluation criteria Continuous cycling PID Controller. Module:3 Fina I/P converter – Pno of Control Valves: butterfly, diaphrag	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process rea g method and Damped oscillation Method. Direct Digital Control I Control Elements: eumatic and electric actuators – Valve Positioner – Control Va - Inherent and Installed characteristics – Classification of cor	r different ction cu ol - Dig lves – C	ent rve ital hara ves alve	proc met form 5 Ho acter – gl sizin	ess. nod, s of ours istic obe, ng –
control modes–Evaluation criteriaContinuous cyclingPID Controller.Module:3FinaI/P converter – Pnaof Control ∨alvesbutterfly, diaphragCavitation and flasModule:4Proce	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process rea g method and Damped oscillation Method. Direct Digital Control I Control Elements: eumatic and electric actuators – Valve Positioner – Control Va - Inherent and Installed characteristics – Classification of con- m, ball valves – Valve body – Commercial valve bodies – Co- hing – Selection criteria. eess Control Strategies:	r differ ction cu ol - Dig lves – C ntrol val ontrol va	ent rve ital hara ves alve	proc met form 5 Ho acter – gl sizin 6 Ho	ess. nod, s of ours istic obe, ng –
control modesEvaluation criteriaContinuous cyclingPID Controller.Module:3FinaI/P converterof Control Valvesbutterfly, diaphragCavitation and flasModule:4ProcFeed-forward control	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process rea g method and Damped oscillation Method. Direct Digital Contro I Control Elements: eumatic and electric actuators – Valve Positioner – Control Va - Inherent and Installed characteristics – Classification of cor m, ball valves – Valve body – Commercial valve bodies – Co hing – Selection criteria. erss Control Strategies: rol – Ratio control – Cascade control – Inferential control	r differencion cu ol - Dig lves – C ntrol valiontrol va l – Spli	ent rve ital Chara ves alve it-ra	proc met form 5 Ho acter – gl sizin 6 Ho nge	bess. nod, s of ours istic obe, ng – ours and
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control modes – Evaluation criteria Continuous cycling PID Controller. Module:3 Fina I/P converter – Pno of Control Valves butterfly, diaphrag Cavitation and flas Module:4 Proc Feed-forward cont introduction to mu	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process rea g method and Damped oscillation Method. Direct Digital Contro I Control Elements: eumatic and electric actuators – Valve Positioner – Control Va - Inherent and Installed characteristics – Classification of cor m, ball valves – Valve body – Commercial valve bodies – Co hing – Selection criteria. erss Control Strategies: rol – Ratio control – Cascade control – Inferential control	r differencion cu ol - Dig lves – C ntrol val ontrol va l – Spli nd boile	ent rve ital 'hara ves hlve it-ra er sy	proc met form 5 Ho acter - gl sizin 6 Ho nge	eess. nod, s of ours istic obe, ng – ours and ns –
control modes – Evaluation criteria Continuous cycling PID Controller. Module:3 Fina I/P converter – Pno of Control Valves butterfly, diaphrag Cavitation and flas Module:4 Proc Feed-forward cont introduction to mu	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process real g method and Damped oscillation Method. Direct Digital Contro I Control Elements: eumatic and electric actuators – Valve Positioner – Control Val - Inherent and Installed characteristics – Classification of con- m, ball valves – Valve body – Commercial valve bodies – Co- hing – Selection criteria. ess Control Strategies: rol – Ratio control – Cascade control – Inferential control ultivariable control – Case studies from distillation column a	r differencion cu ol - Dig lves – C ntrol val ontrol va l – Spli nd boile	ent rve ital 'hara ves hlve it-ra er sy	proc met form 5 Ho acter - gl sizin 6 Ho nge	eess. nod, s of ours istic obe, ng – ours and ns –
control modes – Evaluation criteria Continuous cycling PID Controller. Module:3 Fina I/P converter – Pno of Control Valves: butterfly, diaphrag Cavitation and flas Module:4 Proc Feed-forward cont introduction to mu IMC– Model Pred Algorithm.	Electronic PID controller – Selection of control modes fo – IAE, ISE, ITAE and ¼ decay ratio - Tuning:- Process real g method and Damped oscillation Method. Direct Digital Contro I Control Elements: eumatic and electric actuators – Valve Positioner – Control Val - Inherent and Installed characteristics – Classification of con- m, ball valves – Valve body – Commercial valve bodies – Co- hing – Selection criteria. ess Control Strategies: rol – Ratio control – Cascade control – Inferential control ultivariable control – Case studies from distillation column a	r differencion cu ol - Dig lves – C ntrol val ontrol va l – Spli nd boile	ent rve ital Chara ves alve it-ra er sy ith I	proc met form 5 Ho acter - gl sizin 6 Ho nge	eess. nod, s of ours istic obe, ng – ours and ns – ctor
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Programmable Logic Controller (PLC): Ladder Logic Programming, Remote Terminal Unit (RTU). Distributed Control System (DCS): detail engineering, specifications, configuration and programming - Performance Criteria for DCS and other automation tools.

Module:7Instrumentation Standard Protocols:7 HoursHART Protocol introduction, frame structure, programming, implementation examples, Benefits,
Advantages and Limitations. Foundation Fieldbus H1, introduction, structure, programming, FDS
configuration, implementation examples, Benefits, Advantages and Limitations. Other Industrial
networking protocols MODBUS - Device net – Profibus (Process Field Bus) – Controlnet – CAN -
Industrial Ethernet.

Mod	lule:8	Contemporary issues:	2 Hours
		Total Lecture hours:	45 Hours
Text	Book(s)	
1.	Step	hanopoulos, G., 'Chemical Process Control - An In	troduction to Theory and Practice',
	Pear	son India Education Services, 2015.	
2.	Terr	y L. M. Bartelt, 'Industrial Automated Systems: In	strumentation and Motion Control',
	Cen	gage Learning, 2011.	
3.	Fran	k D. Petruzella, 'Programmable logic controllers', M	IcGraw Hill Education, 3rd Edition,
	2010).	
Refe	rence B		
1.		org, D.E., Edgar, T.F. and Mellichamp, D.A., 'Proc	cess Dynamics and Control', Wiley
		and Sons, 3 rd Edition, 2010.	
2.		ghanowr, D.R., 'Process Systems Analysis and Co	ntrol", McGraw -Hill International
		ion, 2009.	
3.	Beq	uette, B.W., 'Process Control Modeling, Design and S	Simulation', Prentice Hall, 2010.
4.	Curt	is D. Johnson, 'Process Control Instrumentation	Technology', 8th Edition, 2006.
		don: Pearson, 2014.	
5.		rt A. Boyer, SCADA: 'Supervisory control and Dat	a Acquisition', ISA Publication, 4 th
		ion, 2010.	1 , , ,
Mod	e of Eva	luation: CAT / Assignment / Quiz / FAT / Project / Se	eminar
		<u> </u>	
List	of Chall	enging Experiments (Indicative)	
1.	Implem	entation of Level control process using SCADA	2 hours
2.		nentation of Temperature process using SCADA	2 hours
3.	Implem	nentation of Pressure control process using SCADA	2 hours
4.	Analys	is of interacting and non-interacting systems	2 hours
5.	Conica	l tank control using LabVIEW	2 hours
6.	Tuning	of controllers for single loop and multi loop setup	2 hours
7.	Analyz	ing inherent and installed characteristics of control va	lves 2 hours
8.	IMC an	d Smith predictive control strategies using MATLAE	
9.	Analys	is of timer and counter functions using PLC	2 hours
10.	Batch p	process control and Sequential control using PLC	2 hours
11.		lling a pick and place robotic arm using PLC	2 hours
11.			
12.	Control	lling a gantry crane using PLC	2 hours



14.	Multi-level conveyor control using	g PLC			2 hours
15.	15. HMI module interface and coding with PLC				
			Total Labor	ratory Hours	30 hours
Mod	le of evaluation: CAM / FAT				
Reco	ommended by Board of Studies	05/03/2016			
App	roved by Academic Council	47 th AC	Date	18/03/2016	



		(Deenled to be Oniversity under section 5 of OGC Act, 1956)						
EEE4033		Industrial Instrumentation		L	Т	P	J	C
				3	0	0	4	4
Pre-requisite	EEE4021		S	ylla	bus	5 V(ers	ion
Anti-requisite	NIL						v.	1.0
Course Objective	es:							

1. To develop a better understanding of various sensors & instrumentation system applications in industrial monitoring and control.

2. To provide a good design level understanding of industrial measurement systems.

3. To understand the instrumentation methods available to monitor and control process variables like temperature, pressure flow & level.

Expected Course Outcome:

On successful completion of this programme the graduate will

- 1. Understand the physics and methodology for various types of pressure measurement
- 2. Have detailed knowledge and understanding of a wide range of flow techniques

3. Exercise appropriate judgement in planning, design, technical evaluation of temperature measurement

- 4. Design the various industrial level measurement system
- 5. Formulate responses to well defined force and torque process parameter problems
- 6. Understand theory, concepts and methods pertaining to the speed measuring technique

7. Demonstrate a range of standard and specialized research or equivalent tools and techniques of vibrations parameters

8. Design a component or a product applying all the relevant standards with realistic constraints

Module:1 **Pressure Measurement 8 Hours**

Elastic type pressure gauges - Bourdon tubes, bellows, diaphragms; Electrical methods - elastic elements with LVDT and strain gauges - capacitive type pressure gauge - piezo resistive pressure sensor - resonator pressure sensor ; measurement of vacuum - McLeod gauge - pirani gauge thermal conductivity gauges - Ionization gauge cold cathode and hot cathode types.

Flow Measurements: 7 Hours Module:2 Pressure gradient techniques, Positive displacement flow meters, turbine flow meter; Rotameter: Design- Coriolis mass flow meters - thermal mass flow meter - volume flow meter; Electrical type

flow meter: Electromagnetic flow meter, different types of ultrasonic flow meters - laser doppler anemometer systems; vortex shedding flow meter – target flow meter – solid flow rate measurement. **6** Hours

Module:3 **Temperature, Measurements:**

RTDs and Thermistor characteristics; Thermocouples-Laws, Principals, cold junction compensation; Radiation methods of temperature measurement total and selective radiation pyrometers - optical pyrometer; Thermal conductivity measurements-liquids and gases.

Module:4 Level Measurements:

Gauge glass technique coupled with photo electric readout system; float type level indication different schemes - level switches level measurement using displacer and torque tube - bubbler system; differential pressure method; electrical types of level gauges using resistance, capacitance, nuclear radiation and ultrasonic sensors.

Module:5 **Force and Torque Measurements:** **6 Hours**

6 Hours



Hydraulic – Pneumatic – Resistive (Strain gauge) Force measurement: Different methods of torque measurement – Strain gauge, relative regular twist.

Module:6 Speed measurement:

Revolution counter – Capacitive tacho-drag cup type tacho – D.C and A.C tacho generators – Stroboscope.

Module:7	Vibration Measurement:	6 Hours
Nature of vib	prations - Seismic transducer - Types of accelerome	eters – Potentiometric type – LVDT
Acceleromete	er – Piezo electric type.	

Module	e:8	Contemporary issues:			2 hours		
			Total Lecture he	ours:	45 Hours		
Text Be	ook(s))					
1.	1. D. Patranabis, 'Principles of Industrial Instrumentation', Tata McGraw Hill, 2010.						
2.	R.K.Jain, 'Mechanical and Industrial Measurements', Khanna Publishers, 6th edition New						
	Delhi 2010.						
Referen	nce B	ooks					
1.	J.P H	Holman, 'Experimental Metho	ods for Engineers?	Tata McC	raw Hill International, 2010.		
2.	Donald. P Eckman, 'Industrial Instrumentation', CBS publishers, 2012.						
3.	Doe	blein E.O, 'Measurement Sys	tems, Application	s and Desi	gn', McGraw Hill International,		
	2013	3.					
4.	Alar	S. Morris, 'Principles of Me	asurement and Ins	strumentat	on', PHI, 2009.		
Mode o	f Eva	luation: CAT / Assignment /	Quiz / FAT / Proj	ect / Semir	ar		
Recom	nende	ed by Board of Studies	05/03/2016				
Approv	ed by	Academic Council	47 th AC	Date	18/03/2016		

6 Hours



MAT2002 Applications of Differential and Difference Equations L T P J C Equations 3 0 2 0 4 Pre-requisite MAT1011 Syllabus Versite v.1.0 Course Objectives v.1.0 v.1.0 Course is aimed at 1. Presenting the elementary notions of Fourier series, which is vital in practical harmonic analysis 2. Imparting the knowledge of eigenvalues and eigen vectors of matrices and the transform techniques to solve linear systems, that arise in sciences and engineering 3. Enriching the skills in solving initial and boundary value problems 4. Impart the knowledge and application of difference equations and the Z-transform discrete systems, that are inherent in natural and physical processes Expected Course Outcome At the end of the course the student should be able to 1. Employ the tools of Fourier series to find harmonics of periodic functions from the tabulated values 2. Apply the concepts of eigenvalues, eigen vectors and diagonalisation in linear systems 3. Know the Z-transform and its application in population dynamics and digital signal processing 5. Know the Z-transform and its application in population dynamics and digital signal processing 6 hou 6. demonstrate MATLAB programming for engineering problems 6 hou Module:1 Fourier serie	(Deemed to be University under section 3 of UGC Act, 1956)									
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 1. Employ the tools of Fourier series to find harmonics of periodic functions from the tabulated values 2. Apply the concepts of eigenvalues, eigen vectors and diagonalisation in linear systems 3. Know the techniques of solving differential equations 4. understand the series solution of differential equations and finding eigen values, eigen functions of Strum-Liouville's problem 5. Know the Z-transform and its application in population dynamics and digital signal processing 6. demonstrate MATLAB programming for engineering problems Module:1 Fourier series: 6 hour Fourier series - Euler's formulae - Dirichlet's conditions - Change of interval - Half range series - RMS value – Parseval's identity – Computation of harmonics Module:2 Matrices: 6 hour Eigenvalues and Eigen vectors - Properties of eigenvalues and eigen vectors – Cayle Hamilton theorem - Similarity of transformation - Orthogonal transformation and nature quadratic form Module:3 Solution of ordinary differential equations: 6 hour Linear second order ordinary differential equation with constant coefficients – Solutions homogenous and non-homogenous equations - Method of variation of parameters – Solutions of Cauchy-Euler and Cauchy-Legend differential equations Module:4 Solution of differential equations through Laplace transform and matrix method Solution of ODE's - Nonhomogeneous terms involving Heaviside function, Impulfunction - Solving nonhomogeneous system using Laplace transform – Reduction of <i>n</i>	^									
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function - Solving nonhomogeneous system using Laplace transform - Reduction of n		A		• • 1	C	<u></u>	T	1		
and an differential equation to fingt and an arotan. Calculate and a second										
order differential equation to first order system - Solving nonhomogeneous system of find $(M' - M' - Q)$			unnon	logen	eous	sys	ıem	of first		
order differential equations $(X' = AX + G)$ and $X'' = AX$	order differential	equations $(X' = AX + G)$ and $X'' = AX$								
							6	hours		
series Solutions:		1 1					Ū	nouis		
The Strum-Liouville's Problem - Orthogonality of Eigen functions - Series solutions of			nction	s - Se	ries	solu	tion	sof		
differential equations about ordinary and regular singular points - Legendre differential										



equ	ation - Bessel's differential equation	
Mod	ule:6 Z-Transform:	6 hours
Z-tr	ansform -transforms of standard functions - Inverse Z-transform: by partial f	ractions
and	convolution method	
Mod	ule:7 Difference equations:	5 hours
Diffe	erence equation - First and second order difference equations with constant of	coefficients
- Fil	bonacci sequence - Solution of difference equations - Complementary	function -
Parti	cular integral by the method of undetermined coefficients - Solution	of simple
diffe	rence equations using Z-transform	
Mod	lule:8 Contemporary Issues 2 hours	
Indu	stry Expert Lecture	
	Total Lecture hours:	45 hours
	Book(s)	
1.	Advanced Engineering Mathematics, Erwin Kreyszig, 10 th Edition, Joh	n Wiley
	India, 2015	
Refe	rence Books	
1.	Higher Engineering Mathematics, B. S. Grewal, 43 rd Edition, Khanna Publis	shers,
	India, 2015	
2.	Advanced Engineering Mathematics by Michael D. Greenberg, 2 nd Edition,	Pearson
	Education, Indian edition, 2006	
Mod	e of Evaluation	
Digit	tal Assignments (Solutions by using soft skills), Continuous Assessment	
Tests	s, Quiz, Final Assessment Test	
1.	Solving Homogeneous differential equations arising in engineering	2 hours
	problems	
2.	Solving non-homogeneous differential equations and Cauchy, Legendre	2 hours
	equations	
3.	Applying the technique of Laplace transform to solve differential	2 hours
	equations	
4.	Applications of Second order differential equations to Mass spring	2 hours
	system (damped, undamped, Forced oscillations), LCR circuits etc.	
5.	Visualizing Eigen value and Eigen vectors	2 hours
6.	Solving system of differential equations arising in engineering	2 hours
	applications	
7.	Applying the Power series method to solve differential equations arising	2 hours
	in engineering applications	
8.	Applying the Frobenius method to solve differential equations arising in	2 hours
	engineering applications	
9.	Visualising Bessel and Legendre polynomials	2 hours
10.	Evaluating Fourier series-Harmonic series	2 hours
11.	Applying Z-Transforms to functions encountered in engineering	2 hours
12.	Solving Difference equations arising in engineering applications	2 hours
	Total Laboratory Hours	24 hours
Mod	e of Evaluation: Weekly Assessment, Final Assessment Test	
Reco	ommended by Board of Studies 25-02-2017	
App	roved by Academic Council 37 th AC Date 05-10-2017	



MAT3003	Complex Variables and Partial Differential Equation	n	L	Т	Р	J	C
MA15005	Complex Variables and Fartial Differential Equation	/11	<u>L</u> 3	2	0	0	4
Pre-requisit	e MAT2002		-	yllat	-	-	ion
i i e i equisit		D.	y 11ea k		, er s		
						V.	.1.1
Course Obj	ectives :						
The aim of the	nis course is to present a comprehensive, compact and integ	rated	treat	ment	of	two	
	ant branches of applied mathematics for engineers and scie						
functions of	complex variable and Partial differential equations in finite	e and	infini	te do	oma	ins	
Expected Co	ourse Outcome:						
At the end of	the course the student should be able to						
1. construct a	analytic functions and find complex potential of fluid flow	and o	electr	ic fi	elds		
	nage of straight lines by elementary transformations and						
3. able to exp	press analytic functions in power series						
	eal integrals using techniques of contour integration						
	rtial differential equations, and its applications, design the		lary v	alue	e pro	obler	ns
	onal heat and wave equations) and find Fourier series, Fou	rier					
transform te	chniques in their respective engineering problems.						
Module:1	Analytic Functions				(6 ho	urs
Complex var	iable-Analytic functions and Cauchy – Riemann equations	- Lap	lace	equa	tion	and	[
Harmonic fu	nctions - Construction of Harmonic conjugate and analytic	funct	ions -	Ap	plica	ation	ıs
of analytic fu	unctions to fluid-flow and Field problems.						
Module:2	Conformal and Bilinear transformations					5 ho	urs
Conformal n	happing - Elementary transformations-translation, magnifi	catior	n, rota	tion	,		
inversion. E	sponential and Square transformations (w = e^z , z^2) -	Biline	ear tr	ansf	orm	atior	n -
Cross-ratio-I	mages of the regions bounded by straight lines under the al	ove t	ransf	orma	atio	18.	
Module:3	Power series				4	4 ho	urs
Functions give	ven by Power Series - Taylor and Laurent series -singularit	ies - p	oles	– Re	sidu	ies.	
U	· · · · · · · · · · · · · · · · · · ·	•					
Module:4	Complex Integration				5	ho	urs
	f a complex function along a contour - Cauchy-Goursat th	eoren	n- Ca	auch		110	uib
	nula -Cauchy's residue theorem - Evaluation of real int					cont	our
integral.	,	0-440					
0							
Module:5	Partial Differential equations of first order					6 ho	iire
	and solution of partial differential equations of first of def	ular	Com	nlete			u13
	egrals - Partial Differential equations of first order of the fo				and	1	
-	G(x,p)=G(y,q) and Clairaut's form - Lagrange's equation: P)-0,			
· (2,p,q) 0,1	(A,p) S(y,q) and Chandrat 5 form - Lagrange 5 equation. I	<u>רי אי</u>	IX.				
Module:6	Applications of Partial Differential				1	0 ho	urs



Linear partial differential equations of higher order with constant coefficients. Solution of a partial differential equation by separation of variables - Boundary Value Problems-one dimensional wave and heat equations- Fourier series solution.

Module:7 Fourier transforms

7 hours

Complex Fourier transform and properties - Relation between Fourier and Laplace transforms - Fourier sine and cosine transforms - Convolution Theorem and Parseval's identity.

Mo	dule:8	Contemporary issues:			Module:8Contemporary issues:2 hours									
Indu	ustry Ex	pert Lecture												
					e hours:	45 hours								
Tut	torial	1. A minimum of 10	L		ked out	30 hours								
		•	by students inventory Tutorial Class											
		2. Another 5 problem	s per Tutoria	l Class	to be									
		given as home wor	k											
Text Book(s)														
1.	Advan	ced Engineering Mathemati	ics, Erwin Kr	eyszig,	10 th Editi	ion, John Wiley &								
	Sons (V	Viley student Edison) (2015	5)											
Ref	erence l													
1	Higher	Engineering Mathematics,	B. S. Grewal,	, 43 rd	Edition (2	2019), Khanna								
	Publish	ers, New Delhi												
2	A first	course in complex analysis	is with appli	cations,	G.Dennis	s Zill, Patrick D. Shanahan,								
	3rd Edi	tion, 2013, Jones and Bartle	ett Publishers	Series	in Mather	natics:								
3	Advanced Engineering Mathematics, Michael, D. Greenberg, 2 nd Edition, Pearson													
	Education (2006)													
4														
	(2012)													
5														
2	Edition, Narosa Publishers (2013)													
Mode of Evaluation: Digital Assignments, Quiz, Continuous Assessments, Final Assessment Test														
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Rec	ommend	led by Board of Studies	25-02-2017											
App	proved b	y Academic Council	47 th AC	Date	05-10-20	017								



	(Deemed to be University under section 3 of UGC Act, 1956)	т		n	т	C		
MAT3005	Applied Numerical Methods		T 2	P	J	C 4		
Due neguicite	MA T2002	3		$\frac{0}{\sqrt{1-1}}$	0	•		
Pre-requisite	MAT2002	Syl	Syllabus Version v.1.1					
Course Objectives			۷.	1.1				
Course Objectives The aim of this cours	a is to							
	sic, important computer oriented numerical	mathada	for	0.00	1	ina		
	engineering and physical sciences.	memous	101	alla	uyz	mg		
1	he primary computer language to obtain solution	is to a fea	w nrc	hlei	ne t	hat		
			v pro		115 t	nat		
arise in their respective engineering courses. 3. impart skills to analyse problems connected with data analysis,								
	partial differential equations numerically							
Expected Course O								
	rse the student should be able to							
1. Observe the differe	ence between exact solution and approximate solu	ution.						
	l techniques to find the solution of algebraic e		and	sys	tem	of		
equations.		1		•				
3. Fit the data using in	nterpolation technique and spline methods.							
	f ordinary differential equations, Heat and Wave			neric	ally	′ .		
	f variation techniques to extremize the fur	nctional	and	als	o f	ind		
approximate series so	lution to ordinary differential equations							
Module:1	Algebraic and Transcendental Equations	5	hou	rs				
General iterative met	hod- rates of convergence- Secant method - New	vton – Ra	aphso	on m	neth	od-		
System of non-linear	equations by Newton's method.							
Module:2	System of Linear Equations and Eigen	6	hou	rs				
	Value Problems							
Gauss -Seidel ite	ration method. Convergence analysis of	iterative	e m	etho	ds-	LU		
Decomposition -Tri	diagonal system of equations-Thomas algorith	hm- Eig	en v	alue	s o	fa		
matrix by Power and								
Module:3	Interpolation	6	hou	rs				
Finite difference op	erators- Newton's forward-Newton's Backwar	d- Cent	ral d	iffe	renc	es-		
Stirling's interpolation	on - Lagrange's interpolation - Inverse Interpol	lation-Ne	wtor	n's c	livio	ied		
	on with cubic splines.							
Module:4	Numerical Differentiation and Integration	6	hou	rs				
	ation with interpolation polynomials-maxima and				nila	ted		
values-Trapezoidal r	the simpsons $1/3^{rd}$ and $3/8^{th}$ rules. –Romberg's	method	Two	and	Th	ree		
point Gaussian quadr			0					
	Numerical Solution of Ordinary	\$	hou	rs				
	Differential Equations	L L						
	er differential equations - Fourth order Runge –	- Kutta n	netho	d 4	dar	ns-		
	predictor-corrector methods. Finite difference s							
order ordinary differe		Jointion	101 1			/IIU		
	Numerical Solution of Partial Differential	6	hou	ire				
wiouule.v	numerical Solution of Fartial Differential	0	not	115				



Equations
Classification of second order linear partial differential equations-Laplace equation –Gauss-
Seidal method-One dimensional heat equation- Schmidt explicit method-Crank-Nicolson
implicit methodOne dimensional wave equation-Explicit method.

Module:7		Variational Methods			6 hours			
Introduction	n - functi	ional -variational proble	ems- extremals o	f functional o	of a single dependent			
variable and	d its first	t derivative- functional	involving highe	r order deriva	atives- Isoperimetric			
problems- (Galerkins	- Rayleigh Ritz method	ls.					
Module:8		Contemporary Issues	5		2 hours			
Industry Ex	pert Lec	ture						
		I		1				
-			Total Lecture		45 hours			
Tutorial		1. A minimum of 10			30 hours			
		out by students in e						
		2. Another 5 problem		lass to				
		be given for practis	se.					
Text Book								
1.		merical Methods for S						
	Iye	ngar and R. K. Jain, New Age International Ltd., 6 th Edition, 2012.						
2.		blied Numerical Analysis, C. F. Gerald and P.V. Wheatley, Addition-						
	We	esley, 7 th Edition, 2004.						
Reference	Books							
1.	Introdu	ctory Methods of Nur	nerical Analysis	, S.S. Sastry	, PHI Pvt. Ltd., 5th			
		, New Delhi, 2009.						
2.	Applied	l Numerical Methods U	Jsing MATLAB,	W.Y. Yang,	W. Cao, T.S. Chung			
	and							
3.	J. Mori	ris, Wiley India Edn., 20	007.					
4.		cal Methods for Engine						
		C. Chapra and Ra P. Ca						
5.		cal Analysis, R.L. Burd						
6. Numerical Methods: Principles, Analysis and Algorithms, Srimanta Pal, O								
University Press India, 2009.								
Mode of Ev	aluation	: Digital Assignments, G	Continuous Asse	ssment Tests,	Final Assessment			
Test		-						
Recommen	ded by B	oard of Studies	25-02-2017					
		mic Council	47 th AC	Date	05-10-2017			



EEE1007	Neural Networks and Fuzzy Control	L T P J C						
		2 0 0 4 3						
Pre-requisite	MAT1011	Syllabus version						
Anti-requisite	NIL	v. 1.1						
Course Objective	s:							
1. Apply the	design concepts of feed forward and feedback neu	aral networks for solving						
Engineerin	g problems	-						
	copriate weight and learning constant values for every lea	-						
	and analyze the real time system with the knowledge of	fuzzy logic control						
Expected Course								
-	of this course the student will be able to:							
2. Demonstra solution.	mathematical model for single and multi-layer Perceptro te the concepts of feed forward and re-current neural ne e concepts of Recurrent and feedback networks in multila	etworks to find the optimal						
4. Design the	competitive learning neural networks for solving the engine performance of Self organizing networks.	-						
6. Design of fuzzy systems for non-linear simulation with extension principle.7. Apply membership functions with suitable de-fuzzification method and apply neuro-fuzzy inference system concepts to modern controllers.								
	component or a product applying all the relevant	standards with realistic						
	roduction to Artificial Neural Networks and Learni							
	networks and their biological motivation – Terminological							
	cteristics of artificial neural networks – Types of activati							
-	Learning methods – Error correction learning – Hebbia erceptron learning rule convergence theorem – Adaline –							
Module:2 Feed	d Forward Networks	4 Hours						
Multilayer Percept	tron – Delta Learning – Back Propagation learning algor	rithm – Universal function						
approximation – A	Associative memory: auto association and hetero associat	ion.						
Module:3 Rec	urrent Neural Networks	2 Hours						
Bi-directional asso	ociative memory – Hopfield neural network – Travelling	Salesman Problem.						
Module:4 Uns	upervised Learning	3 Hours						
	ing neural networks – Max net – Maxican Hat – Hammin	ng net.						
Module:5 Self	Organizing Networks	5 Hours						
	anizing Feature Map – Counter propagation – Learni							
-	nce Theory – Concept of support vector machines	-						
-	TCE THEORY = CONCEDE OF SUDDON VECTOR HIACHINES							
IICLWOIKS III IIIIA2C								
	processing, signal processing, modeling and control.							
Module:6 Fuz		5 Hours						



functions – principle.	Fuzzy to Crisp conversi	on, Fuzzy Arith	metic, nui	mbers, v	vectors	and ext	ension
Module:7	Fuzzy Decision Making					2	Hours
Fuzzy rule ba methods.	ased systems – Fuzzy nonlir	near simulation –	Fuzzy con	trol syste	ems and	Defuzzi	fication
Neuro Fuzzy	* Mathematical formulation	of adaptive Neur	o – Fuzzy	inferenc	e system	IS.	
Module:8	Contemporary issues:					2	Hours
Text Book(s	5)						
1.	Jacek. M. Zurada, "Intro House, 2006.	oduction to Artif	icial Neu	ral Syste	ems", Ja	aico Pul	blishing
2.	Simon Haykin, Neural Net New York, 2016.	tworks and learning	ng Machin	es", Mac	Millen	College	Pubco.,
Reference B	ooks						
1.	1. Laurene Fausett, Fundamentals of Neural Networks – Architectures, algorithms and applications, Pearson Education Inc., 2004						
2.	Timothy J.Ross, Fuzzy L 2017.	ogic with Engine	ering App	lications	, John V	Wiley an	nd sons,
3.	J.S.R. Jang, C.T. Sun, computational Approach Inc., 2010.			•		-	0
Mode of Eva	luation: CAT / Assignment /	/ Quiz / FAT / Pro	ject / Sem	inar			
Recommende	ed by Board of Studies	05/03/2016					
Approved by	Academic Council	40 th AC	Date	18/03/2	2016		



	(Deemed to be University under section 3 of UGC Act, 1956)							
EEE1008	Bio-Medical Instrumentation	L	T P J C					
		3	0 0 4 4					
Pre-requisite	NIL	Sylla	bus version					
Anti-requisite	NIL		v. 2.0					
Course Objectives								
1. To give an u	nderstanding of the biological signals and signal acquisition							
2. To provide t	he design concepts of bioelectric amplifiers							
3. To learn the	principle and operation of various biomedical systems							
Expected Course	Outcomes:							
On the completion of	of this course the student will be able to:							
	analyse the different physiological signals							
	nowledge to select appropriate medical instruments							
0	oio electric devices used for diagnostic equipment							
	analyse the therapeutic devices.							
	the procedure for blood analysis in medical laboratory							
	process involved in blood cell counters and sensors							
	e the advanced diagnostic techniques.	1						
8. Design a coi	mponent or a product applying all the relevant standards with re-	ealistic c	onstraints					
Module:1 Intro	duction to Diamodical Instrumentation and Macaurament		8 Hours					
	duction to Biomedical Instrumentation and Measurement							
	ric potentials, cardiovascular system, Central nervous system alysis of different physiological signals (ECG, EEG, EMG)							
	rsis including Nernst equation, Goldman equation, Electric		•					
	is for ECG, EEG &EMG.		Juctivity 0					
	ral Considerations of Medical Instruments		8 Hours					
	fiers, Bioelectric Amplifiers, Selection of biomedical am	nlifiers						
	amplifiers and Chopper amplifier. Characteristics of b							
	ogical effects of electric currents, Electric shock hazards an							
Methods of acciden		ia iouita	50 currents					
	nostic Equipment		7 Hour					
	ration, Vector cardiograph, Phono-cardiograph, EEG and EM	G Electr						
	ement of various volumes/capacity of lungs, Spirometer. Mea							
output, blood flow a								
	apeutic Equipment		6 Hours					
	s, cardiac defibrillators, nerve & muscle stimulators, diatherm	iy-types,						
Dialyzer.		5 51 7						
	cal Laboratory Instrumentation		5 Hours					
	Measurement of pH, pO2 and pCO2 value of blood using pH/ga	as analyz	zers					
-	cal Laboratory Measurement		4 Hours					
Photometers, Hema	tology, Blood cell counters, Electrophoresis- Serum detection	n and cl	assification					
	sors, GSR measurements.							
Module:7Advanced Diagnostic Techniques5 Hours								
	nd Visualization (X-Ray, MRI, CT), Biomedical Spectroscopy	y, Optica	l coherence					
	escence based Bio-detection & Bio-imaging- Case study:							
health care monitor								
Module:8 Con	temporary issues:		2 hours					
Text Book(s)								



	(Deemed to be Oniversity under section 5 or OOC Act, 1950)						
1.	Leslie Cromwell, Fred J, Weibell & Erich A and P Feiffer, 'Biomedical Instrumentation and						
1.	Measurements', 2 nd Edition, PHI, 2011.						
2.	J.J. Carr & J.M. Brown, 'Introduction to biomedical Equipment Technology', Prentice Hall,						
۷.	4 th Edition, 2011.						
Reference Books							
1.	R. S. Khandpur, 'Handbook of Biomedical Instrumentation', Tata Mc-Graw Hill, 2nd						
1.	edition, 2014.						
2.	John.E. Hall, Guyton and Hall, Textbook of Medical Physiology, Saunders; 13 th Edition,						
Ζ.	2015.						
2	Rangaraj M. Rangayyan, 'Biomedical Signal Analysis', A Case-Study Approach, Wiley, 2 nd						
3.	Edition, 2015.						
Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40%							
Recom	nended by Board of Studies 30/11/2015						
Approv	ed by Academic Council 39th AC Date 17/12/2015						



 3. Practical knowledge imparted on LabVIEW usage in PCBA testing for its furbehaviour Expected Course Outcome: On the completion of this course the student will be able to: Discover the possible component faults that can occur in electronic manufac Classify the faults that occur in PCBs. Analyze and develop practical skills involved in troubleshooting. 	cond ll fun	uipr itio	s ve	rsio v. 1										
Anti-requisite NIL Course Objectives: 1. Aims to provide knowledge about the testing of IC's using automated Testin (ATE). 2. Providing hands-on in Simulation software's used to simulate the evaluation 3. Practical knowledge imparted on LabVIEW usage in PCBA testing for its fu behaviour Expected Course Outcome: 0n the completion of this course the student will be able to: 1. Discover the possible component faults that can occur in electronic manufac 2. Classify the faults that occur in PCBs. 3. Analyze and develop practical skills involved in troubleshooting.	g Equ cond ll fun	uipr itio	nen ns.	v. 1										
 Course Objectives: Aims to provide knowledge about the testing of IC's using automated Testin (ATE). Providing hands-on in Simulation software's used to simulate the evaluation Practical knowledge imparted on LabVIEW usage in PCBA testing for its fubehaviour Expected Course Outcome: Discover the possible component faults that can occur in electronic manufac Classify the faults that occur in PCBs. Analyze and develop practical skills involved in troubleshooting. 	cond ll fun	itio	nen		1.0									
 Aims to provide knowledge about the testing of IC's using automated Testin (ATE). Providing hands-on in Simulation software's used to simulate the evaluation Practical knowledge imparted on LabVIEW usage in PCBA testing for its fu behaviour Expected Course Outcome: On the completion of this course the student will be able to: Discover the possible component faults that can occur in electronic manufac Classify the faults that occur in PCBs. Analyze and develop practical skills involved in troubleshooting. 	cond ll fun	itio	ns.	t										
 (ATE). 2. Providing hands-on in Simulation software's used to simulate the evaluation 3. Practical knowledge imparted on LabVIEW usage in PCBA testing for its furbehaviour Expected Course Outcome: On the completion of this course the student will be able to: 1. Discover the possible component faults that can occur in electronic manufac 2. Classify the faults that occur in PCBs. 3. Analyze and develop practical skills involved in troubleshooting. 	cond ll fun	itio	ns.	t										
 On the completion of this course the student will be able to: 1. Discover the possible component faults that can occur in electronic manufac 2. Classify the faults that occur in PCBs. 3. Analyze and develop practical skills involved in troubleshooting. 	turing				(ATE).2. Providing hands-on in Simulation software's used to simulate the evaluation conditions.3. Practical knowledge imparted on LabVIEW usage in PCBA testing for its full functional									
 On the completion of this course the student will be able to: 1. Discover the possible component faults that can occur in electronic manufac 2. Classify the faults that occur in PCBs. 3. Analyze and develop practical skills involved in troubleshooting. 	uring													
 Understand the board functional testing. Design and analyze the board functional Testing. 	 Discover the possible component faults that can occur in electronic manufacturing. Classify the faults that occur in PCBs. Analyze and develop practical skills involved in troubleshooting. Test the Various parameters involved in ATE Understand the board functional testing. Design and analyze the board functional Testing. Distinguish the Boundary Scan and Board Testing to understand the equipment used in automated testing. 													
Module:1Introduction Topcb Assemblies:Printed Circuit Board (PCB)-types of PCB-multilayer PCBs-Plat Plated though HSurface Mount Technology (SMT) – Ball Grid Array (BGA) Technology – manufacturing process – Bare board testing– PCB Inspection methods – Visual, OInspection systems– Electrical tests in PCBs	PCB	Ba	re	ogy boa	y - urd									
Module:2 PCBA Troubleshoot Methods:			2 E											
PCB assembly troubleshoot – locating faults & Manual troubleshoot – Online & Of – Fault types and causes in circuits – Tools and instruments for usage – DMM(Dig CRO (Cathode Ray Oscilloscope) - Logic probes – Logic pulser – Logic Analyzer.														
Module:3 PCBA Troubleshoot Methods:			2 H	[011	rs									
Automated Testing of PCBs – Out-circuit & In-circuit test methods – VI Trace Technique – signature analysis – Board Functional Testing Techniques– Boundary Scan Test Strategy & methods – External Instrumentation in Automated Testing – PCB diagnostic testers – Diagnostic Testing technique.														
Module:4 Automated Test Techniques:			5 H	lou	rs									
Automated Test Techniques – Various parameters – AC – DC Parametric test Identify and troubleshoot the failures of parameters– Environmental, Electri Requirements for IC testing – In-circuit Testing methodologies – Back Driving Digital, Analog and Mixed Signal ICs– Guarding Technique – VI Trace Technique Boundary Scan Test for components on board – In-circuit measurement of passi Kelvin measurement – Test Fixtures – Types of Test Fixtures – Bed of Nails Fixt	cal S - fun of co ve co	stan ctic ompomp	tes idar onal pone	ting ds tes ents ents	g– & st– s –									



Test Fixtures – Reverse Engg to rebuild the Schematic Diagram using ATE and Software.								
Module:	5	Board Fi	unctional Tes	ting (BFT):				6 Hours
Backtra Compre testing–	cking ehens - BC – Ex	tional Test g Techniqu iveness of SS– Interfa ternal Instr	(BFT) techniq e – Simulators Board program ce adaptor or pe	ues – Go-No – Online an – Fault Dicti ersonality adap	-go T d Off onary- otor(Po	fline Sin – Analy (od) - Sa	nulation - Fau sis – BS and mple board pro	Guided Probe ult Simulation– Non-BS device ogramming and – Integration of
Module:	:6	DFT:						4 Hours
Design : ATE for			OFT)- test issues	– Fault Models	s — B	oundary	v Scan Test– Se	elf Test design –
Module:	:7	DFM:						6 Hours
-	ies –		-				-	oduction process cturing – Various
Module:	:8	Contemp	orary issues:					2 Hours
				Total Lectur	e houi	rs:		30 Hours
Text Boo	ok(s)							
		Sabapathi, on, 2011.	"Test Engineer	ing for Electro	onic H	Iardware	e", Tata McGr	aw Hill, First
Reference		,						
			and Yon Mayhe	, "Engineerin	g The	rmodyn	amics", Pearson	n,2009
2.	Floy							Education India,
List of C	Chall	enging Exp	eriments (Indio	ative)				
1. Fur	nctio	nal Test Us	ing Boundary Sc	an Tester		·		2hours
2. Clu	ıster	Test Using	Boundary Scan	Tester				2 hours
3. Ou	t Cir	cuit Functio	onal Test					2 hours
4. In (Circu	it Function	al Test					2 hours
5. QS	SMV]	[Signature]	Test					2 hours
6. Sca	an Cl	nain Test						2 hours
7.Continuity Test Using Short Locater2 hours						2 hours		
8. Analog Test Using ATE 2 hours							2 hours	
9. Par	rame	tric Testing	DC and AC para	ameters				2 hours
10. VL	LSI h	igh speed T	esting using AT	E				2 hours
							ratory Hours	20 hours
Mode of			CAT I & II – 3		- 20%	6, Quiz	– 10%, FAT –	40%
		d by Board		05/03/2016				
Approve	Approved by Academic Council40th ACDate18/03/2016							



	(Deemed to be University under section 3 of UGC Act, 1956)	
EEE1012	Optoelectronic Instrumentation	L T P J C
Pre-requisite	PHY1001/PHY1701	Syllabus version
Anti-requisite	NIL	v. 1.0
Course Objectives		
	nd the principles underlying the theory and wide application	ations of optical
instrumenta		
-	nd develop an optical instrument for non-contact measu	
3. To provide	an exposure on latest developments of optical instrumer	itation
Course Outcome:		
	of this course the student will be able to:	
-	d the various types of noncontact optical instruments	
-	the working principle of various optical sources and de	tectors
	tical fiber characteristics and their usage in measuremen	
1	fiber optic sensor for various physical parameter measur	
5. Design the	laser based optical instrumentation.	
	the use of laser in optical non-destructive testing.	
7. Develop sol	utions for real world problems using optical instrument	ation
		2.11
	view Of Optical Instrumentation:	3 Hours
	antages of noncontact measurements, competing techn	ologies, classification of
optical measuremen	nts.	
Module:2 Opti	cal Sources and detectors :	10 Hours
1	t emission, materials, population inversion, pum	
	iconductor Optical Sources - homojunction and double	
-	bonse time, design of drive circuitry. Classifications: I	
-	ers, CO2 Lasers, Dye Lasers, Fiber lasers. Detectors: I	
), gain and responsivity calculation. Quadrant photod	
displays.), guin une responsivity curculation. Quadrant photod	node, CCD cameras and
1 7		
Module:3 Fund	lamentals of Fiber Optics:	5 Hours
Optical Fiber Char	acteristics and Classifications. Manufacturing of Optic	al fibers, Light sources -
	wer coupling, calculations, Fiber connectors and splic	es - Splicing techniques.
Fiber Amplifier and	d optical modulators.	
	er Optic Instrumentation:	5 Hours
_	s – measurement of displacement, pressure, temperatu	ure, acceleration, torque,
strain, fluid level an	nd flow. Electric and magnetic field sensors.	
Module:5 Lase	r Instrumentation:	10 Hours
	measurements and applications. Laser Interferometer	
-	lications. Alignment, position and sizing Instruments -	
	sor, particle sizing. Laser doppler velocimetry -	
with diameter set	ion, particle sizing. Laser doppier verochnetty -	



performance parameters, electronic processing of doppler signal.	Holography - Basic principles -
Methods of holographic interferometry and applications.	

Module:6 Optical Non-Destructive Testing:							5 Hours	
Fiber optic	s, Laser	speckle,	Infrared	thermography,	endoscopy,	holography	and	terahertz
technology.								

Module:7	Advanced optical Instrumentation:					5 Hours			
Laser remote	e sensing	(LIDAR),	advanced	optical	pollution	mea	surements,	optical	imaging,
lithography, spectrometers.									

Module	e:8	Contem	porary issues:			2 Hours	
				Total Lectur	e hours:	45 Hours	
Text Bo	Text Book(s)						
1.				ē		endez, "Fiber optic Sensors:	
	Fund	lamental a	nd Applications",	SPIE, 4 th Edition, 2	2015.		
2.	Silva	ano Donati	i, 'Electro-Optica	l Instrumentation: S	Sensing an	d Measurements with lasers',	
	PHI,	2010.					
3.	W. 0	Osten and	N. Reingand, P,"	Advanced Methods	s for Optic	cal Nondestructive Testing, in	
	Opti	cal Imagir	g and Metrology	: Advanced Techn	ologies", V	Wiley-VCH Verlag GmbH &	
	Co.	KGaA, 20	12.				
Referen	nce B	ooks					
1.	Gerc	l Keiser, "	Optical Fiber Cor	nmunications", Tata	a McGraw	Hill, 5 th Edition, 2013.	
2.	A.K	.Ganguly,	" Optical and C	ptoelectronics Inst	rumentatio	on", Alpha Science Intl Ltd,	
	2010).					
3.	John G. Webster, Halit Eren, "Measurement, Instrumentation, and Sensors Handbook,						
	Second Edition: Electromagnetic, Optical, Radiation, Chemical, and Biomedical						
	Measurement", CRC press, 2014.						
Mode o	f valu	ation:	CAT I & II – 30	%, DA I & II – 20%	%, Quiz – 1	10%, FAT – 40%	
Recom	nende	ed by Boar	d of Studies	05/03/2016			
Approv	ed by	Academic	Council	40 th AC	Date	18/03/2016	



EEE1013		Analytical Instrumentati	on	L	ΤI	P J C
				3	0 0	03
Pre-requisite)	PHY1001		Sylla	bus v	ersion
Anti-requisit	te	NIL				v. 1.0
Course Obje	ctives:		·			
 To de To un 	sign the derstan	nd interpret data from different chromatograp e radiation sources, detectors and optical syste d the working principles of spectrometry and he performance of various nuclear radiation s	ems for various spectrophotom	eter.	eters.	
Course Outc	ome:					
		f this course the student will be able to:				
types 2. Apply given 3. Analy 4. Demo 5. Apply 6. Illustr condu 7. Measu in the Module:1	y and sample se the o nstrate y chrom ate th ctivity are and given s Electron spectro	the interaction of electromagnetic radiations analyse the analytical techniques to deter accurately. concepts of NMR, Spectrometers and their we contemporary measurement techniques relate atography to analyse industrial environments e working principle of Ion Selective meters. formulate the composition of dissolved oxyg maples. omagnetic Radiation: cteristics – interaction of EM radiation with n scopy – Beer-Lamberts Law – radiation source gratings.	mine the elem orking. ed to analyzers. s. Electrodes, I gen, sodium, sil	PH elec ica eleme methods	sent trode: ents p 5 of an	in the s and present Hours alysis
		mentation for Absorption and Emission			8	Hours
Module:2	spectr	oscopy:				
UV – Visible and detectors absorption sp instrumentation	spectrose spectrose on, sou	oscopy – single beam and double beam ins ectroscopy - FTIR spectrometer – instrument copy – instrumentation, sources and detect rces and detectors; Applications of absorption	ation- sources a ors; Flame em	nd detect ission pl	ors. A notom s.	Atomic etry –
UV – Visible and detectors absorption sp instrumentation	spectrose (in spectrose (on, sou (Nucle)	roscopy – single beam and double beam ins ectroscopy - FTIR spectrometer – instrument copy – instrumentation, sources and detect	ation- sources a ors; Flame em	nd detect ission pl	ors. A notom s.	Atomic etry –
and detectors absorption sp instrumentation Module:3 Nuclear Mag spectrometers	s pectrosic spectrosic on, sou Nucle Techn gnetic	roscopy – single beam and double beam ins ectroscopy - FTIR spectrometer – instrument copy – instrumentation, sources and detect rces and detectors; Applications of absorption ar Magnetic Resonance and Radiation	ation- sources a ors; Flame em n spectroscopy t nal features and A counter – pro	nd detect ission ph echnique d workir	ors. Anotom s. 8 ng of	Atomic hetry – Hours NMR
UV – Visible and detectors absorption sp instrumentation Module:3 Nuclear Mag spectrometers scintillation c Module:4	spectrose spectrose on, sou Nuclea Techn gnetic 1 s – app ounter; Mass	 soscopy – single beam and double beam instructions performed performance of a sources and detect present and detectors; Applications of absorption ar Magnetic Resonance and Radiation iques: Resonance – basic principles –Construction plications. Nuclear radiation detectors – GN X- ray diffraction- instrumentation and applications 	ation- sources a ors; Flame em n spectroscopy t nal features an A counter – pro- ications.	nd detect ission ph echnique d workin oportiona	sors. Anotom s. 8 ng of 11 cou	Atomic hetry – Hours NMR
UV – Visible and detectors absorption sp instrumentation Module:3 Nuclear Mag spectrometers scintillation c	scopy –	 soscopy – single beam and double beam instruments pectroscopy - FTIR spectrometer – instrument copy – instrumentation, sources and detect rces and detectors; Applications of absorption ar Magnetic Resonance and Radiation iques: Resonance – basic principles –Construction blications. Nuclear radiation detectors – GN X- ray diffraction- instrumentation and appli spectroscopy: basic principles – Constructional features and 	ation- sources a ors; Flame em n spectroscopy t nal features an A counter – pro- ications.	nd detect ission ph echnique d workin oportiona	sors. Anotom s. 8 ng of 11 cou	Atomic letry – Hours NMR inter –
UV – Visible and detectors absorption sp instrumentation Module:3 Nuclear Mag spectrometers scintillation c	scopy –	 soscopy – single beam and double beam instructions performed performance of a sources and detect present and detectors; Applications of absorption ar Magnetic Resonance and Radiation iques: Resonance – basic principles –Construction plications. Nuclear radiation detectors – GN X- ray diffraction- instrumentation and applications 	ation- sources a ors; Flame em n spectroscopy t nal features an A counter – pro- ications.	nd detect ission ph echnique d workin oportiona	s. 8 10 10 10 10 10 10 10 10 10 10	Atomic letry – Hours NMR inter –



chromatogra	phy – instrumentation a	nd applications.				
Module:6	pH Conductivity & D Analyser:	Dissolved Component		5 Hours		
	e electrodes – conducti ilica analyser – moistur	• •	s – disso	olved oxygen analyser – sodium		
Module:7	Gas Analysers:			5 Hours		
-	rs for Oxygen, CO, N measurement.	Ox - dust and smoke	detector	rs – analysers based on thermal		
Module:8	Contemporary issue	es:		2 Hours		
		Total Lecture ho	urs:	45 Hours		
Text Book(s)		•			
1.	R.S.Khandpur, 'Hand Company Ltd., 3rd Edit	•	Instrume	ents', McGraw Hill Publishing		
2.	Douglas A. Skoog, F. James Holler and Stanley R. Crouch, 'Principles of Instrumental Analysis', Thomson Brooks/Cole, 7 th Edition, 2007.					
Reference B	ooks					
1.	Ewing G.W., 'Instrumental methods of chemical analysis, McGraw-Hill, Newyork.2009.					
2.	Sivasankar B, 'Instrumental Methods of Analysis', Oxford University press.2012.					
3.	Willard, H.H., Merrit L.L., Dean J.A Seattle F.L., 'Instrumental Methods of Analysis', CBS Publishing and Distribution, 2012.					
Mode of Eva	aluation:	CAT I & II – 30%, D 40%	AI&I	I – 20%, Quiz – 10%, FAT –		
Recommend Studies	ed by Board of	05/03/2016				
Approved by	Academic Council	40 th AC	Date	18/03/2016		



	(Deemed to be University under section 3 of UGC Act, 1956)		<u> </u>	
EEE1014	Fiber Optic Sensors	L	T P J	C
		3	000	3
Pre-requisite	PHY1001/PHY1701	Sylla	abus vers	ion
Anti-requisite	NIL		v.	1.0
Course Objectiv	ves:			
	nderstand the principles underlying the theory and its wide app	L		
	esign and develop fiber optic sensors for industrial application			
3. To de	esign and implementation of fiber optic distributed sensors for	various ap	plications	.
Expected Cours	e Outcome:			
-	on of this course the student will be able to:			
-	rstand the overview of fiber optic sensors and its unique appli	ications		
	yse the optical fiber characteristics and their usage in sensing.			
	prehend the working principle of various optical sources and o		ed for fib	er
optic	sensors			
	rstand the principle of various fiber optic components used to sensor	o construct	the fiber	
-	yse the working principle of fiber optic sensors.			
	y the fiber optic sensor for different physical parameter measure	irements.		
	in the multiplexing and distributed sensing of optical fiber ser			
	verview of Optical Sensors:		3 Ho	
Introduction - A sensors.	Advantages of optical sensors, Competing technologies, C	Classificatio	n of opti	ical
Module:2 Fu	undamentals of Fiber Optics:		5 Ho	urs
Basic characteris	stics of optical fiber, Classification, dispersion, attenuation, n	onlinear op	tical effe	cts-
SRS, SBS, SPM	. Modal birefringence and polarization maintaining fibers. S	ource to fil	er coupli	ng,
fiber to fiber join	nts, fiber splicing, optical fiber connectors			
Module:3 O	ptical Sources and Detectors:		5 Ho	urs
-	- LED and laser diodes - various structures, radiation	-		
	light sources. Photo detector – PIN Photodiodes and A	valanche	Photodioc	les-
1 1 1	um efficiency, responsivity, detector noises.			
	ptical Fiber Components and Devices:		3 Ho	
-	lers, polarizers, polarization splitters, polarization controllers	-		
•	th division multiplexers and demultiplexers, switches, intensi	ty, phase a	nd freque	ncy
modulators.				
Module:5 Pr	inciples of Fiber Optic Sensors:		10 Ho	lire
	ation sensors – Extrinsic and intrinsic type – Transmissive, R	eflective N		
-	Effects sensor. Phase modulation sensors – Michelson Interfe			-
-	Mach – Zender Interferometer and Sagnac Interferometer. Pols		-	
	oplications of Fiber Optic Sensors:		8 Ho	
1120441010 [1]	Provident of Free Origon Di		0 110	WE 13



Temperature Measurement, Pressure Measurement, Fluid – Level Measurement, Flow Measurement, Current – Voltage Measurement, Vibration Measurement. Laser Doppler velocimetry. Optical gyroscope. Fiber Bragg grating sensors – strain, temperature, pressure and acceleration measurement – distributed sensing. Nonlinear fiber optic sensor for very high temperature sensing.

Module	e:7	Sensor N	Multiplexing, I	Distributed Se	ensors and	9 Hours
		smart Str	uctures:			
Sensor	netv	vork arch	itectures. Multi	iplexing of	intensity-base	d sensors. Multiplexing of
Interfer	ometr	ic sensors	. Distributed se	ensing – quas	si and fully	distributed sensing - linear
backsca	tterin	g, nonlinea	r backscattering	and forward	scattering sys	tems. Fiber optic smart sensor
system	– App	olication of	fiber optic smart	structures and	skins	
Module	e:8	Contemp	oorary issues:			2 Hours
				Total Le	cture hours:	45 Hours
Text Bo	ook(s))				
1.	Dav	id A. Kro	hn, Trevor W.	MacDougall a	and Alexis N	Aendez, "Fiber optic Sensors:
	Fund	lamental ar	d Applications",	SPIE, Fourth B	Edition, 2015.	
2.	Eric	Uddand W	'illiam B. Spillm	an, Jr., "Fiber o	optics sensors	: An introduction for Engineers
	and	scientists",	John Wiley & So	ons, Second Edi	ition, 2011.	
Referen	nce B	ooks				
1.	Gerc	l Keiser, "C	Optical Fiber Con	nmunications",	Tata McGraw	Hill, Fifth Edition, 2013.
2.	José	Miguel L	.ópez-Higuera, '	'Handbook of	Optical Fibr	e Sensing Technology", John
	Wile	ey & Sons I	Ltd., 2002.			
3.	Zuji	e Fang, Ke	en Chin, Ronghu	ii Qu, Haiwen	Cai, Kai Ch	ang, "Fundamentals of Optical
	Fibe	r Sensors",	John Wiley &So	ons Inc, 2012.		
4.	Eric	Udd, Willi	am <mark>B. Spillman<u>.</u>,</mark>	"Field guide to	o Fiber optics	sensors", SPIE, 2014.
Mode o	f Eva	luation:	CAT I & II – 3	0%, DA I & II	- 20%, Quiz -	-10%, FAT - 40%
Recom	nende	ed by Board	l of Studies	05/03/2016		
Approv	ed by	Academic	Council	40 th AC	Date	18/03/2016



	(Deemed to be University under section 3 of UGC Act, 1956)	
EEE1015	Micro Electromechanical Systems	L T P J C
		3 0 0 4 4
Pre-requisite	MAT2002	Syllabus version
Anti-requisite	NIL	v. 1.1
Course Objectives		
	nd the operation principles of MEMS Devices,	
	nd the various micromachining techniques used to fabricate	
	familiar with a wide variety of MEMS application areas suc Optical MEMS, and Fluidic MEMS	in as MEMS sensors,
KI' WILWIS,	Optical MEMS, and Fluidic MEMS	
Expected Course (Dutcome:	
	of this course the student will be able to:	
-	ng laws for miniaturization,	
	the concepts of micro fabrication techniques	
3. Select the m	ost suitable manufacturing process and strategies for micro	fabrication
	the working principles of MEMS sensors and Actuators	
•	mechanical properties of MEMS based application	
	MEMS and relevant detection methods	
	MS based devices for various applications	
-	mponent or a product applying all the relevant standards wi	th realistic
constraints		
Module:1 Intro	oduction to MEMS: 4 Hours	
	lution from microelectronics-Comparative Study - Multi-	
MEMS	nution from interoclectronics comparative study whith	disciplinary nature of
Module:2 MEN	AS and Miniaturization: 6 Hours	
	Ainiaturization - Scaling in Geometry - Rigid Body Dyn	
Forces - Electromag	gnetic Forces – Electricity - Fluid Mechanics - Heat Transfe	er
	rials and Process: 10 Hours	
	Glass, Ceramics; Photolithography, Bulk Micromachin	0
1 0	and Anisotropic Etching; Dry Etching; Wafer Bonding Surface Micromachining: basic process flow, release, Stict	
residual stress; CVI	· · ·	tion, material choices,
	IS Actuators and Sensors:	10 Hours
	s, Pumps, Motors; comb drive, levitation, equivalent circu	
	ucers; Thermoelectric devices; accelerometers & gyroscope	
	for MEMS:	5 Hours
	erial properties, measurement & characterization of me	1
0	and strain, flexural rigidity, residual stress, boundar	y conditions, spring
combinations		
Module:6 MOI	CMS and Bio-MEMS:	4 Hours
	iew, MOEM technology and applications to telecom, mi	
	cro-optic components, testing and applications.	
· · · · · · · · · · · · · · · · · · ·	1 · · · · · · · · · · · · · · · · · · ·	



Bio-MEMS: Materials and processes for Bio-MEMS; Biochips and microarrays; Systems on Chip; Biochip Sensors & detection methods - Electrochemical; Optical (labeled and unlabeled)

Module	:7 Applications of MEMS:	4 Hours
	esistive Pressure Sensors, Capacitive Accelerometer	
Piezoele	ectric Gyroscope; DNA Amplification; Thermoelectric	ric Inkjet Print heads; Micro valves and
Pumps		
Module	1 7	2 Hours
	Total Lecture hours:	45 Hours
Text Bo	pok(s)	
1.	Richard C. Jaeger, "Introduction to Microelectro	nic Fabrication", Singapore: Pearson
	Education South Asia, 2014.	
2.	Stephen D Senturia, "Microsystem design", Kluwer	Academic Publishers, 2003.
Referen	ice Books	
1.	Marc. J. Madou, "Fundamentals of microfabricat	tion and nanotechnology. Volume II,
	Manufacturing techniques for microfabrication and	d nanotechnology", Boca Raton, FL :
	CRC Press, 2012.	
2.	P. Rai-Choudhury, "MEMS and MOEMS Technolog	gy and Applications", SPIE, 2017.
3.	Thomas Adams and Richard Layton, "Introductory	MEMS: Fabrication and Applications",
	Springer, 2010.	
4.	M-H. Bao, "Micromechanical Transducers: Pr	essure sensors, accelerometers and
	gyroscopes", Elsevier, 2000.	,
5.	Wanjun Wang, Steven A. Soper, "Bio-MEMS: 7	echnologies and Applications". CRC
	Press, 2007.	

Recommended by Board of Studies	05/03/2016		
Approved by Academic Council	40 th AC	Date	18/03/2016



EEE1016		Non Destructive Testing	5	L	Т	P J	C
				3	0	0 0	3
Pre-requisite	5	PHY1001		Sylla	bus	vers	sion
Anti-requisit	te	NIL				v.	1.0
Course Obje	ctives:						
1. To stu	ıdy and	understand the various Non Destructive Eva	luation and Testi	ing meth	nods	s, the	ory
and th	eir ind	ustrial applications					
Expected Co							
-		f this course the student will be able to:					
-		Ion Destructive Testing techniques to determi	ne defects and cl	haracter	izat	ion c	of
industrial cor	-						
•		the visual testing					
-		onstrate liquid penetrant testing methods					
1		of magnetic particle and eddy current testing ical implementation of radiographic testing					
•	-	ement ultrasonic testing for NDT					
		ment of research and implementation of NDE	E technology				
Module:1	Visua	l Testing:				6 Ho	ours
Fundamental	s of Vi	sual Testing - Vision, lighting, material attri	butes, environme	ental fac	ctors	s, Vi	sual
perception, d	irect an	d indirect methods - mirrors, magnifiers, Bo	roscopes Fibrosc	copes, c	lose	d cir	cuit
television, lig	ght sour	rces and special lighting, A systems, comput	er enhanced syst	tem, sta	nda	rds u	nits
and codes.							
Module:2	Liani	d Penetrant Testing:				6 Ha	mrs
		nd properties of liquid penetrants - develop	ers – advantage	s and li			
		Preparation of test materials - Application					
		post cleaning selection of penetrant n					
		units and codes				,	
	3.4						
Module:3	0	etic Particle Testing:		4		7 Ho	
•	0	m -magnetisation by means of direct and all	•				0
		pth of penetration factors, Direct pulsating on techniques, field around a strength condu					
-		calculation - Longitudinal magnetization - f	-				
		oils, field strength, current calculations, Ma					
(MBN).		ons, neid strength, current calculations, Ma	ignetic Durghau	sali indi	150 1	Anai	y 515
(IMDIA).							
Module:4	Radio	graphy:				6 Ha	ours
X-rays, Prope	erties o	f X-rays relevant to NDE. Absorption of ray	s,scattering, type	es and u	se c	of filt	ters,
screens, geor	netric f	factors, inverse square, law, film type and p	rocessing, chara	cteristic	s of	f filr	ns -
density, spe	ed, co	ntrast, Characteristic curves, Penetrameter	rs, Exposure c	harts, 1	adio	ograp	phic
equivalence,	Radiog	graphy of pipes, welds and castings. Safety	with X-rays Sp	pecial R	ladi	ograj	phic
Techniques							
Module:5	•	Current Testing:				7 Ho	
Generation of	of eddy	y currents - effect of created fields - ef	fect of change	of im	peda	ance	on
B.TECH (EIE)				Page	112	=)	



instrumentation - properties of eddy currents - eddy current sensing elements, probes, type of arrangement - a) absolute b) differential lift off, operation, applications, advantages, limitations - Through encircling or around coils, type of arrangements a)absolute b) differential fill factor, operation, application, advantages, limitations - Factors affecting sensing elements and coil impedance - test part and test system - Signal to noise ratio, relationship to eddy current testing - equipment's

Ultrasonic NDT principles, Different types of wave modes, Physics of wave generation, reception, interactions and propagation. Calibration, data collection, quantification, and interpretation, New methods using guided waves, Resonance and other Low Frequency Methods; Angle beam inspection – thickness measurements – Applications. Module:7 Other Techniques: 5 Hour Holography and Acoustic emission technique. Pressure and leak testing. Condition monitoring of machines, Wear monitoring, Spark testing. Brief over view of Non- Destructive testing standards ASTM, ISO, ASNT, API, ASME boiler and pressure vessel code. Module:8 Contemporary issues: 2 Hour Text Book(s) 1. B Hull, "Non-destructive testing", S.I. : Springer, 2012. 2. Ravi Prakash, "Non-Destructive Testing Techniques", Tunbridge Wells : New Academic Science, 2012. 1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Editio New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies								
interactions and propagation. Calibration, data collection, quantification, and interpretation, New methods using guided waves, Resonance and other Low Frequency Methods; Angle beam inspection – thickness measurements – Applications. Module:7 Other Techniques: 5 Hour Module:7 Other Techniques: 5 Hour Holography and Acoustic emission technique. Pressure and leak testing. Condition monitoring or machines, Wear monitoring, Spark testing. Brief over view of Non- Destructive testing standards ASTM, ISO, ASNT, API, ASME boiler and pressure vessel code. Module:8 Contemporary issues: 2 Hour Text Book(s) 1. B Hull, "Non-destructive testing", S.I. : Springer, 2012. 45 Hour Reference Books 1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies	Module:	:6	Ultrasonic 7	Festing:				6 Hours
methods using guided waves, Resonance and other Low Frequency Methods; Angle beam Module:7 Other Techniques: 5 Hour Holography and Acoustic emission technique. Pressure and leak testing. Condition monitoring of machines, Wear monitoring, Spark testing. Brief over view of Non- Destructive testing standards ASTM, ISO, ASNT, API, ASME boiler and pressure vessel code. 2 Hour Module:8 Contemporary issues: 2 Hour Text Book(s) 1. B Hull, "Non-destructive testing", S.I. : Springer, 2012. 2. Ravi Prakash, "Non-Destructive Testing Techniques", Tunbridge Wells : New Academic Science, 2012. Reference Books 1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Editio New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016	Ultrasor	nic N	NDT principle	s, Different ty	pes of wave modes	s, Phys	sics of	f wave generation, reception,
inspection – thickness measurements – Applications. Module:7 Other Techniques: 5 Hour Holography and Acoustic emission technique. Pressure and leak testing. Condition monitoring of machines, Wear monitoring, Spark testing. Brief over view of Non- Destructive testing standards ASTM, ISO, ASNT, API, ASME boiler and pressure vessel code. Module:8 Contemporary issues: 2 Hour Module:8 Contemporary issues: 2 Hour Text Book(s) 1. B Hull, "Non-destructive testing", S.I. : Springer, 2012. 2. Ravi Prakash, "Non-Destructive Testing Techniques", Tunbridge Wells : New Academic Science, 2012. Reference Books 1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Editio New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016	interact	ions	and propagat	ion. Calibratio	on, data collection,	, quant	tificat	ion, and interpretation, New
Module:7 Other Techniques: 5 Hour Holography and Acoustic emission technique. Pressure and leak testing. Condition monitoring or machines, Wear monitoring, Spark testing. Brief over view of Non- Destructive testing standards ASTM, ISO, ASNT, API, ASME boiler and pressure vessel code. Module:8 Contemporary issues: 2 Hour Module:8 Contemporary issues: 2 Hour Total Lecture hours: Module:8 Contemporary issues: 45 Hour Text Book(s) 1. B Hull, "Non-destructive testing", S.I. : Springer, 2012. 45 Hour 2. Ravi Prakash, "Non-Destructive Testing Techniques", Tunbridge Wells : New Academic Science, 2012. 5 Reference Books 1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016	method	s us	ing guided v	waves, Resona	ance and other L	low F	reque	ncy Methods; Angle beam
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Holography and Acoustic emission technique. Pressure and leak testing. Condition monitoring of machines, Wear monitoring, Spark testing. Brief over view of Non- Destructive testing standards ASTM, ISO, ASNT, API, ASME boiler and pressure vessel code. Module:8 Contemporary issues: 2 Hour Total Lecture hours: 2 Hour Module:8 Contemporary issues: 2 Hour Total Lecture hours: 2 Hour Text Book(s) 1. B Hull, "Non-destructive testing", S.I. : Springer, 2012. 45 Hour 2. Ravi Prakash, "Non-Destructive Testing Techniques", Tunbridge Wells : New Academic Science, 2012. Science, 2012. Reference Books 1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Editio New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies		-		•				
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1. B Hull, "Non-destructive testing", S.l. : Springer, 2012. 2. Ravi Prakash, "Non-Destructive Testing Techniques", Tunbridge Wells : New Academic Science, 2012. Reference Books 1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Editio New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016					Total Lecture ho	ours:		45 Hours
 Ravi Prakash, "Non-Destructive Testing Techniques", Tunbridge Wells : New Academic Science, 2012. Reference Books Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Editio New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 								
Science, 2012. Reference Books 1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016	1.	BH	ull,"Non-dest	ructive testing ⁻	⁺ , S.l. : Springer, 20	012.		
Reference Books 1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016				on-Destructive	Testing Technique	es", Tu	unbrid	lge Wells : New Academic
1. Charles, J. Hellier, Handbook of Non destructive evaluation, McGraw Hill, New York 2013 2. Baldev Raj, T.Jayakumar, M.Thavasimuthu , Practical Non-Destructive Testing", Naros Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Editio New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016								
 Baldev Raj, T.Jayakumar, M.Thavasimuthu, Practical Non-Destructive Testing", Naros Publishing House, 2009. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016 	Referen	ce B	ooks					
Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition. New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016	1.	Char	rles, J. Hellier	, Handbook of	Non destructive e	valuati	ion, M	IcGraw Hill, New York 2013.
Publishing House, 2009. 3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition. New Jersey, 2005. Mode of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016		D 11		1 1 1	11 · (1 D	<u>/' 1</u>	NT	
3. Paul E Mix, Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition New Jersey, 2005. Node of Evaluation: CAT I & II – 30%, DA I & II – 20%, Quiz – 10%, FAT – 40% Recommended by Board of Studies 05/03/2016				•	navasimutnu , Pra	actical	Non	-Destructive Testing, Narosa
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Approved by Academic Council 40 th AC Date 18/03/2016	Recomm	nende	ed by Board o	f Studies	05/03/2016			
	Approve	d by	Academic Co	ouncil	40 th AC	Date	1	18/03/2016



EEE1018	(Deemed to be University under section 3 of U Nano Technology Fundamentals A		L	ΤP	J	С
EEEI010	Nano Technology Fundamentais A	nu its Applications			_	
D	DIN/1001		3			3
Pre-requisit			Sy	llabu	IS VO	ersion
Anti-requisi						v. 1.0
Course Obj						
	derstand the basic concepts involved in Nanosci		1 .	· .		•
-	in knowledge about various methods of synthes	sis, characterization ar	id app	licatio	ons	1n
	echnology.					
=	urse Outcomes:					
-	etion of this course the student will be able to:					
	stand the fundamental aspects of nanoscience	as and annliastions				
	fy various types of nanomaterials, their properti	es and applications				
	are the different nano fabrication processes esize and understand the properties & application	on of Carbon Nanotub	96			
	cterize nanoscale particles using various charac		68			
	stand the limitations of current technology and		oscale	electr	oni	C
devic			beure	01000	0111	•
	v nanotechnology in photonic devices					
11						
Module:1	Basic Concepts			8	Н	ours
Basic prope	ties of Conductors, Insulators and Semicond	uctors; Band diagran	n conc	ept o	of t	ypical
semiconduct	ors; Basic Chemistry Concepts; Physical a	spects, Bonding, W	ave-pa	rticle	d d	uality,
	Incertainty Principle, Schrödinger wave equation		-			•
-	of the nanometer length scale- Change in proper					
Module:2					<u> </u>	
	Nanomaterials					Hours
• 1	of Nanostructures- Quantum wells, Quantum W					Hours
Quantum Do	of Nanostructures- Quantum wells, Quantum W s, Nanoclusters; Nanoparticles- Colloidal nanop					Hours
Quantum Do nanoparticles	of Nanostructures- Quantum wells, Quantum W s, Nanoclusters; Nanoparticles- Colloidal nanop				es;	
Quantum Do nanoparticles Module:3	of Nanostructures- Quantum wells, Quantum W ts, Nanoclusters; Nanoparticles- Colloidal nanop Fabrication Methods	particle crystals, Funct	ionali	zed	es; 5 1	Hours
Quantum Do nanoparticles Module:3 Top-down pr	of Nanostructures- Quantum wells, Quantum W as, Nanoclusters; Nanoparticles- Colloidal nanop Fabrication Methods ocesses, Bottom-up processes, Nanolithography	techniques, Arc disc	ionali	zed	es; 5 1	Hours
Quantum Do nanoparticles Module:3 Top-down pr	of Nanostructures- Quantum wells, Quantum W ts, Nanoclusters; Nanoparticles- Colloidal nanop Fabrication Methods	techniques, Arc disc	ionali	zed	es; 5 1	Hours
Quantum Do nanoparticles Module:3 Top-down pr Ablaton met	of Nanostructures- Quantum wells, Quantum W ts, Nanoclusters; Nanoparticles- Colloidal nanop Fabrication Methods ocesses, Bottom-up processes, Nanolithography od, Ion Implantation, Chemical Vapour deposit	techniques, Arc disc	ionali	zed	es; 51 od, 1	Hours Laser
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Phot	tonic Cry	stals and their applications, F	Plasmonics, Near f	ield optics	s, Q-Dot Lasers
Moo	dule:8	Contemporary issues:			2 Hours
		ן	Fotal Lecture hou	irs:	45 Hours
Tex	t Book(s))			
1	Jeremy	J. Ramsden, Nanotechnology	y-An Introduction,	Second E	dition, Elseiver, 2016
2	Amreta	shis Sengupta , Chandan Kur	nar Sarkar (Eds.)	"Introduc	tion to Nano-Basics to
	Nanosc	ience and Nanotechnology",	Springer, 2015		
Refe	erence B	ooks			
1	Chri	s Binns , "Introduction to Na	noscience and Nat	notechnolo	ogy", Wiley, 2010
Mod	le of Eva	luation: CAT / Assignment /	Quiz / FAT / Proj	ect / Semi	nar
Reco	ommende	ed by Board of Studies	05/03/2016		
App	roved by	Academic Council	40 th AC	Date	18/03/2016



EEE1020	Engineering Optimization	L T P J C
		2 1 0 1 4
Pre-requisite	NIL	Syllabus version
Anti-requisit	e NIL	v. 1.1
Course Obje		
-	sure to and learning of engineering optimization concepts applied	d across the spectrum of
course	s in engineering curriculum	
Expected Co	ırse Outcome:	
	etion of each module the student will be able to:	
-	stand the basic concepts of engineering optimization	
	ze the 1- D search methods in optimization	
	gradient based optimization method for various algorithms	
4. Formu	late and analyze systems using conjugate direction methods	
	m and analyze dynamic optimization techniques	
	mathematics and science in engineering applications	
	stand genetic algorithm and PSO algorithm	
8. Design	a component or a product applying all the relevant standards wi	ith realistic constraints
Module:1	Classical Optimization basics	7 Hours
	s, Single-variable optimization, Multivariable optimization with	
	straints, Definitness of matrices, Sylvester's criterion, Convex p	
Module:2	1-D search methods	5 Hours
Golden Sectio	n Search, Fibonacci Search, Inexact line search.	
Module:3	Gradient based optimization	7 Hours
	ent method, method of steepest descent, Newton's Method, Leve	enberg-Marquardt
algorithm.		
Module:4	Conjugate Direction Methods:	7 Hours
Conjugate dire of all algorith	ections and conjugate gradient method, Fletcher-Reeves formula	a. Convergence analysis
of all algorith	115.	
Module:5	Miscellaneous topics	6 Hours
	ramming. Dynamic optimization. Sample applications of gradier	nt based and gradient free
methods in en		
Module:6	Application of optimization methods to neural networks	5 Hours
	pabilities and limitations of single perceptron, multilayer percept	tron. Training by gradient
based and grad	dient free methods.	
	Gradient-free Optimization	6 Hours
	irect methods, Limitations of gradient based methods, metaheur	
Introduction to	o the genetic algorithm, particle swarm optimization. Simulated a	annealing.
Module:8	Contemporary issues:	2 Hours
Text Book		
	luction to Optimization by Chong and Zak, John Wiley & Sons,	Inc., IV Ed., 2013.
B.TECH (EIE)		Page 116



Referen	nce Books			
1.	Engineering Optimization, Theo	ry and Practic	e by S S Ra	o, John Wiley & Sons, Inc., IV Ed.,
	2009.			
2.	Practical Methods of Optimization	on, by Fletche	er, John Wil	ley & Sons, Inc., II Ed., 2006
3.	Current literature.			
Mode o	f Evaluation: CAT / Assignment	Quiz / FAT	/ Project / Se	eminar
Recom	mended by Board of Studies	05/03/2016		
Approv	ed by Academic Council	40 th AC	Date	18/03/2016



EEE2006	Communication Engineering]	T	P J	C
			30	20	4
Pre-requisite	EEE1005	Syl	labu	s vers	ion
Anti-requisite	NIL			v.	2.0
Course Objectiv	es:				
fundamen 2. To teach t 3. To provid	he students various communication systems and its analysis & e basic understanding of appropriate tools and technologies to	applic	ation	_	
	ation-engineering solutions.				
Expected Course	n of this course the student will be able to:				
1	ate the need for modulation.				
	he presence of noise in communication systems.				
	nodulation techniques for analog and digital Signals.				
	nsmitters and receivers for communication systems				
	ious shift keying techniques.				
	ate spread spectrum techniques and channel assignment strate	nies			
	nd design modern communication systems.	gies.			
-	d Conduct experiments, as well as analyze and interpret data				
0. Design an	d Conduct experiments, as wen as analyze and interpret data				
Module:1 Int	roduction to Communication System			6 Ho	iirc
	ystems: Introduction, need, importance, elements, block diag	ram and	l role		
	iency ranges – bandwidth– pre-emphasis and de-emphasis –n				CII
	s of electronic communications.	louului	on a	nu no	
	se in CW Modulation System			4 Ho	ure
Internal noise – e	kternal noise – noise voltage – signal-to-noise ratio– noise fig	ure - nc	ise	4 110	uis
temperature_ nois	e in CW modulation systems.		150		
	plitude Modulation			8 Ho	urs
	d generation of analog modulation systems including AM, SS	B DSF	NS VS		uis
	m, power relation – different types of modulators – AM transr				nd
	tion – SSB transmitter – AM demodulators: Square-law detec				
	detector, synchronous detector – characteristics of receivers –				•
	per heterodyne receiver – SSB receiver – comparison of diffe	-		-	
	· · ·		~		
				10 Ho	urs
Module:4 Pha	se Modulation:				
Representation and NBFM and WBF conversion of FM	Ase Modulation: Ind generation of frequency and phase modulation (FM and M – FM transmitters – comparison of AM and FM – compari- to PM and PM to FM – TRF Receivers – Choice of IF and FM super heterodyne receiver– slope detectors – HF Comm n.	ison of oscillat	gene FM a or fre	eratior and Pl equen	M – cies
Representation an NBFM and WBF conversion of FM – AVC – AFC – diversity receptio	nd generation of frequency and phase modulation (FM and M – FM transmitters – comparison of AM and FM – comparison of PM and PM to FM – TRF Receivers – Choice of IF and FM super heterodyne receiver– slope detectors – HF Common.	ison of oscillat	gene FM a or fre	eration and Pl equent eceive	M – cies er –
Representation an NBFM and WBF conversion of FM – AVC – AFC – diversity receptio Module:5 Pul	nd generation of frequency and phase modulation (FM and M – FM transmitters – comparison of AM and FM – compar- to PM and PM to FM – TRF Receivers – Choice of IF and FM super heterodyne receiver– slope detectors – HF Comm n. se Modulation Systems	ison of oscillat unicati	gend FM a or fro on R	eration and Pl equent eceive 5 Ho	M – cies er – urs
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Module:7 Cellular concept 5 Hour Channel assignment strategies – interference and system capacity – spread spectrum modulation direct sequence spread spectrum – Frequency hop spread spectrum – code division multiplexing OFDM for wireless communication – Broadband integrated services network.
Channel assignment strategies – interference and system capacity – spread spectrum modulation direct sequence spread spectrum – Frequency hop spread spectrum – code division multiplexing
direct sequence spread spectrum - Frequency hop spread spectrum - code division multiplexing
OFDM for wireless communication – Broadband integrated services network.
Module:8Contemporary issues:2 Hour
Total Lecture hours: 45 Hour
Text Book(s)
1. Simon Haykin; Michael Moher, "An Introduction to Analog and Digital Communications.", Hoboken : Wiley Textbooks, 2012.
2. Leon W Couch, "Digital and analog communication systems", Upper Saddle River, N.J,
Prentice Hall, 2013
3. Rappaport T.S., "Wireless Communications", Pearson Education, 2010.
Reference Books
1. Herbert Taub; Donald L Schilling; Goutam Saha, "Principles of communication
systems", New Delhi : McGrew Hill Education, 2013.
2. Ramjee Prasad, "OFDM for wireless communications systems", Boston; London:
Artech House, 2004.
3. Wayne Tomasi, "Electronic Communication Systems – Fundamentals through
advanced", 4th edition, Pearson Education, 2005.
4. John G Proakis; Masoud Salehi, "Digital Communication", 5th edition, New Yor
McGraw-Hill 2014.
5. Kennedy and Davis, "Electronic Communication Systems", 4th edition, Tata McGraw Hil
2008.
Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar
List of Challenging Experiments (Indicative)
1. Amplitude Modulation 2 hours
2. Pre-Emphasis and De-Emphasis 2 hours
3. Pulse Amplitude Modulation 2 hours
4. Pulse Width Modulation 2 hours
5. Frequency Modulation/Mixer 2 hours
6. Generation of Shift Keying Methods 2 hours
7. DSB, SSB Modulation and Detection 2 hours
8. FM and PM Modulation and Detection 2 hours
9. Pulse Code Modulation and Delta Modulation 2 hours
10.Generation and Detection of spread spectrum2 hours
Total Laboratory Hours 30 hours
Recommended by Board of Studies 30/11/2015
Approved by Academic Council 39th AC Date 17/12/2015



EEE2008	Electrical Technology	L	Т	P	J	С
		3	0	2	0	4
Pre-requisite	EEE1002	S	Sylla	bus	vers	ion
Anti-requisite	NIL				v.	1.0
Course Objectives						
1. To analyze t	he basic working principle of DC Machines					
2. To understan	nd the various performance and testing of transformer					
3. Evaluate the	various characteristics of AC Machines and Special Machines	ines				
Expected Course (Outcome:					
On the completion	of this course the student will be able to:					
1. Understand	the constructional details and working principle of DC Ger	nerat	or			
2. Analyse and	evaluate the performance characteristics of DC motor					
	the theory and operation of transformer					
-	e equivalent circuit parameters of transformer					
•	working principle of synchronous generator					
	I the working principle of synchronous motor and application					
	the different types of induction motor and miscellaneous m	achi	nes			
8. Design and	Conduct experiments, as well as analyze and interpret data					
	enerators:	Б			Ho	
	ails of DC machines, Operation of DC generators	– E	MF	equ	ation	l —
	fferent types of generators.				TT	
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Finciple of operation	OII OI DC IIIOIOIS - IOIQUE alla speed equation - Chara					
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Mod	lule:8	Contemp	orary issues:					2 Hours
				Total Lecture h	ours:			45 Hours
List	of Chal	lenging Exp	oeriments (Indi	cative)				
1.	OCC o	f DC shunt g	generator					2 hours
2.	Load c	haracteristic	s of DC shunt g	enerator				2 hours
3.	Load te	est on DC co	mpound genera	itor				2 hours
4.	No loa	d saturation	characteristics of	of separately excit	ed DC g	generator		2 hours
5.	6					2 hours		
6.	Load c	haracteristic	s of DC separat	ely excited genera	ıtor			2 hours
7.	Load te	est on DC se	ries motor					2 hours
8.	Load te	est on DC sh	unt motor					2 hours
9.	Speed	control of D	C shunt motor					2 hours
10.	Swinbu	urne's Test						2 hours
11.	OC/SC	test on a sir	ngle phase trans	former				2 hours
12.	Load te	est on single	phase transform	ner				2 hours
13.	Paralle	l operation o	of single phase t	ransformer				2 hours
14.	Predete	ermination of	of percentage	regulation of alte	ernator	by synchrone	ous	2 hours
	impeda	nce method						
15.	Load te	est on three p	phase alternator	with resistive loa	d			2 hours
16.	Load te	est on three p	phase alternator	with RL load				2 hours
17.			phase Induction					2 hours
18.	Load te	est on three p	phase squirrel ca	age induction mot	or			2 hours
19.	Load te	est on three p	phase slip-ring i	nduction motor				2 hours
				Τ	'otal La	boratory Hou	urs 30	hours
Text	t Book(s							
1.	D.P	. Kothari an	d I.J. Nagrath, '	Electrical Machir	nes", Ta	ta McGraw-H	ill Educa	ation, 4th
		tion, 2014.						
2.		-	-	Debnath, "Elect	rical M	lachines", Ta	nta McC	braw-Hill
	Edu	cation, 2012						
	erence B							
1.			vanced Electric	al Technology",	CBS P	ublishers and	Distrib	utors, New.
		hi, 2001.					th	
				trical Machines",				
				A Text Book of E	lectrica	I Technology'	', S.Char	ıd, Vol. No.
		th Edition, 20					-	
	e of Eva			30%, DA I & II – 1	20%, Q	uiz – 10%, FA	T - 40%)
		ed by Board		05/03/2016	-			
Appı	roved by	Academic	Council	40 th AC	Date	18/03	3/2016	



EEE3008		_		_	
	Data Communication Network	L	T	P J	
		3	0	0 0	3
Pre-requisite	EEE2006	Sylla	bus		
Anti-requisite	NIL			v.	1.0
Course Objectiv					
	the basic fundamentals in network topology.				
-	le essential knowledge on various layer in OSI model	1			
_	e the students to the recent advances in various protocol in applic	cation la	yer.		
4. To teach	various networking.				
Expected Cours	e Outcome:				
	on of this course the student will be able to:				
-	nd the overview of a data communication and network.				
2. Analyze t	he bandwidth utilization and switching of data networks				
3. Understan	nd the protocol of seven layer model.				
	end and configure Local Area Networks				
	e various communication methods in transmission media.				
	nd the different coding methods to avoid error in communication	in data	link	laye	r.
	e the strategies for QoS network applications				
8. Apprecia	te usefulness and importance of application layer protocol in toda	ay life a	nd s	ociet	У
Module:1 O	verview of data communication:			4 Ho	iire
	ta Communications, Networks, The Internet, Protocols and	Standar		-	
	I Model, Layers in the OSI Model, TCP/IP Protocol Suite, A				
Layer and Media		luuressi	ng,	I II y S	icui
24)01 4110 1110 414	•				
Module:2 Ba	andwidth utilization and switching:			6 Ha	urs
	Indwidth utilization and switching: Spreading, Transmission Media Wireless, Switching - Circuit-	Switche	d N	6 Ho	
Multiplexing and	Spreading, Transmission Media Wireless. Switching - Circuit-	Switche	ed N		
Multiplexing and		Switche	d N		
Multiplexing and Datagram Netwo	Spreading, Transmission Media Wireless. Switching - Circuit-	Switche			rks,
Multiplexing and Datagram Netwo Module:3 Da	l Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch.			etwo 7 Ho	rks, ours
Multiplexing and Datagram Netwo Module:3 Da Error Detection	I Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch. ta Link Layer:	es, Che	cksi	etwo 7 H o 1m, I	rks, urs Data
Multiplexing and Datagram Netwo Module:3 Da Error Detection Link Control - F	I Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch. ta Link Layer: and Correction- Block Coding, Liner Block Codes, Cyclic Cod	es, Che	cksı .C,	fetwo 7 Ho 1m, I Point	rks, ours Data -to-
Multiplexing and Datagram Netwo Module:3 Da Error Detection Link Control - H Point Protocol,	I Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch. Ita Link Layer: and Correction- Block Coding, Liner Block Codes, Cyclic Cod Framing, Flow and Error Control, Protocols, Noiseless Channel	es, Che ls, HDL nanneliz	cksu .C, atio	fetwo 7 Ho 1m, I Point n, II	rks, ours Data -to- EEE
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Multiplexing and Datagram Netwo Module:3 Da Error Detection Link Control - H Point Protocol, Standards - Star 802.11, Bluetoot	I Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch. ta Link Layer: and Correction- Block Coding, Liner Block Codes, Cyclic Cod Framing, Flow and Error Control, Protocols, Noiseless Channel Multiple Access - Random Access, Controlled Access, Chander h	es, Che ls, HDL nanneliz	cksu .C, atio	fetwo 7 Ho 1m, I Point n, II et, II	rks, ours Data -to- EEE EEE
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Multiplexing and Datagram Netwo Module:3 Da Error Detection Error Detection Link Control - H Point Protocol, Standards - Stan 802.11, Bluetoot Module:4 Lo Connecting LAN Satellite Network	I Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch. ta Link Layer: and Correction- Block Coding, Liner Block Codes, Cyclic Cod Framing, Flow and Error Control, Protocols, Noiseless Channel Multiple Access - Random Access, Controlled Access, Chadard Ethernet, Changes in the Standard, Fast Ethernet, Giga h cal Area Network: s, Backbone Networks, and Virtual LANs, Connecting Devices, ts, Sonet/SDH, Architecture, STS Multiplexing, Sonet Networks, State S	es, Chea ls, HDL nanneliz abit Eth Cellular , Virtual	cksu C, atio ern	7 Ho um, I Point n, II et, II 6 Ho	rks, urs Data -to- EEE EEE EEE urs
Multiplexing and Datagram Netwo Module:3 Da Error Detection Error Detection Link Control - H Point Protocol, Standards - Stan 802.11, Bluetoot Module:4 Lo Connecting LAN Satellite Network	I Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch. ta Link Layer: and Correction- Block Coding, Liner Block Codes, Cyclic Cod Framing, Flow and Error Control, Protocols, Noiseless Channel Multiple Access - Random Access, Controlled Access, Cr ndard Ethernet, Changes in the Standard, Fast Ethernet, Gigan h Ocal Area Network: s, Backbone Networks, and Virtual LANs, Connecting Devices,	es, Chea ls, HDL nanneliz abit Eth Cellular , Virtual	cksu C, atio ern	7 Ho um, I Point n, II et, II 6 Ho	rks, urs Data -to- EEE EEE EEE urs
MultiplexingandDatagram NetwoModule:3DaError DetectionLink Control - HPoint Protocol,Standards - Stan802.11, BluetottModule:4LoConnecting LANSatellite NetworkVirtual-Circuit NModule:5Ne	I Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch. ta Link Layer: and Correction- Block Coding, Liner Block Codes, Cyclic Cod Framing, Flow and Error Control, Protocols, Noiseless Channel Multiple Access - Random Access, Controlled Access, Chandard Ethernet, Changes in the Standard, Fast Ethernet, Gigan bcal Area Network: s, Backbone Networks, and Virtual LANs, Connecting Devices, teworks: Frame Relay and ATM, Frame Relay, ATM, ATM LAI twork Layer:	es, Chea ls, HDL nanneliz abit Eth Cellular , Virtual Ns.	cksu C, atio ern r Te	7 Ho 1 m, I Point n, I et, I 6 Ho butan 6 Ho	rks, urs Data -to- EEE EEE Durs Dny, iies, urs
Multiplexing and Datagram Network Module:3 Da Error Detection Image: Construction of the second sec	I Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch. ta Link Layer: and Correction- Block Coding, Liner Block Codes, Cyclic Cod Framing, Flow and Error Control, Protocols, Noiseless Channel Multiple Access - Random Access, Controlled Access, Cr ndard Ethernet, Changes in the Standard, Fast Ethernet, Giga nd ocal Area Network: s, Backbone Networks, and Virtual LANs, Connecting Devices, as, Sonet/SDH, Architecture, STS Multiplexing, Sonet Networks, etworks: Frame Relay and ATM, Frame Relay, ATM, ATM LAX twork Layer: Internet Protocol, Internetworking, IPv4, IPv6, Transition f	es, Chea ls, HDL nanneliz abit Eth Cellular , Virtual Ns.	cksu C, atio ern r Te	fetwo 7 Ho 1m, I Point n, II et, II 6 Ho butan 6 Ho butan	rks, ours Data -to- EEE EEE ony, ies, ours Pv6,
Multiplexing and Datagram Netwo Module:3 Da Error Detection Error Detection Link Control - H Point Protocol, Standards - Star 802.11, Bluetoot Module:4 Loc Connecting LAN Satellite Network Virtual-Circuit N Network Layer: Address Mappin Address Mappin	I Spreading, Transmission Media Wireless. Switching - Circuit- rks, Virtual-Circuit Networks, Structure of a Switch. ta Link Layer: and Correction- Block Coding, Liner Block Codes, Cyclic Cod Framing, Flow and Error Control, Protocols, Noiseless Channel Multiple Access - Random Access, Controlled Access, Chandard Ethernet, Changes in the Standard, Fast Ethernet, Gigan bcal Area Network: s, Backbone Networks, and Virtual LANs, Connecting Devices, teworks: Frame Relay and ATM, Frame Relay, ATM, ATM LAI twork Layer:	es, Chea ls, HDL nanneliz abit Eth Cellular , Virtual Ns.	cksu C, atio ern r Te	fetwo 7 Ho 1m, I Point n, II et, II 6 Ho butan 6 Ho butan	rks, ours Data -to- EEE EEE ony, ies, ours Pv6,



Module:6	Transport Layer:	6 Hours
Process-Proc	ess Delivery: UDP, TCP and SCTP, Process-to	-Process Delivery, User Datagram
Protocol (UI	DP), TCP, SCTP, Congestion Control and Quality of	f Service, Data Traffic, Congestion,
Congestion (Control, Quality Service, Techniques to improve Qos	S, Integrated Services, Differentiated
Services, Qo	S in Switched Networks.	_
Module:7	Application Layer:	8 Hours
Domain Nar	ne System - Name Space, Domain Name Space, Dist	ribution of Name Space, DNS in the
	olution, DNS Messages, Types of Records, Registra	
	capsulation, Remote Logging, Electronic Mail ar	d File Transfer, Remote Logging,
	ronic Mail, File Transfer.	
WWW and		
	, Web Documents, HTTP, Network Manageme ple Network Management Protocol (SNMP), Multi	
•	ideo Compression, Streaming Stored Audio/Video,	
	tive Audio/Video, RTP, RTCP, Voice over IP.	Streaming Live Audio/ video, Kear-
Thie interac		
Module:8	Contemporary issues:	2 Hours
	Total Lecture hours:	45 Hours
		ie mourb
Text Book(s)	
1.Behrouz A) . Forouzan, "Data Communications and Networking"	', McGraw Hill, Fifth Edition, 2017.
1.Behrouz A)	', McGraw Hill, Fifth Edition, 2017.
1.Behrouz A) . Forouzan, "Data Communications and Networking nbaum, "Computer Networks", Pearson education, 5	', McGraw Hill, Fifth Edition, 2017.
1.Behrouz A 2.A. S. Taner Reference B) . Forouzan, "Data Communications and Networking nbaum, "Computer Networks", Pearson education, 5 ooks	', McGraw Hill, Fifth Edition, 2017. h Edition, 2013.
1.Behrouz A 2.A. S. Tanez Reference B 1. W. T) . Forouzan, "Data Communications and Networking nbaum, "Computer Networks", Pearson education, 5	', McGraw Hill, Fifth Edition, 2017. h Edition, 2013.
1.Behrouz A 2.A. S. Tanes Reference B 1. W. T 4thEc) . Forouzan, "Data Communications and Networking hbaum, "Computer Networks", Pearson education, 5 ooks Comasi, "Introduction to Data communications an	', McGraw Hill, Fifth Edition, 2017. h Edition, 2013. d Networking", Pearson education,
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1.Behrouz A 2.A. S. Tane Reference B 1. W. T 4thEo 2. G.S.H 3. S.Kee 2ndE 4. W.A.) Forouzan, "Data Communications and Networking hbaum, "Computer Networks", Pearson education, 5 ooks ooks oomasi, "Introduction to Data communications an lition, 2005. Hura and M.Singhal, "Data and Computer Communic shav, "An Engineering Approach to Computer dition, 2010. Shay,"Understanding communications and Networ	', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. d Networking", Pearson education, cations", CRC Press, 2001. r Networks", Pearson Education, tks",Cengage Learning,3rd Edition,
1.Behrouz A 2.A. S. Tane Reference B 1. W. T 4thEo 2. G.S.H 3. S.Kes 2ndE 4. W.A. 2008 Mode of valu) Forouzan, "Data Communications and Networking abaum, "Computer Networks", Pearson education, 5 ooks Tomasi, "Introduction to Data communications an lition, 2005. Hura and M.Singhal, "Data and Computer Communic shav, "An Engineering Approach to Computer dition, 2010. Shay,"Understanding communications and Networ	', McGraw Hill, Fifth Edition, 2017. th Edition, 2013. d Networking", Pearson education, cations", CRC Press, 2001. r Networks", Pearson Education, tks",Cengage Learning,3rd Edition,



EEE3009	Digital Image Processing	g L T P J C
		3 0 0 4 4
Pre-requisite	EEE2005	Syllabus versior
Anti-requisite	NIL	v. 2.1
Course Objective	s:	
associated	p student's skills in performing spatial and with image processing and skills associated wit complex algorithms and to reinstate sophis	th techniques related to coding.
±.		
Expected Course	ion of this course the student will be able to:	
-	I the fundamentals of digital image processing	
	e various image transform techniques	
•	frequency domain in image enhancement	
-	nd the image compression techniques	
-	e images using various segmentation techniques	5
•	and describe the image processing techniques	
-	mage processing techniques in various application	ions
-	omponent or a product applying all the relevant	standards with realistic
constraints		
Basics of Digital Introduction, Fun Acquisition – Ima	Image Processing (DIP): damental steps in DIP – Elements of visu- ge Sampling and Quantization – Imaging geo	metry, discrete image mathematical
Basics of Digital Introduction, Fun Acquisition – Ima characterization- I Processing – Smo	damental steps in DIP - Elements of visu	al perception -Image sensing and metry, discrete image mathematica level Transformations – Histogram
Introduction, Fun Acquisition – Ima characterization- I Processing – Smo	damental steps in DIP – Elements of visu- ge Sampling and Quantization – Imaging geo Basic relationship between pixels. Basic Gray pothing spatial filters- Sharpening spatial filt	al perception -Image sensing and metry, discrete image mathematica level Transformations – Histogram
Basics of Digital Introduction, Fun Acquisition – Ima characterization- I Processing – Smo models-pseudo col	damental steps in DIP – Elements of visu- ge Sampling and Quantization – Imaging geo Basic relationship between pixels. Basic Gray pothing spatial filters- Sharpening spatial filt for image processing- color transformations.	al perception -Image sensing and metry, discrete image mathematica level Transformations – Histogram ters -color Image Processing-Color
Basics of Digital I Introduction, Fun Acquisition – Ima characterization- I Processing – Smo models-pseudo col Module:2 Image Transform	damental steps in DIP – Elements of visu- ge Sampling and Quantization – Imaging geo Basic relationship between pixels. Basic Gray pothing spatial filters- Sharpening spatial filt for image processing- color transformations.	al perception -Image sensing and metry, discrete image mathematical level Transformations – Histogram ters -color Image Processing-Color 10 Hours
Basics of Digital T Introduction, Fun Acquisition – Ima characterization- I Processing – Smo models-pseudo col Module:2 Image Transform Two dimensional	damental steps in DIP – Elements of visu- ge Sampling and Quantization – Imaging geo Basic relationship between pixels. Basic Gray bothing spatial filters- Sharpening spatial filt for image processing- color transformations.	al perception -Image sensing and metry, discrete image mathematica level Transformations – Histogram ters -color Image Processing-Color 10 Hours Transform – Inverse FFT- Discrete
Basics of Digital I Introduction, Fun Acquisition – Ima characterization- I Processing – Smo models-pseudo col Module:2 Image Transform Two dimensional cosine transform Transform- the	damental steps in DIP – Elements of visu ge Sampling and Quantization – Imaging geo Basic relationship between pixels. Basic Gray pothing spatial filters- Sharpening spatial filt for image processing- color transformations. Is: Fourier Transform- Properties – Fast Fourier and KL transformDiscrete Short time Fou Haar wavelet family-Multirate solution an	al perception -Image sensing and metry, discrete image mathematica level Transformations – Histogram ters -color Image Processing-Color 10 Hours Transform – Inverse FFT- Discrete urier Transform. Discrete Wavele
Basics of Digital Introduction, Fun Acquisition – Ima characterization- I Processing – Smo models-pseudo col Module:2 Image Transform Two dimensional cosine transform Transform Transform The Implementation us	damental steps in DIP – Elements of visu ge Sampling and Quantization – Imaging geo Basic relationship between pixels. Basic Gray pothing spatial filters- Sharpening spatial filt for image processing- color transformations. Is: Fourier Transform- Properties – Fast Fourier and KL transformDiscrete Short time Fou Haar wavelet family-Multirate solution an	al perception -Image sensing and metry, discrete image mathematica level Transformations – Histogram ters -color Image Processing-Color 10 Hours Transform – Inverse FFT- Discrete urier Transform. Discrete Waveler alysis and the scaling function
Basics of Digital 2Introduction, FunAcquisition – Imacharacterization- IProcessing – Smemodels-pseudo colModule:2Image TransformTwo dimensionalcosine transformTransform- theImplementation usModule:3	damental steps in DIP – Elements of visu ge Sampling and Quantization – Imaging geo Basic relationship between pixels. Basic Gray bothing spatial filters- Sharpening spatial filt for image processing- color transformations. Is: Fourier Transform- Properties – Fast Fourier and KL transformDiscrete Short time Fou Haar wavelet family-Multirate solution an ing filters.	al perception -Image sensing and metry, discrete image mathematica level Transformations – Histogram ters -color Image Processing-Color 10 Hours Transform – Inverse FFT- Discrete urier Transform. Discrete Wavele
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Image Segmentation:

Detection of discontinuities – edge linking and boundary detection- thresholding -edge based segmentation-region based segmentation- matching-morphological segmentation- watershed algorithm

Module:6

Representation and Description:

Boundary descriptions-Region descriptors- Use of Principal Components and Description, Texture description.

Module:7

Applications of Image Processing:

Machine Vision- Image Analysis-pattern recognition and introduction to video processing

Modul	e:8	Contemporary issues:			2 Hours
			Total Lecture ho	ours:	45 Hours
Text B	ook(s)		1	
1.		el C.Gonzalez, Richard E.Wo on, 2017.	oods, "Digital Ima	ge Process	sing", Pearson Education 4th
2.	Anil	K.Jain, "Fundamentals of Di	gital Image Proces	ssing", Pea	arson Education, 2000.
Refere	nce B	ooks			
1.					uman and Computer Vision aylor and Francis, 2 nd Edition,
2.	Willi	am K. Pratt, "Digital Image F	Processing", John	Wiley & S	Sons, 2016.
3.	Stepl	nane Mallat , "A Wavelet tour lemic Press, 2009.			
4.		Nixon, Alberto Aguado, "Fe chnology Publicatiton, Secon		and Image	Processing", Elsevier's Science
5.	K.P.S	Soman, K.I Ramchandran, N. ice", Third Edition, PHI, 201	G.Resmi, "Insight	s into Wa	velets: From Theory to
6.		anda,D.DuttaMajumder, "Dig , 2011	gital Image Proces	sing and A	Analysis", Prentice Hall of
Mode of	of Eva	luation: CAT / Assignment /	Quiz / FAT / Proje	ect / Semin	nar
Recom	mende	ed by Board of Studies	05/03/2016		
Approv	ved by	Academic Council	40 th AC	Date	18/03/2016

3 Hours

3 Hours



EEE4018		Advanced Control Theory	L	T P J C
		v	3	0 0 4 4
Pre-requisite	e	EEE 3001	-	bus version
Anti-requisit		NIL	J	v. 2.0
Course Obje				
v		pth knowledge in the field of control theory, analysis and desi	ign of [MIMO
systems i			U	
2. Basic un	derstan	ding on features of linear and nonlinear systems		
3. To analy	yze the f	features of linear and nonlinear systems using phase plane ana	alysis a	and
describin	ig functi	ion analysis		
4. To analy	yze the s	stability of linear and nonlinear systems using stability concep	ots	
Expected Co	urse Ou	utcome:		
On the compl	letion of	f this course the student will be able to:		
1. Mode	el physic	cal systems using state variable approach		
2. Analy	yze MIN	MO systems by state space approach		
0		eedback controller and observer for simple and practical dyna	amic s	ystems
	•	classify the nonlinearities in the physical systems		
		features and stability of nonlinear systems using phase portrai		
		systems with common nonlinearities using describing function	n	
		ility of linear and non – linear systems		
	-	nponent or a product applying all the relevant standards with r	realisti	ic
constr	aints			
		Variable Representation		6 Hours
		ot of State Equation for Dynamic Systems, Non Uniquenes		
-				
1. 1. 11		nysical Systems and State Assignments - State space	repres	sentation of
multivariable	system	s	repres	
Module:2	system: Solutio	s on Of State Equations		6 Hours
Module:2 State transit	systems Solutionion ma	s on Of State Equations atrix – Properties and Computation. Controllability at		6 Hours
Module:2 State transiti Stabilizability	systems Solution ion may and De	s on Of State Equations atrix – Properties and Computation. Controllability at etectability.		6 Hours bservability,
Module:2 State transiti Stabilizability Module:3	Solution Solution ion ma y and De Design	s on Of State Equations atrix – Properties and Computation. Controllability at etectability. In State Space	ind O	6 Hours bservability, 7 Hours
Module:2StateStabilizabilityModule:3StateFeedbace	systems Solutio ion ma y and De Design ck, Out	s on Of State Equations atrix – Properties and Computation. Controllability at etectability. In State Space tput Feedback, Design Methods, Pole Assignment, Full O	ind O	6 Hours bservability, 7 Hours
Module:2StateStabilizabilityModule:3StateFeedbace	systems Solutio ion ma y and De Design ck, Out	s on Of State Equations atrix – Properties and Computation. Controllability at etectability. In State Space	ind O	6 Hours bservability, 7 Hours
Module:2 State transiti Stabilizability Module:3 State Feedbar Order Observ	Solution Solution ion ma y and De Design ck, Out vers. Intr	s on Of State Equations atrix – Properties and Computation. Controllability at etectability. In State Space tput Feedback, Design Methods, Pole Assignment, Full Or roduction to Linear Quadratic problems.	ind O	6 Hours bservability, 7 Hours
Module:2 State transiti Stabilizability Module:3 State Feedbac Order Observ Module:4	systems Solutic ion ma y and De Design ck, Out vers. Intr Introd	s on Of State Equations atrix – Properties and Computation. Controllability at etectability. In State Space tput Feedback, Design Methods, Pole Assignment, Full Or roduction to Linear Quadratic problems. uction To Non Linear Sytems	ind O	6 Hours bservability, 7 Hours nd Reduced 5 Hours
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Module:2 State transit: Stabilizability Module:3 State Feedbar Order Observ Module:4 Introduction, nonlinearities Limit cycles Module:5 Construction system and no Module:6 Describing fu	systems Solutic ion ma y and De Design ck, Out vers. Intr Introd Feature in cont PHAS of phas onlinear Descrii unction ysis of r	s on Of State Equations atrix – Properties and Computation. Controllability at etectability. In State Space tput Feedback, Design Methods, Pole Assignment, Full Or roduction to Linear Quadratic problems. uction To Non Linear Sytems es of Linear and Non Linear Systems, Types of non-line rol systems, Typical Examples , Concept of phase portraits - E PLANE ANALYSIS se portrait, Concepts of phase plane analysis Phase plane system, Existence of limit cycles. bing Function Analysis fundamentals, Describing functions of common nonlinear	nd O order a nearity – Sing analys	6 Hours bservability, 7 Hours nd Reduced 5 Hours , Common ular points – 7 Hours sis of linear 6 Hours
Module:2 State transit: Stabilizability Module:3 State Feedbar Order Observ Module:4 Introduction, nonlinearities Limit cycles Module:5 Construction system and no Module:6 Describing fu function analy	Systems Solution ion ma y and De Design ck, Out vers. Intr Introd Feature in cont PHAS of phas onlinear Descrii unction ysis of r	s on Of State Equations atrix – Properties and Computation. Controllability at etectability. In State Space tput Feedback, Design Methods, Pole Assignment, Full Or roduction to Linear Quadratic problems. Uction To Non Linear Sytems es of Linear and Non Linear Systems, Types of non-lin rrol systems, Typical Examples , Concept of phase portraits - E PLANE ANALYSIS se portrait, Concepts of phase plane analysis Phase plane system, Existence of limit cycles. bing Function Analysis fundamentals, Describing functions of common nonlinear nonlinear systems, Limit cycles , Stability of Oscillations	order a prder a nearity – Sing analys	6 Hours bservability, 7 Hours nd Reduced 5 Hours 5 Hours , Common ular points – 7 Hours sis of linear 6 Hours Describing 6 Hours



Lyapun	ov's I	Direct method, Variable grad	lient method Freq	uency Don	nain Stability Criteria, Popov's	
Method	& its	Extension.	-	-		
Module	Module:8 Contemporal				2 Hours	
		- · · · · · · · · · · · · · · · · · · ·	Fotal Lecture ho	urs:	45 Hours	
Text Bo	ook(s)					
1.	Kats	uhiko Ogata, "Modern Cont	rol Engineering ",	PHI Learn	ing Pvt Ltd, 5 th Edition, 2010.	
2.	Hass	an K Khalil, "Nonlinear Co	ntrol ", Pearson Pr	entice Hall	$1, 1^{st}$ Edition, 2014.	
Referen	nce Bo	ooks				
1.	М. С	Jopal, "Modern Control Syst	ems Theory", Nev	v Age Pub	lishers, 3 rd Edition, 2014.	
2.	Rich	ard C. Dorf, Robert H. Bish	op, "Modern Cont	trol System	ns", Prentice Hall, 12 th Edition,	
	2010					
Mode o	Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar					
Recom	nende	d by Board of Studies	05/03/2016			
Approv	ed by	Academic Council	40 th AC	Date	18/03/2016	



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EEE4019	Advanced Digital Design with FPGAs	L	Τ	Р	J	С
		2	0	0	4	3
Pre-requisite	EEE3002	Syl	labu	IS V		
Anti-requisite	NIL				v. 1	0.
Course Objectives:						
-	x digital systems using Hardware Description L					. d
1	rogrammable gate array (FPGA) technologies a $array (CAD)$ tools to symptocize and analyze dia				ciat	ea
Expected Course Outco	esign (CAD) tools to synthesize and analyze dig	ital sys	sterns	5.		
	s course the student will be able to:					
	nize the trade-offs involved in digital design flo	ws for	svste	m		
2. Compile and synt	• •	w 3 101	syste	/111		
	hesize digital modules and circuits for a wide ap	plicatio	on ra	nge		
	nines to control complex systems.	pnoun	011 10		•	
e	st bench to test Verilog modules.					
•	ous DSP system in Verilog and verify its perfor	mance.				
•	point arithmetic using the IEEE-754 Standard.					
8. Design a compone	ent or a product applying all the relevant standar	rds witl	h rea	listi	С	
constraints						
Madula 1	Introduction to EDCAs			21	Tar	
	Introduction to FPGAs gic architectures, Complex Programmable Log	ic Davi	ices			
0	e Arrays (FPGAs), Design Flow, Design Tools.		ices	(Cr	LD	5),
	Anays (11 OAS), Design 110w, Design 1001s.					
	Introduction to Verilog HDL				Hou	
	, Modeling styles: Behavioral, Dataflow, and	Structu	ral N	Mod	lelin	ıg,
gate delays switch-level						
Succession, Switch-iever	Modeling, Hierarchal structural modeling.					
		nal		41	Hou	re
Module:3	Implementing Logic using MSI Combination	nal		4]	Hou	Irs
Module:3	Implementing Logic using MSI Combination Logic Blocks	nal		4]	Hou	rs
Module:3 Multiplexer, DeMultiplex	Implementing Logic using MSI Combination Logic Blocks ker, Encoder, Decoder, ROM, PAL, PLA.	nal				
Module:3 Multiplexer, DeMultiplex Module:4	Implementing Logic using MSI Combination Logic Blocks ker, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits	nal			Hou Hou	
Module:3 Multiplexer, DeMultiplex Module:4 Flip-Flops, Shift Register	Implementing Logic using MSI Combination Logic Blocks eer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling.	nal		4]	Hou	Irs
Module:3Multiplexer, DeMultiplexModule:4Flip-Flops, Shift RegisterModule:5	Implementing Logic using MSI Combination Logic Blocks ker, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling. Verification			4]	Hou Hou	irs
Module:3Multiplexer, DeMultiplexModule:4Flip-Flops, Shift RegisterModule:5Functional verification,	Implementing Logic using MSI Combination Logic Blocks eer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling.		dum	4]	Hou Hou	irs
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Module:3Multiplexer, DeMultiplexModule:4Flip-Flops, Shift RegisterModule:5Functional verification, files.Module:6	Implementing Logic using MSI Combination Logic Blocks xer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling. Verification simulation types, Test Bench design, value c Design	hange		4] 3] ap (6]	Hou Hou VC	urs urs D)
Module:3Multiplexer, DeMultiplexModule:4Flip-Flops, Shift RegisterModule:5Functional verification, files.Module:6Adders and Substractors	Implementing Logic using MSI Combination Logic Blocks xer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling. Verification simulation types, Test Bench design, value c Design a, Multiplication Digital Signal Processing module	hange iles: FI	R an	4] 3] ap (6]	Hou Hou VC	urs urs D)
Module:3Multiplexer, DeMultiplexModule:4Flip-Flops, Shift RegisterModule:5Functional verification, files.Module:6Adders and SubstractorsFilters, Bus structures, S	Implementing Logic using MSI Combination Logic Blocks Exer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits Exer, Counters, Finite State Machine Modelling. State State Machine Modelling. Exercise State Machine Modelling. Verification Implement of the state Machine Modelling. Simulation types, Test Bench design, value complexity Implement of the state Machine Modelling. Multiplication Digital Signal Processing moduly Implement of the state Machine Modelling.	hange iles: FI	R an	4] 3] ap (6]	Hou Hou VC	urs urs D)
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Module:3 Multiplexer, DeMultiplex Module:4 Flip-Flops, Shift Register Module:5 Functional verification, files. Module:6 Adders and Substractors Filters, Bus structures, S rate generator, A simple	Implementing Logic using MSI Combination Logic Blocks xer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling. Verification simulation types, Test Bench design, value c Design a, Multiplication Digital Signal Processing modu aynchronous & Asynchronous data transfer, UA CPU design.	hange iles: FI	R an	4] 3] ap (6] d II	Hou Hou VC	Urs Urs D)
Module:3 Multiplexer, DeMultiplex Module:4 Flip-Flops, Shift Register Module:5 Functional verification, files. Module:6 Adders and Substractors Filters, Bus structures, S rate generator, A simple Module:7	Implementing Logic using MSI Combination Logic Blocks xer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling. Verification simulation types, Test Bench design, value c Design Gynchronous & Asynchronous data transfer, UA CPU design. Floating point arithmetic circuits	hange iles: FI	R an	4] 3] ap (6] d II	Hou Hou VC	Urs Urs D)
Module:3Multiplexer, DeMultiplexModule:4Flip-Flops, Shift RegisterModule:5Functional verification, files.Module:6Adders and SubstractorsFilters, Bus structures, Srate generator, A simple	Implementing Logic using MSI Combination Logic Blocks xer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling. Verification simulation types, Test Bench design, value c Design Gynchronous & Asynchronous data transfer, UA CPU design. Floating point arithmetic circuits	hange iles: FI	R an	4] 3] ap (6] d II	Hou Hou VC	Urs Urs D)
Module:3 Multiplexer, DeMultiplex Module:4 Flip-Flops, Shift Register Module:5 Functional verification, files. Module:6 Adders and Substractors Filters, Bus structures, S rate generator, A simple Module:7 Adders, Subtractors, Mul	Implementing Logic using MSI Combination Logic Blocks xer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling. Verification simulation types, Test Bench design, value c Design	hange iles: FI	R an	4] 3] ap (6] d II	Hou Hou R Hou	Irs D) Irs
Module:3 Multiplexer, DeMultiplex Module:4 Flip-Flops, Shift Register Module:5 Functional verification, files. Module:6 Adders and Substractors Filters, Bus structures, S rate generator, A simple Module:7	Implementing Logic using MSI Combination Logic Blocks xer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling. Verification simulation types, Test Bench design, value c Design	hange iles: FI	R an 1d	4 1 3 1 10 (6 1 d 11 3 1 2 1	Hou Hou R Hou Hou	Irs D) Irs Irs
Module:3 Multiplexer, DeMultiplex Module:4 Flip-Flops, Shift Register Module:5 Functional verification, files. Module:6 Adders and Substractors Filters, Bus structures, S rate generator, A simple Module:7 Adders, Subtractors, Multiplex	Implementing Logic using MSI Combination Logic Blocks xer, Encoder, Decoder, ROM, PAL, PLA. Verilog Modelling of Sequential Circuits rs, Counters, Finite State Machine Modelling. Verification simulation types, Test Bench design, value c Design	hange iles: FI	R an 1d	4 1 3 1 10 (6 1 d 11 3 1 2 1	Hou Hou R Hou	Irs D) Irs Irs



- Michael D Ciletti, "Advanced Digital Design with the Verilog HDL" Prentice Hall, 2nd Edition, 2011.
- 2. Samir Palnitkar, "Verilog HDL: A Guide to Digital Design and Synthesis" Pearson, Second Edition, 2009.

Reference Books

- 1. Stephen Brown & Zvonko Vranesic, "Fundamentals of digital Logic with Verilog Design" TATA Mc Graw Hill Ltd. 3rd Edition 2014.
- 2. Ming-Bo Lin., Digital System Designs and Practices Using Verilog HDL and FPGAs. Wiley, 2008.
- 3. Woods, R., McAllister, J., Yi, Y. and Lightbody, G. FPGA-based implementation of signal processing systems. John Wiley & Sons, 2017.

Mode of Evaluation: CAT / Assignment / Quiz / FAT / Project / Seminar

Recommended by Board of Studies	05/03/2016		
Approved by Academic Council	40 th AC	Date	18/03/2016



EEE4020	Embedded System Design	L T P J C
Pre-requisite	EEE4001	Syllabus version
Anti-requisite	NIL	v. 1.0
Course Objectives:		
	nasis on the characteristics and hardware architecture	of embedded system and
real time operation		Ş
1	ential knowledge on various communication protoco	ls and understanding of
Mealy and Moor	e machines.	
-	essential knowledge in the embedded modeling an	d design of finite state
machines.		
Expected Course C)utcome:	
-	of this course the student will be able to:	
_	characteristics and concepts of embedded system.	
	architecture of hardware embedded system	
3. Compare the co	oncepts of RTOS with general purpose OS.	
	re components/architecture for embedded system applic	cations.
	red and wireless communication protocols.	
	ace model using Moore and Mealy technique	-
•	bedded system modelling with state transition and FSM	
8. Design a compo	onent or a product applying all the relevant standards w	ith realistic constraints
Module:1 Intro	duction to Embedded systems:	3 Hours
Embedded system-	Definition, Categories, Requirements. Challenges	and issues in embedded
software developm	ent, Trends in embedded software development, Ap	oplications of embedded
systems.		
Module:2 Hard	ware architecture of embedded system:	4 Hours
	, Memory models, Latches and Buffers, crystal, Timers	
•		s reset circuit watchdog
		-
· •	logic circuit, ADC and DAC, Display units, Co	-
Introduction to emu	logic circuit, ADC and DAC, Display units, Co lators.	-
Introduction to emu Module:3 Real	logic circuit, ADC and DAC, Display units, Co lators. time operating system (RTOS) with Kernel:	ommunication interfaces, 4 Hours
Introduction to emu Module:3 Real RTOS vs General p	logic circuit, ADC and DAC, Display units, Co lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities - Ta	ommunication interfaces, 4 Hours ask management, Process
Introduction to emuModule:3RealRTOS vs General pScheduling, Resourt	logic circuit, ADC and DAC, Display units, Co lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities - Ta rce management (Semaphores and Mutex), Task Syn	ommunication interfaces, 4 Hours ask management, Process
Introduction to emuModule:3RealRTOS vs General pScheduling, Resoursoftware developme	logic circuit, ADC and DAC, Display units, Co lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities - Ta rce management (Semaphores and Mutex), Task Syn ent Life cycle.	mmunication interfaces, 4 Hours ask management, Process achronization. Embedded
Introduction to emu Module:3 Real RTOS vs General p Scheduling, Resourd software developme Module:4 Serial	logic circuit, ADC and DAC, Display units, Co lators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities - Ta rce management (Semaphores and Mutex), Task Syn ent Life cycle. I Bus for embedded systems:	A Hours ask management, Process achronization. Embedded 5 Hours
Introduction to emu Module:3 Real RTOS vs General p Scheduling, Resour software developme Module:4 Seria I2C- Features, Arbi	logic circuit, ADC and DAC, Display units, Collators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities - Take tree management (Semaphores and Mutex), Task Synemt Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CAN-	A Hours ask management, Process achronization. Embedded 5 Hours - Layered Architecture of
Introduction to emu Module:3 Real RTOS vs General p Scheduling, Resour software developme Module:4 Seria I2C- Features, Arbi CAN, properties, D	logic circuit, ADC and DAC, Display units, Colators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities - Take arce management (Semaphores and Mutex), Task Synemt Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CAN- ata Rates, Frame types. USB- Physical interface, Enur	A Hours ask management, Process achronization. Embedded 5 Hours - Layered Architecture of
Introduction to emu Module:3 Real RTOS vs General p Scheduling, Resour software developme Module:4 Seria I2C- Features, Arbi	logic circuit, ADC and DAC, Display units, Colators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities - Take arce management (Semaphores and Mutex), Task Synemt Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CAN- ata Rates, Frame types. USB- Physical interface, Enur	A Hours ask management, Process achronization. Embedded 5 Hours - Layered Architecture of
Introduction to emu Module:3 Real RTOS vs General p Scheduling, Resour software developme Module:4 Seria I2C- Features, Arbi CAN, properties, D Types of packets, T	logic circuit, ADC and DAC, Display units, Colators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities - Take management (Semaphores and Mutex), Task Synent Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CANata Rates, Frame types. USB- Physical interface, Enury systems	A Hours ask management, Process achronization. Embedded 5 Hours Layered Architecture of neration process in USB,
Introduction to emuModule:3RealRTOS vs Ge−eral pScheduling, Resoursoftware developmeModule:4SeriaI2C- Features, ArbiCAN, properties, DTypes of packets, TModule:5Wire	logic circuit, ADC and DAC, Display units, Colators.time operating system (RTOS) with Kernel:urpose OS, Kernel Architecture and Functionalities - Take rce management (Semaphores and Mutex), Task Syment Life cycle.I Bus for embedded systems:tration, Bit Transfer Waveform and exceptions. CAN- ata Rates, Frame types. USB- Physical interface, Enur ypes of transfers.less Applications:	A Hours ask management, Process achronization. Embedded 5 Hours Layered Architecture of neration process in USB, 4 Hours
Introduction to emu Module:3 Real RTOS vs General p Scheduling, Resourd software developme Module:4 Seria I2C- Features, Arbit CAN, properties, D Types of packets, T Module:5 Wire	logic circuit, ADC and DAC, Display units, Colators. time operating system (RTOS) with Kernel: urpose OS, Kernel Architecture and Functionalities - Take management (Semaphores and Mutex), Task Synent Life cycle. I Bus for embedded systems: tration, Bit Transfer Waveform and exceptions. CANata Rates, Frame types. USB- Physical interface, Enury systems	4 Hours ask management, Process achronization. Embedded 5 Hours • Layered Architecture of neration process in USB, 4 Hours , power levels, Device



Architecture objectives, Network model, ZigBee stack block diagram, Network layer. ZigBee Vs Bluetooth.

Module:6	Introduction to Moore an	d Mealy models	4 Hours
definition o		implementing Moore and M ansition diagram to state tab atroduction.	
Module:7	Embedded System Model	ling:	4 Hours
Finite State I	Machine (FSM) - Rules for	designing FSM, Design examined	mples implementing state and
state transitio	on diagram for vending mach	nine, ATM, digital lock.	
Module:8	Contemporary issues:		2 Hours
		Total Lecture hours:	30 Hours
Text Book(s)		
1. David	I.E. Simon, "An Embedded	Software primer", Pearson Ec	lucation Inc., 2012.
2. Tamn	ny Noergaard, "Embedded s	systems architecture: a comp	rehensive guide for engineers
and p	rogrammers" Berlin: Elsevie	er, 2014.	
Reference B	ooks		
1. Xiaco	ong Fan, "Real-time embedd	led systems: Design principle	es and engineering practices",
Amst	erdam [Netherlands]: Newno	es, 2015.	
2. Frank	Vahid and Tony Givargis,	"Embedded System Design:	A Unified Hardware/Software
Appro	oach", Wiley; Student editio	n, 2010.	
Mode of Eva	luation: CAT / Assignment /	/ Quiz / FAT / Project / Semin	nar
	ed by Board of Studies	05/03/2016	

40th AC

Date

Approved by Academic Council

18/03/2016



EEE4022		(Deemed to be University under section 3 of UGC Act, 1 Analog VLSI Design		L	T	P J	J C
				3	0	0 (0 3
Pre-requisit	e	EEE3002		Sylla	bus	ver	sion
Anti-requisi	te	NIL				v	. 1.0
Course Obje	ectives:						
		nd about various types of Analog systems, CM	1	ind osci	illat	ors.	
2. To un	Iderstan	d Applications of MOSFET in Analog device	es.				
	0						
Expected Co							
-		f this course the student will be able to:	was in siging of t	noncist	-		
		he characteristics of MOS and identify the iss based amplifier circuits with various configu		ransisu	JIS.		
		rential amplifiers using MOS for various appl					
C	·	based biasing circuit for electronics circuit a					
5. Desig	n Op-A	mp for linear ICs using CMOS.	11				
		ators using MOS devices.					
7. Desig	n charg	e pumps for boosting the signals using MOS	devices.				
Module:1		luction to Analog VLSI design:					ours
Basic MOS c	levice, l	/V characteristics, small-signal model, long-	channel and short	t chann	el d	evic	es.
<u></u>	G • 1					- 11	
Module:2		-Stage MOS Amplifier:					ours
		h resistive load, diode-connected load, curren	it source load, So	urce to	nov	ver,	
common gate	e, casca	de ampimer.					
Module:3	Differ	ential Amplifiers:				8 H	ours
		ferential operation, basic differential pair ana	lysis common m	nde re			Juis
-		MOS loads and Frequency response of Amp	-	1040 10	por	150,	
uniterentiar p							
Module:4	Curre	ent Mirrors:				5 He	ours
		rs, cascade current mirrors, Active current	mirrors- small s	signal a			
common mod				0		5	
	1 1						
Module:5	Opera	tional Amplifiers:				7 He	ours
Basic CMOS	Op-An	np, One stage Op-amps, Two-stage Op-Amps	s, Gain Boosting,	Noise	in ()p-A	mp.
Module:6	Oscilla	ators:				7 He	ours
Ring Oscilla	ators, L	C Oscillators, Voltage-Controlled Oscillators	•				
Module:7		-Locked Loops:				5 He	ours
Basic PLL, C	Charge-I	Pump PLLs, Non-ideal effects in PLLs.					
	C ·	•					
Module:8	Cont	emporary issues:					ours
		Total Lecture hours:			4	5 Ho	ours
Text Book(s)						



1.	Tony Chan C	Carusone David	A. Johns Kenn	eth W. Marti	n, "Computer System					
Architecture", John Wiley & Sons, Inc, Second Edition, 2012.										
2.	2. Behzad Razavi, "Design of Analog CMOS integrated circuits", Tata McGraw Hill,									
	Second Edition, 2003.									
Refere	nce Books									
1. Jaco	b Baker, "CMOS	S circuit design",	Wiley-IEEE press,	Third Edition,	2010					
Mode of	of valuation:	CAT I & II – 30	9%, DA I & II – 20	%, Quiz – 10%	, FAT – 40%					
Recom	mended by Boar	rd of Studies	05/03/2016							
Approv	ved by Academic	c Council	40 th AC	Date	18/03/2016					



		(Deemed to be University under section 3 of UGC Act, 1956)			<u> </u>		
EEE4024		Computer Architecture & Organization			T	P J	_
						0 0	
Pre-requisit		EEE3002	Sy	llał	ous		sion
Anti-requisi		NIL				V	. 1.0
Course Obj							
0		nderstanding of computer data representation and manipula					
2. To ur	nderstar	ad the basic organization for data storage and access across	various	mee	dia.		
Expected Co							
-		of this course the student will be able to:					
-	-	data flow between various modules of the computer and	data rej	ores	sen	tatio	n in
	us form						
		performance of processor and their interconnections. various arithmetic tasks and familiarize the various multipli	cation a	امم	ritk	ma	
		knowledge about floating point and decimal arithmetic's.	cation a	igu	1111		
-		arious register transfer functions and develop programs for	various	CP	U		
-	ization			•-	C		
U		various mapping techniques and familiarize the various data	transfer	me	ech	anis	m.
		functionality and issues of parallel and vector processing.					
Module:1	Fund	amental Concepts				4 He	ours
Introduction-	Gener	ation of Computer, Computer families and developments, I	Function	alı	uni	ts, B	asic
operational c	oncepts	s, Data Representation-Fixed point and Floating point numb	ers.				
Module:2	Intro	duction to computer architecture				5 H	ours
CPU organi	zation	by Vou-Newmann model, CPU transistor count-Moor	e's law	, P	erf	orm	ance
analysis of C	CPU, Ty	pical Mother board, interconnection of components.					
Module:3	Comp	outer Arithmetic				7 H	ours
Fixed-Point	Arithm	etic, Addition, Subtraction, Multiplication and Division	n, Com	oina	atic	nal	and
Sequential A	LUs, C	arry look ahead adder, Robertson algorithm, booth's algorithm	thm, M	odi	fiec	l bo	oth's
Algorithm.							
Module:4		ing point and Decimal Arithmetic				<u>3 H</u>	ours
Floating Poin	nt Arith	metic, Decimal Arithmetic unit-Decimal Arithmetic operation	ons.				
Module:5	Intro	duction to CPU Design				9 H	ours
Function of G	CPU, R	egister Classification and organization, ALU and control un	nit, instr	ucti	ion	set	with
examples, ad	ldressin	g modes, stack organization, Register Transfer, Bus and m	emory t	ran	sfe	rs, I	nput
- Output and	Interru	pt. Micro programmed control CPU design.					
Module:6		ory System Design and I/O Organization					ours
	-	niconductors, RAM memories, Read-only memories- Cache		•			
mapping- V	√irtual	memories. Introduction to buses and connecting I/O c	levices	to	CP	U a	ind



			su to be Oniversity under section 5 o				
memory-Pro	ogrammed	controlled I/O tra	nsfer- Interrupt co	ontrolled I/C	D transfer-DMA Controller.		
Module:7	Pipeline a	and Vector Proce	essing		8 Hours		
Introduction	to pipelinii	ng and pipeline ha	zards-design issu	es of pipeli	ne architecture-Instruction level		
parallelism a	nd advanc	ed issues-parallel	processing conc	epts-Vector	Processing, Array Processors,		
CISC, and RI	ISC & VLI	W.					
Module:8	Contem	porary issues:			2 Hours		
			Total Lecture h	ours:	45 Hours		
Editi2.	ion, 2016.	, Zvonks Vranesi			ture", Prentice Hall, Tenth Organization", McGraw Hill,		
Reference B	ooks						
1. David A.	Patterson	& John L. Henr	nessy, "Computer	Architectu	re: A Quantitative Approach",		
Elsevier, Fift	h Edition, 2	2012.					
Mode of valu	ation:	CAT I & II – 30	%, DA I & II – 20	%, Quiz –	10%, FAT – 40%		
Recommende	ed by Boar	d of Studies	05/03/2016				
Approved by Academic Council40th ACDate18/03/2016							
				•			



EEE4026	Digital Control Systems	L	T	P J	C
		2	0	0 4	1 3
Pre-requisite	EEE3001	Sylla	bu	s ver	sion
Anti-requisite	NIL			v	. 1.0
Course Objectives	8:				
2. To understa properties s	this course is to understand the discretization of continuous system and the discrete state space modelling of physical systems and to e uch as controllability, observability. The digital controller.		it th	le	
Expected Course	Outcome:				
On the completion 1. Visualise d	of this course the student will be able to: iscrete and continuous system e response of the discrete system.				
-	e stability of the discrete system.				
	ollability/ observability of a system				
-	d design digital PID controllers				
	analyze State variable methods				
	the mechanization of control algorithms omponent or a product applying all the relevant standards with rea	listic	cor	ıstrai	nts
Module:1 Intro	oduction:			4 H	ours
	n approaches, continuous versus digital control, sampling pro D/A conversion. Calculus of difference equations. Z-transfor				
	ility Analysis of discrete systems:			2 H	ours
	Jury's stability criterion, stability analysis through bilinear tra	nsfor	ms.		0000
F,					
Module:3 State	e variable analysis :			4 He	ours
State equations of	discrete data systems – State transition equations – Relationsl Fer functions - Characteristic equations – Eigen value – Eigen vec		etw	een :	state
Module:4 State	e Space Model Transformation:			4 H	ours
Diagonalization of State diagram – De	Matrix – Jordan canonical form – Methods of computing state the composition of discrete data transfer function. Controllability and the discrete data systems.			mati	rix –
Met				6 H	ours
Digital PID control	llers and frequency domain compensation design.				
Feed	gn of Digital Control Systems – State Iback Design:				ours
State variable meth problem.	ods - Pole placement design, Observer design and the discrete lin	ear re	egu	ator	



Module:7		Microprocessor Implementation:	Based	Digital	Contr	rol	3 Hours				
		-			algorith	ms. Ite	rative computation via parallel,				
direct, c	canon	ical, cascade realizat	tion. Case	studies.							
Module	e :8	Contemporary is	sues:				2 Hours				
				Fotal Lectu	ire hour	rs:	30 Hours				
Text Book(s)											
1.	1. K. Ogata, "Discrete-time control systems", Pearson, 2015.										
2.	G. F. Franklin, J. D. Powell and M Workman, 'Digital Control of Dynamic Systems' PHI										
	(Pea	rson), 2008.									
Referen	nce B	ooks									
1.	G. F	. Franklin, J. D. Pov	well and A	A. E. Naein	i, 'Feedł	back Co	ntrol of Dynamic Systems' PHI				
	(Pea	rson), 2015.									
2.	Loar	D. Landau, Gian	luca Zito	, 'Digital	Control	l Syster	ns, Design, Identification and				
		ementation' Springe				2					
3.	D. It	orahim, 'Micro-conti	roller base	ed Applied	Digital (Control'	John Wiley & Sons Ltd., 2006				
4.	.M.Gopal, "Digital Control Engineering", New Age Publishers, 2008.										
Mode o	of Eva	luation: CAT / Assig	gnment / (Quiz / FAT	/ Projec	t / Semi	nar				
Recom	mende	ed by Board of Studi	ies	05/03/2016							
Approv	ed by	Academic Council	4	40 th AC	D	ate	18/03/2016				



		Robo	otics and Co	ontrol			L	Т	P J	C
						_	2	0	0 4	3
Pre-requisite	EEE3001					5	Sylla	bus	s vers	sion
Anti-requisite	NIL								V.	1.0
Course Objectiv		1 1 1	· 1		. 1	.1 •	1			
 To devel motions To devel 	op the student's kn op student's skills & some knowledge op student's skills ge and skills associ	in perform and analys in perform	ning spatial sis skills ass ning kinem	transfo sociated atic an	rmations a l with traje	ssociated ctory pla	l wit nnin	h ri g.	-	-
Expected Cours										
 Select dif Apply spa Analyse f Derive Ja Identify th Generate Implement 	n of this course the ferent types of sensi- tial transformation orward and inverse cobian matrix and he dynamics of the joint trajectories for t the multivariable component or a pro-	to obtain t kinematics dentify sin robotic ma r motion pl controller	tuators for re- the forward is s for simple gularities. nipulator us lanning. for setpoint	obotic kinema robot sing Eu trackin	tic equation nanipulato ler Lagrang g and distu	rs. gian appi irbance r	roach reject	ion		
	troduction			ere vant	standards		15010	001	2 Ho	
workspace, End	effectors and Diff	erent types		s, vacu	um and ot	her meth	ods	of	gripp	ing.
workspace, End Pneumatic, hydr industrial robots.	effectors and Diffaulic and electric	erent types al actuators	of grippers s, application	s, vacu ons of	um and ot	her meth	ods	of	gripp diffe	ing. rent
workspace, End Pneumatic, hydr industrial robots. Module:2 Rig	effectors and Diffaulic and electric	erent types	of grippers	s, vacu ons of	um and ot	her meth	ods	of	gripp	ing. rent
workspace, End Pneumatic, hydr industrial robots. Module:2 Rig tra Position definition rotations and rel current frame, pa Homogeneous tra	effectors and Diffeaulic and electrica gid Motion nsformation ns. Coordinate fran ative motion, Cor rameterisation of mathematical nsformation	and and mes. Differ nposition c rotation, Eu	of grippers s, application Homogen rent orientation of rotation,	s, vacu ons of neous ion des rotatio	um and ot robots, sp criptions. I n with res	her meth pecificati Free vect spect to	ons ons	of of Tra	gripp diffe 5 Ho nslati ame	ing. rent ours ions and
workspace, End Pneumatic, hydr industrial robots. Module:2 Rig tra Position definition rotations and rel current frame, pa Homogeneous tra Module:3 Fo	effectors and Diff aulic and electrica gid Motion nsformation ns. Coordinate fran ative motion, Cor rameterisation of n nsformation rward Kinematics	and mes. Differ nposition contaction, Eu	of grippers s, application Homogen rent orientation of rotation, iler Angele,	s, vacu ons of neous ion des rotatio roll, p	um and ot robots, sp criptions. I n with res itch, yaw,	Free vect spect to axis/angl	ons ons cors. fixed le rej	of of Tra 1 fr	gripp diffe 5 Ho nslati ame entat	ing. rent ours ions and ion,
workspace, End Pneumatic, hydr industrial robots. Module:2 Position definition rotations and relicutions and relicutions and relicutions current frame, par Homogeneous tra Module:3 Fo Link coordinate field end effector Car different configured	effectors and Diffeaulic and electrica gid Motion nsformation ns. Coordinate fran ative motion, Cor rameterisation of mathematical nsformation	and mes. Differ nposition of rotation, Eu	of grippers s, application Homogen rent orientation of rotation, iler Angele, onvention.	s, vacu ons of neous ion des rotatio roll, p Assignmeters a	um and ot robots, sp criptions. I n with res itch, yaw, ment, of co and forwar	Free vect spect to axis/angl	tods ons cors. fixed le rej fran	of of Tra 1 fr pres	gripp diffe 5 Ho nslati ame entat 4 Ho Joint	ing. rent ours ions and ion, ours and
workspace, End Pneumatic, hydr industrial robots. Module:2 Rig tra Position definition rotations and rel current frame, pa Homogeneous tra Module:3 Fo Link coordinate end effector Car different configu Spherical Wrist a	effectors and Diffe aulic and electrica gid Motion nsformation ns. Coordinate fran ative motion, Cor rameterisation of n nsformation ward Kinematics rames. Denavit-Ha tesian space. Calc ration of manipula	and mes. Differ nposition contation, Eu artenberg contation of tor, Planne tion.	of grippers s, application Homogen rent orientation of rotation, iler Angele, onvention.	s, vacu ons of neous ion des rotatio roll, p Assignmeters a	um and ot robots, sp criptions. I n with res itch, yaw, ment, of co and forwar	Free vect spect to axis/angl	tods ons cors. fixed le rej fran	of of Tra 1 fr pres	gripp diffe 5 Ho nslati ame entat 4 Ho Joint	ing. rent ours ions and ion. and n of RA.
workspace, End Pneumatic, hydr industrial robots. Module:2 Rig tra Position definition rotations and relicutions and relicutions and relicutions and relicution rotations and relicutions and relicutions notations and relicutions and relicutions rotations and relicutions rotati	effectors and Diff aulic and electrica gid Motion nsformation ns. Coordinate fran ative motion, Cor rameterisation of 1 nsformation rward Kinematics frames. Denavit-Ha tesian space. Calc ration of manipula nd other configura	and mes. Differ nposition of cotation, Eu artenberg co culation of tor, Planne tion.	of grippers s, application Homogen rent orientation of rotation, aller Angele, onvention. A onvention. A onvention. A onvention. A onvention. A onvention. A	s, vacu ons of neous ion des rotatio roll, p Assign neters a anipula	um and ot robots, sp criptions. I n with res itch, yaw, ment, of co and forwar tor, Cylind	Free vect spect to axis/angl	fran atic ee lin	of of Tra 1 fr pres	gripp diffe 5 Ho nslati ame entat 4 Ho SCA 4 Ho	ing rent ours ions and ion and RA
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time tra	ajector	y, Trajectories for Paths Sp	pecified by Via P	oints. R	obot langua	ges, computer control			
and Ro	bot so	ftware							
Modul		Independent Joint Contro			Hours				
		amics, Set point tracking Fee	ed forward control	, Drive	Frain dynam	ics. Introduction to			
force co	ontrol	and multivariable control.							
Modul	e:8	Contemporary issues:				2 Hours			
Text B									
1.	revise edition, 2012								
2.	J.J. Craig, Introduction to Robotics: Mechanics and Control, Pearson Education, 4 th Edition, 2017								
3.		Groover, et.al., Industrial Re 2 nd indian edition, 2012.	obots: Technology	y, Progra	mming and	applications, McGraw			
Refere	nce B	poks							
1.		ot Manipulators : Modeling ma Khalil, Somerset : Wiley		nalysis a	nd Control.	by Etienne Dombre;			
2.		Tokhi, A K M Azad,Flexil on, 2017.	ble robot manipul	ator :mo	delling,simu	lation and control 2 nd			
3.									
Mode of	of Eval	luation: CAT / Assignment /	/ Quiz / FAT / Pro	ject / Ser	ninar				
Recom	mende	ed by Board of Studies	05/03/2016						
Approv	ved by	Academic Council	40 th AC	Date	18/03/20	16			



EEE4028		VLSI Design		L	Т	P J	C
				3	0	2 0	4
Pre-requisite	e e	EEE3002		Sylla	bu	s ver	sion
Anti-requisite	te	NIL				v	. 2.0
Course Objec	ctives:						
1. To pro	ovide a	n understanding of the digital VLSI concepts,	circuit design,	principle	es.		
-		ntroduction to architecture and design conce	epts underlyin	g moder	n c	ompl	ex
VLSI.							
		tudents with the background needed to design			tal	circu	its
		Hardware Description Language (VHDL) an					
4. 10 pro	ovide tr	he students to design the digital circuits using	transistors for	complex	sys	tems	•
Expected Cou	urse O	utcome:					
-		f this course the student will be able to:					
-		identify the methodologies for fabricating the	ICs.				
•		nd design arithmetic circuits using HDL.					
•		circuits using CMOS and its equivalent layou	t for fabricatio	on.			
e	0	characteristics of CMOS to reduce the delay a			los	ric	
circuit			I I I I I I I I I I I I I I I I I I I	1	- 2	, -	
5. Identif	fy trans	istor configurations for better performance in	logic circuits.				
6. Design	n mem	bry devices using transistors.					
7. Identif	fy and	design arithmetic circuits for various applicati	ons.				
8. Design	n and C	Conduct experiments, as well as analyze and ir	nterpret data				
Madada 1	0	· · · · · · · · · · · · · · · · · · ·				4 11	
		view of VLSI Design Methodology	Dhysical dasis	n lavou	- at	4 Ho	
custom, Semi		cocess, Architectural design, logical design, l	Physical desig	, n, nayou	l st <u></u>	/les,	гип
custom, Semi	custon	Tapproaches.					
Module:2	Intro	luction to Verilog HDL				6 Ho	ours
Introduction V	Verilog	HDL, Gate level, data flow, behavioral mode	ling, Data type	es and Op	bera	tors,	
Blocking and	non-bl	ocking assignment statements. Test benches.					
			<				
		luction to MOS Devices	6 Hours				
Introduction 4		S Transistor Theory: nMOS, pMOS Enhancen					~ ~
						s. M(JS
Switch, Thresh		bltage, MOS Device Design Equations, Body	effect, Second	order ef	tect		
Switch, Thresh Transistor Cir	rcuit M	odel. Stick Diagram, Layout Design Rules.	effect, Second	order ef	lect		
Switch, Threst Transistor Circ Module:4	rcuit M Circui	odel. Stick Diagram, Layout Design Rules.	effect, Second	order ef		6 Ho	ours
Switch, Threst Transistor Circ Module:4	rcuit M Circui Estim	odel. Stick Diagram, Layout Design Rules. it Characterization And Performance ation				6 Ho	
Switch, Thresh Transistor Cirr Module:4 DC Character	rcuit M Circui Estim eristics	odel. Stick Diagram, Layout Design Rules. A Characterization And Performance ation of CMOS Inverter, Switching Characterist	ics of CMOS	Inverte	г, Т	6 H o	istor
Switch, Threst Transistor Circ Module:4 DC Character Sizing Analyt	rcuit M Circui Estim pristics tical D	odel. Stick Diagram, Layout Design Rules. it Characterization And Performance ation of CMOS Inverter, Switching Characterist velay model- Rise Time, Fall Time. Gate D	ics of CMOS Delays, RC De	Inverte	г, Т	6 H o	istor
Switch, Threst Transistor Circ Module:4 DC Character Sizing Analyt Effort. Power	rcuit M Circui Estim ristics tical D Dissip	odel. Stick Diagram, Layout Design Rules. A Characterization And Performance ation of CMOS Inverter, Switching Characterist relay model- Rise Time, Fall Time. Gate D ation: Static- Dynamic-Short Circuit Power D	ics of CMOS Delays, RC De	Inverte	г, Т	6 H Fransi , Log	istor gical
Switch, Threst Transistor Cirr Module:4 DC Character Sizing Analyt Effort. Power Module:5	rcuit M Circu Estim ristics tical D Dissip Comb	odel. Stick Diagram, Layout Design Rules. A Characterization And Performance ation of CMOS Inverter, Switching Characterist relay model- Rise Time, Fall Time. Gate D ation: Static- Dynamic-Short Circuit Power D inational logic Circuits	ics of CMOS Delays, RC De Dissipation	Inverte lay Mod	r, T lels,	6 Ha Fransi , Log 6 Ha	istor gical
Switch, Threst Transistor Circ Module:4 DC Character Sizing Analyt Effort. Power Module:5 Introduction,	rcuit M Circui Estim oristics tical D Dissip Comb Static	odel. Stick Diagram, Layout Design Rules. it Characterization And Performance ation of CMOS Inverter, Switching Characterist elay model- Rise Time, Fall Time. Gate D ation: Static- Dynamic-Short Circuit Power D inational logic Circuits CMOS Design- Complex Logic Gates, Rat	ics of CMOS Delays, RC De Dissipation	Inverter elay Moc	r, T lels,	6 Ho Fransi , Log 6 Ho or Lo	istor gical ours ogic,
Switch, Threst Transistor Circ Module:4 DC Character Sizing Analyt Effort. Power Module:5 Introduction, Transmission	rcuit M Circui Estim ristics tical D Dissip Comb Static gate I	odel. Stick Diagram, Layout Design Rules. it Characterization And Performance ation of CMOS Inverter, Switching Characterist relay model- Rise Time, Fall Time. Gate D ation: Static- Dynamic-Short Circuit Power D inational logic Circuits CMOS Design- Complex Logic Gates, Rat Logic, Dynamic CMOS Logic Design: Dynamic	ics of CMOS Delays, RC De Dissipation ioed Logic, P unic Logic De	Inverter elay Moc ass-Trans	r, T lels, sisto nsic	6 Ho Fransi , Log 6 Ho or Lo lerati	istor gical ours ogic, ons.
Switch, Threst Transistor Cirv Module:4 DC Character Sizing Analyt Effort. Power Module:5 Introduction, Transmission Speed and Poy	rcuit M Circu Estim ristics tical D Dissip Comb Static gate I wer Di	odel. Stick Diagram, Layout Design Rules. it Characterization And Performance ation of CMOS Inverter, Switching Characterist elay model- Rise Time, Fall Time. Gate D ation: Static- Dynamic-Short Circuit Power D inational logic Circuits CMOS Design- Complex Logic Gates, Rat	ics of CMOS Delays, RC De Dissipation ioed Logic, P unic Logic De	Inverter elay Moc ass-Trans	r, T lels, sisto nsic	6 Ho Fransi , Log 6 Ho or Lo lerati	istor gical ours ogic, ons.



Static and D	Dynamic Latches and Registers, Timing issues, pipeli	ning
Module:7	Designing arithmetic circuits	9 Ho
		/ 110
11	le carry, Carry-Look ahead, Multiplier using Array b	
Save adder, N	Multiplier using Tree based-Wallace Tree, Dadda Tre	ee, Booth Multiplier, Squarer.
Modeling of	arithmetic circuits using HDL:	
Pipelined Mu	Itiplier and Accumulator, FIR filter design. Verilog	Coding for arithmetic circuits.

Mod	lule:8	Contempo	rary issues:				2 Hours	
				Total Lecture ho	urs:		45 Hours	
List	of Chall	enging Exp	eriments (Indic	cative)				
1.	Four b	it adder usin	g different appr	oaches for delay an	d Are	a reduction	2 Hours	
2.	Four B	it Wallace tr	ee multiplier				2 Hours	
3.	Four b	it dada tree 1	nultiplier				2 Hours	
4.	Four bi	t squarer des	sign				2 Hours	
5.	Multipl	ier and Accu	umulator design				2 Hours	
6.	FIR filter design						2 Hours	
7.								
8.	3. CMOS switch level implementation of adder and subtractor							
9.	Implem	entation of 1	Boolean function	n using various trar	nsisto	°S	2 Hours	
10.							2 Hours	
					Tot	al Laboratory Hour	s 30 hours	
Text	t Book(s))						
1	. Jan	Rabaey, Ar	antha Chandra	kasan, B.Nikolic,	"Dig	ital Integrated circu	its: A design	
	persp	ective". Sec	ond Edition, Pre	entice Hall of India	, 2013	3.		
2	2. Neil	H.E.Weste,	David Money	Harris, "CMOS	VLSI	DESIGN: a circuit	s and systems	
	persp	ective", Fou	rth edition, Pear	rson 2015.				
Ref	erence B							
1	. Sam	ir Palnitkar,	"Verilog HDL"	, Prentice Hall, 201	0.			
2	2. Sung	g-Ma Kong,	Yusuf Leblebi	ci and Chulwoo I	Kim,	"CMOS digital integ	grated circuits:	
	anal	ysis and desi	gn", 4th edition	, McGraw-Hill Edu	icatio	n, 2015.		
Mod	e of Eva	luation:	CAT I & II – 3	0%, DA I & II – 20	0%, Q	uiz – 10%, FAT – 40	%	
Reco	ommende	ed by Board	of Studies	05/03/2016				
Approved by Academic Council40th ACDate18/03/2016								

9 Hours



EEE4029		(Deemed to be University under section 3 of UGC Act, 19: Advanced Microcontroller	81	Ι	T	P J	C
				2		04	3
Pre-requisit	e	EEE4001		Syll	abus	vers	ion
Anti-requisi							1.0
Course Obj	ectives:						
		nphasis on the features of ARM Processors &		ntroller			
		ssential knowledge on various operating mode					
		inters, control register and the various types of	interrupts of t	hose			
	rocontro						
Expected Co		f this course the student will be able to:					
-		architecture of ARM processor					
		Peripherals of ARM processor					
	•	Program for processor peripherals					
	-	owledge to utilize the ARM processor for real	time applicati	ons			
5. Com	prehend	the architecture of PIC18FXX microcontrolle	r				
6. Deve	lop the	program for PIC18FXX microcontroller					
		IPLAB software to simulate PIC18FXX micro					
8. Desig	gn a con	nponent or a product applying all the relevant s	standards with	realistic	con	strain	ts
Module:1	Archi	tecture of LPC 21XX				3 Ho	urs
		of LPC 21XX architecture, Various registers of	f 21XX, ports	of LPC			
Module:2		ional Blocks of LPC 21XX	/ 1			4 Ho	urs
Timers, ADO	C and D	AC, Serial communication and Interrupt.					
Module:3	Progr	amming of LPC21XX Functional Blocks			(6 Ho	urs
Programmin	g of LP	C 21XX: GPIO, Timer, ADC, DAC, UART ar	d Interrupt.				
Module:4	Case	Studies				3 Ho	urs
		ising temperature sensor, generation of delay,	multitasking u	sing inte	rrup	t.	
		tecture of PIC 18FXX				3 Ho	urs
		hitecture—PIC18F Family, Programming Mod	lel and Its regi	sters.			
Module:6	Instru 18FX	iction Set & Functional Blocks of PIC X				6 Ho	urs
		hmetic, and Branch Instructions, Introduction	•	-			
·	ivide C	perations, Stack and Subroutines. Input/ou	tput (I/O) Po	orts, Inte	errup	ots ar	nd
Timers.							
						<u></u>	
Module:7		cation Programs	V			3 Ho	urs
		n, solving real time problems using PIC 18FX	Δ.			<u> </u>	
Module:8	Com	emporary issues:				2 Ho	
		Total Lecture hours:			3	0 Ho	urs
Text Book(s	•				•	<u> </u>	1
		Sloss, Dominic Symes, Chris Wright, "					
Des	igning a	and Optimizing System Software ", Morgan	Kaumann P	ublishers		editi	on,
200	0				, I	• • • • •	



2.	Muhammad Ali Mazidi , Rolin D. McKinlay, Danny Causey, "PIC Microcontroller and									
۷.										
	Embedded Systems Using Assembly and C for PIC 18", Prentice Hall, 2 nd Edition, 2009.									
Referen	nce Books									
1.	David Seal, "ARM Architecture Reference Manual ", Addison Wesley, 2 nd Edition, 2007									
2.	Peatman, "Designing with PIC Microcontroller", Pearson Education, 1 st Edition, 2011.									
3.	P.V Guruprasad, "Arm Architecture System on Chip and More ", Apress, 2013.									
4.	http://www.nxp.com/documents/user_manual/UM10114.pdf.									
Mode of Evaluation: CAT I & II -3			0%, DA I & II – 20%, Quiz – 10%, FAT – 40%							
Recommended by Board of Studies			05/03/2016							
Approved by Academic Council			40 th AC	Date	18/03/2016					



			Systen	n on Chip I	Design				L	ΓР	J	С
			J	Ľ	0				3 (0 0	4	4
Pre-requisite	e	NIL								0	s vei	rsion
Anti-requisit		NIL							~yn	avu		v. 2.1
Course Obje								1				1
0		n overview on t	the present of	lay design	techno	logy for	System	n-On-	Chip			
		d how various									twa	re,
		digital constru		C								,
	0											
Expected Co	ourse O	utcome:										
On the compl	letion of	f this course the	e student wi	ll be able to):							
1. Under	rstand tl	ne basics of So	C.									
		ign issues in pi										
-		complex SoC s	•									
	-	RTL coding for	-									
Ũ		erify the variou	0		C syste	em.						
		nowledge of p										
•		various routing				-						
8. Desig	n a com	ponent or a pro	oduct applyi	ing all the r	elevan	t standa	rds with	n reali	stic c	const	rain	ts
M 1	T 4				<u> </u>						2 11	r
Module:1		uction to SoC				C1					3 H	lours
Technology t	renas, a	lesign challeng	es, Overvie	W OF SOC L	esign 1	Flow.						
Module:2	SoC D	esign									7 H	ours
Hardware Sy				a .								Jours
			are structure	. Semicond	uctor F	Econom	ics. Ma	ior iss	sues i	n So	\mathbf{C}	
Design. Desig												
Design. Designultiple proc	gn for Iı	ntegration. Acc										
-	gn for Iı											
-	gn for In cessors.		elerating Pr								sign	lours
multiple proc Module:3	gn for In æssors. Systen	ntegration. Acc	elerating Pr	ocessor for	traditi	onal sof	tware t	ask. S	yster	n de	sign 5 H	
Module:3 Complex SoC	gn for In cessors. Systen C systen	ntegration. Acc	Processor co	entric SoC	traditi	onal sof	tware ta	ask. S	yster	n de	sign 5 H	
multiple proc Module:3 Complex So Hardware and	gn for In cessors. Systen C systen d Softw	ntegration. Acc n Level Desigr n architecture, 1 are interconnec	Processor co	entric SoC	traditi	onal sof	tware ta	ask. S	yster	n de	sign 5 H 1 –	ours
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Module:3Complex SocHardware andModule:4Review of V	gn for In cessors. Systen C systen d Softw RTL S 'erilog -	ntegration. Acc n Level Design n architecture, 1 are interconnec Synthesis • RTL Coding	elerating Pr Processor ce cts, Non-pro and RTL S	entric SoC	traditi organiz ding bl	onal sof	Communication Communication Communication Communication Contraction Contractication Contracticaticaticaticaticaticaticaticaticati	ask. S nicati ign.	on D	n de esigr	sign 5 H 1 – 8 H	ours
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			Total Lec	ture hours:		45 Hours
T (D						
Text B	` ´ ′					
1.	Chri	s Rowen, "Engineering th	ne Compley	x SOC: Fast,	Flexible Design with	Configurable
	Proc	essors", Pearson, 2004.				
2.	Rocl	nit Rajsuman, 'System-on-a	a-Chip: Des	ign and Test'	, Artech House, 2006.	
Refere	ence B	ooks				
1.	Prak	ash Rashinkar, Peter Paters	son, Leena S	Singh, "Syste	m on a chip verificatio	n: Methodology
	and	Verification", Kluwer Acad	lemic Publi	shers, 2013		
2.	Hima	anshu Bhatnagar, "Advance	ed ASIC Ch	nip Synthesis'	', Kluwer Academic Pr	ublishers, 2nd
	Editi	on, 2002.				
3.	Rao	Tummala, Madhavan Swar	ninathan , '	'Introduction	to System-On-Package	e:
	Min	iaturization of the entire sys	stem", McC	Braw-Hill, 1st	Edition, 2008.	
Mode of	of Eva	luation: CAT / Assignment	/ Quiz / FA	T / Project /	Seminar	
Recom	Recommended by Board of Studies 05/03/2016					
Approv	Approved by Academic Council40 th ACDate:18/03/2016				18/03/2016	



EEE4034		Wireless Sensor Networks		Т	P J	С
			3	0	0 4	4
Pre-requisite	e	EEE4021	Sylla	abu	s ver	sion
Anti-requisit	te	NIL			V.	1.0
Course Obje	ectives:		•			
1. To explore	e the ba	sic fundamentals in wireless sensor technology.				
2. To expose	the stu	dents to the recent advances in various wireless networks.				
3. To discove	er vario	us routing mechanism and the storage requirement for netwo	orking of	ser ?	isors.	
Expected Co	ourse O	utcome:				
		f this course the student will be able to:				
-		fundamentals and basic features of wireless sensor networks				
		alization and tracking techniques of wireless sensor network				
-		wledge about Medium access and sleep based control strates		vire	less	
channels						
		rious routing protocols, energy minimization and secur	ity issue	es i	n sei	nsor
networks						
		fundamentals of sensor tasking and control	~			
		storage management, retrieval and solve security challenge tance of wireless sensors security and reliability	S			
		nent or a product applying all the relevant standards with re-	alistic co	onst	raints	1
o. Design a	compo	nent of a product apprying an are role tant standards with re-		51150	runne	,
Module:1	Intro	luction:			8 Ho	ours
		ork architectural elements, Advantages of Sensor Netwo				
-		ds- Storage, search and Retrieval - Network Deployment				
		ment - Network topology- Connectivity in geometric	c rando	n	graph	.s -
Connectivity	using p	ower control-Coverage metrics- Mobile deployment				
Module:2	Locali	ization and Tracking :			6 Ho	ours
Localization	and Tr					
		U U	ization -	Tł	eore	
	calizati	racking – Localization approaches -Network-wide local on techniques-Tracking Methods	ization -	Tł	eore	
analysis of lo		racking – Localization approaches -Network-wide local on techniques-Tracking Methods	ization -	Tł		tical
		racking – Localization approaches -Network-wide local on techniques-Tracking Methods Im Access and Sleep Based Topology	ization -	Tł	eoret	tical
analysis of lo Module:3	Media Contr	racking – Localization approaches -Network-wide local on techniques-Tracking Methods Im Access and Sleep Based Topology			6 Ho	ical ours
analysis of lo Module:3 Medium Acc	Mediu Contr ess and	racking – Localization approaches -Network-wide local on techniques-Tracking Methods Im Access and Sleep Based Topology ol:	Access	-Co	6 Ho	ical ours ion-
analysis of lo Module:3 Medium Acc Based Mediu	Mediu Contr ess and im Acc	racking – Localization approaches -Network-wide local on techniques-Tracking Methods Im Access and Sleep Based Topology ol: Sleep Based Topology Control - Contention-Free Medium	Access	-Co	6 Ho	ical ours ion-
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Data-centric networking:

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Data-c	Data-centric networking- Data-centric routing -Data-gathering with compression - Querying -							
Data-c	entric	storage and retrieval- Th	e database perspe	ective on	sensor networks-sensor group			
manag	emen	t						
Module	Module:7Transport reliability and Security:5 Hours							
Transpo	ort rel	iability and Security - Basic	mechanisms and	tunable p	arameters- Reliability guarantees			
-Securit	y Att	acks in Sensor Networks - P	rotocols and Mech	nanisms f	or Security- Case Studies.			
Module	e:8	Contemporary issues:			2 Hours			
			Total Lecture he	ours:	45 Hours			
Text Bo	ook(s)						
1.	Bha	skarKrishnamachari, "Netw	orking Wireless S	Sensors",	Cambridge University Press,			
	201	l.	C					
2.	Ian I	Fuat Akyildiz, "Wireless ser	nsor networks", Ch	nichester	[u.a.] : Wiley, 2011.			
Referen	nce B	ooks						
1.	Dan	iel Minoli, TaiebZnati,K	azemSohra, 'Wi	reless S	ensor Networks: Technology,			
	Prot	ocols, and Applications' Joh	n wiley& sons, 20	007.				
2.	Feng	g Zhao, Leonidas. J.Gui	bas, 'Wireless S	Sensor N	letworks', Morgan Kaufamann			
	Pub	ishers, 2008.			-			
3.	Ivan	Stojmenovi, 'Handbook of	Sensor Networks:	Algorith	ms and Architectures', Hoboken:			
		Wiley & Sons, 2005.		-				
4.	Rag	havendra, C. S., Sivalinga	um, Krishna M.,	Znati, T	aie, Wireless Sensor Networks,			
	-	wer Academic publishers, 20						
Mode o		luation: CAT / Assignment		ject / Sen	ninar			
Recom	nende	ed by Board of Studies	05/03/2016					
		Academic Council	40 th AC	Date	18/03/2016			
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management.

Module:6

5 Hours



Image: standing virtual instrument concepts Virtual Instrument concepts 2 Developing Virtual Instrument concepts 2 Developing Virtual Instruments for practical works. 3 Analog and digital measurement principles 4 Data Acquisition operation Expected Course Outcome: On the completion of this course the student will be able to: 1 Analyse the analog and digital signals acquired from devices. 2 Design a component or a product applying all the relevant standards with realistic constraints List of Challenging Experiments (Indicative) 1 Basic arithmetic and boolean operations. 2 Program using SUBVI concept. 3 Wave forms & Graphs 4 Iterative data processing using (FOR,WHILE Loops, Formula Node.) 5 Case Structures. 6 Introduction to various tool boxes 7 Array and string operations. 8 Analog signals interfacing using DAQ. 9 Digital signals interfacing using DAQ. 9 Digital signals interfacing using DAQ. 1 Gary W. Johnson, Richard Jenning, "LabVIEW Graphical Programming", 4th /c, Tata	EEE4035	;		to be University under section 3 of V			L	T P J	C
Pre-requisite EEE4021 Syllabus verside Anti-requisite NIL v. 1 Course Objectives: v. 1 Understanding Virtual Instrument concepts v. 1 2. Developing Virtual Instruments for practical works. 3. Analog and digital measurement principles v. 1 4. Data Acquisition operation Expected Course Outcome: v. 1 0n the completion of this course the student will be able to: 1. Analys the analog and digital signals acquired from devices. 2. Design a component or a product applying all the relevant standards with realistic constraints List of Challenging Experiments (Indicative) 1 Basic arithmetic and boolean operations. v. 1 2 Program using SUBVI concept. 3 3 Wave forms & Graphs 4 4 Iterative data processing using (FOR,WHILE Loops, Formula Node.) 5 5 Case Structures. 6 6 Introduction to various tool boxes 7 7 Array and string operations. 8 8 Analog signals interfacing using DAQ. 9 9 Digital signals interfacing using DAQ. 1 <td< th=""><th></th><th>, </th><th>•</th><th></th><th></th><th></th><th></th><th></th><th></th></td<>		, 	•						
Anti-requisite NIL v. 1 Course Objectives: .	Pre-reau	isite	FFF4021				÷	-	1
Course Objectives: 1. Understanding Virtual Instrument concepts 2. Developing Virtual Instruments for practical works. 3. Analog and digital measurement principles 4. Data Acquisition operation Expected Course Outcome: On the completion of this course the student will be able to: 1. Analyse the analog and digital signals acquired from devices. 2. Design a component or a product applying all the relevant standards with realistic constraints List of Challenging Experiments (Indicative) 1 Basic arithmetic and boolean operations. 2 Program using SUBVI concept. 3 Wave forms & Graphs 4 Iterative data processing using (FOR,WHILE Loops, Formula Node.) 5 Case Structures. 6 Introduction to various tool boxes 7 Array and string operations. 8 Analog signals interfacing using DAQ. 9 Digital signals interfacing using DAQ. 10 NI ELVIS. Text Book(s) 1. Robert H Bishop, "LabVIEW", Pearson,2016. Reference Books <td< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td>Byna</td><th></th><td></td></td<>							Byna		
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Pre-requisite NIL Syllabus version Anti-requisite v.1.0 Course Objectives: v.1.0 1. This course exposes students to hands-on experience in the design and test of a wide variety of prototype electric and electronic systems hardware v.1.0 2. Engineering design by applying a combination of human creativity and modern computational tools to the synthesis of a simple component or system. Expected Course Outcome: On the completion of this course the student will be able to: 1. Design and Conduct experiments, as well as analyze and interpret data 1 Accumulator design in Verilog 2 MAC design in Verilog 2 MAC design in Verilog 2 MAC design in Verilog 3 HDL programming- Adder, Subtractor,Multplexer, Demultiplexer 4 Code converter 5 Shift register/Universal shift register 6 Upcounter/Downcounters 7 FIR filter 8 Array multiplier 9 Rapid Prototyping of Power Electronics Converters for Photovoltaic System Application Using Xilinx System Generator 10 10 Design Principles for Rapid Prototyping Forces Sensors Using 3-D Printing 11 11 Rapid Prototyping of a Low-Cost Solar Array Si	EEE40 3	37	Rapie	d Prototyping wi	th FPGAs			LT	P J			
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11 Applications 12 Rapid Prototyping of a Low-Cost Solar Array Simulator Using an Off-the-Shelf DC Power Supply 13 Rapid Prototyping of Miniature Capsule Robots 13 Rapid Prototyping of Miniature Capsule Robots Total Laboratory Hours 60 hours Reference Total Laboratory Hours 60 hours Reference 1. Chee Kai Chua, Kah Fai Leong, Chu Sing Lim Rapid Prototyping: Principles and Applications ,3rd Edition, Kindle Edition 2. Miltiadis Boboulas, CAD-CAM & Rapid prototyping Application Evaluation, Bookboon 3. R. C. Cofer Benjamin Harding , Rapid System Prototyping with FPGAs Recommended by Board of Studies	10	-				-		_				
12 Power Supply 13 Rapid Prototyping of Miniature Capsule Robots Total Laboratory Hours 60 hours Reference Books 1. Chee Kai Chua, Kah Fai Leong, Chu Sing Lim Rapid Prototyping: Principles and Applications ,3rd Edition, Kindle Edition 2. Miltiadis Boboulas, CAD-CAM & Rapid prototyping Application Evaluation, Bookboon 3. R. C. Cofer Benjamin Harding , Rapid System Prototyping with FPGAs Recommended by Board of Studies	11	-		g of Active Vit	oration Co	ntrol Syste	ems	in Ai	itomo	tive		
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Total Laboratory Hours 60 hours Reference Books 1. Chee Kai Chua, Kah Fai Leong, Chu Sing Lim Rapid Prototyping: Principles and Applications ,3rd Edition, Kindle Edition 2. Miltiadis Boboulas, CAD-CAM & Rapid prototyping Application Evaluation, Bookboon 3. R. C. Cofer Benjamin Harding , Rapid System Prototyping with FPGAs Recommended by Board of Studies	12	Power	r Supply									
Reference Books 1. Chee Kai Chua, Kah Fai Leong, Chu Sing Lim Rapid Prototyping: Principles and Applications ,3rd Edition, Kindle Edition 2. Miltiadis Boboulas, CAD-CAM & Rapid prototyping Application Evaluation, Bookboon 3. R. C. Cofer Benjamin Harding , Rapid System Prototyping with FPGAs Recommended by Board of Studies 10-05-2017	13	Rapid	Prototyping of Miniat	ture Capsule Robo	ots							
1. Chee Kai Chua, Kah Fai Leong, Chu Sing Lim Rapid Prototyping: Principles and Applications ,3rd Edition, Kindle Edition 2. Miltiadis Boboulas, CAD-CAM & Rapid prototyping Application Evaluation, Bookboon 3. R. C. Cofer Benjamin Harding , Rapid System Prototyping with FPGAs Recommended by Board of Studies				Total I	Laboratory	Hours			60 ha	ours		
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2. Miltiadis Boboulas, CAD-CAM & Rapid prototyping Application Evaluation, Bookboon 3. R. C. Cofer Benjamin Harding , Rapid System Prototyping with FPGAs Recommended by Board of Studies 10-05-2017	1.	Chee Kai	Chua, Kah Fai Lee	ong, Chu Sing	Lim Rapi	d Prototyp	ing:	Princi	ples	and		
3. R. C. Cofer Benjamin Harding , Rapid System Prototyping with FPGAs Recommended by Board of Studies 10-05-2017												
Recommended by Board of Studies 10-05-2017	2.	Miltiadis B	oboulas, CAD-CAM &	& Rapid prototypi	ng Applica	tion Evalua	ation,	Book	boon			
	3.	R. C. Cofer	Benjamin Harding , F	Rapid System Prot	otyping wi	th FPGAs						
Approved by Academic Council53 th ACDate13-12-2018	Recomm	Recommended by Board of Studies 10-05-2017										
	Approve	ed by Acade	mic Council	53 th AC	Date	13-12-201	8					



(Deemed to be University under section 3 of UGC Act, 1956)						
EEE4038		Testir	ng and Calibration	on Systems	6	L T P J C
	_					0 0 2 0 1
Pre-requi		EEE4021/EEE2004				Syllabus version
Anti-requ		NIL				v. 1.0
Course O						
1. ′	To explore	e the basic concepts ar	nd terminology of	testing and	l calibration s	systems.
Expected	Course O	outcome:				
On the cor	npletion o	f this course the stude	nt will be able to:			
1	. Design a	and Conduct experime	ents, as well as and	alyze and ir	nterpret data	
List of Ex	periment	S				
1	Perform	a comparative experies eight Pressure Gauge (-			
2	an experi	the errors and estimation the errors and estimation the errors and estimation the errors and estimate	ration of pressure	gauge to o	vercome the	same.
3	estimatic	an experimental stu on of uncertainties dur	ing flow measure	ment.		-
4		uncertainty calculation ing multifunctional ca	-			
5		a verification and ver. Perform uncertainty			wattmeter a	and a single-phase
6	kettle be	re and calibrate the g tween 25°C to 250°C.	Perform uncertai	nty analysi	s.	
7	temperat	a calibration and un ure of a system betwe	en 25°C to 150°C	•		
8	measurer	a verification and van ment uncertainty for the	ne same.		-	humidity. Perform
9		an experiment for RT				
10	Conduct	an experiment for tor	que transducer cal	ibration an	d check the e	errors
			Tot	al Laborat	ory Hours	30 hours
Reference	Books					
1. (Calibration	Handbook of Measur	ring Instruments b	y Alessand	lro Brunelli ,I	Ist Edition,ISA.
2.cti	on to Mea	suration and Calibration	on by Paul.D.Q. C	Campbell Ir	dustrial Press	s Inc
	ensors and /iley India	l Signal Conditioning	by Ramon Pallas-	Areny/Joh	n.G.Webster	, Second Edition,
Mode of E	valuation	CAT / Assignment /	Quiz / FAT / Proj	ect / Semin	nar	_
Recomme	nded by B	oard of Studies	13-10-2018			
Approved	by Acade	mic Council	53 rd AC	Date	13-12-2018	



MEE1006	Applied Mechanics and Thermal Engineering L T P J C							
Pre-requisite	ite NIL Syllabus version							
		2	.1					
Course Objectives:								
1. To make the	students to understand the principles of solid me	echanics.						

- 2. To make the students to understand the basic concepts of mechanical vibrations.
- 3. To familiarize the students with the properties of fluids and the applications of fluid mechanics.
- 4. To make the students to understand the principles of thermodynamics and to get broad knowledge in its applications.
- 5. To provide the students a gist of the theory behind the refrigeration and air conditioning system.
- 6. To make the students to understand the principles of heat transfer.

Expected Course Outcome:

Student will be able to

- 1. Evaluate the allowable loads and associated allowable stresses before mechanical failure in different types of structures.
- 2. Assess the vibrations associated with various mechanical systems.
- 3. Apply the fundamental laws of thermodynamics for the analysis of wide range of thermodynamic systems.
- 4. Explain basic concepts of fluid mechanics and their applications.
- 5. Demonstrate and analyze various refrigeration and air conditioning systems.
- 6. Evaluate heat transfer through different modes.

Module 1	Solid Mechanics			5 hour		
Concept of	stress and strain-Normal and shear stress -relation	ionship betwe	en stress	and strain-		
Elasticity-	poisson's ratio-shear force and bending momen	t diagrams fo	or simply	supported,		
cantilever an	cantilever and overhanging beams - Analysis of forces in truss members					

Module 2 Mechanical Vibrations	5 hour						
Single degree of freedom systems- Un-damped and damped- Na	tural frequency- transverse vibration						
of shafts- critical speed by Rayleigh's and Dunkerley's method.	of shafts- critical speed by Rayleigh's and Dunkerley's method. Forced vibration-Harmonic						
excitation-Magnification factor- Vibration isolation-Torsional vibration-Holzer's analysis.							

Module 3	Fluid Mechanics		4 hour				
Properties of	Properties of fluid- Uniform and steady flow- Euler's and Bernoulli's Equations- pressure losses						
along the flo	w. Flow measurement- Venturi meter and Orifice	meters, Pipes	in series and parallel.				
Introduction	to Turbines and pumps - classification of tur	rbines - speci	fic speed and speed				
governance.	Classification of pumps- characteristics and efficient	ncy.					
Module 4	Thermodynamic systems		3 hour				
Basic concepts of Thermodynamics - First law of thermodynamics- Second law of thermodynamics							
- applications. Working Principle of four stroke and two stroke engines - Open and closed cycle gas							
turbines							

Module 5Steam Boilers and Turbines3 hourFormation of steam – Thermal power plant – Boilers -Modern features of high-pressure boilers -



0	and accessories - S		•		on principle.	1
Module 6	Compressors, conditioning	Refrigeration		Air		5 hour
Basic functi	-	on-Vapour Comp	ression a	-	-	al flow compressors - n systems-Principle of
	ing system- Type					
Module 7	Heat Transfer					3 hour
						convection and forced r and transformers
Module 8	Conte	emporary Discus	sion			2 hour
		Total hours			30 hour	
-	ped Class Room, t to Industry, Min		-		e of physical	cut section models to
Practical E		·		•		
	n of Engineering S	Stress / Strain Dia	gram on S	Steel ro	d, Thin and Ty	visted Bars under
tension.			-			
2. Compress	sion test on Bricks	Concrete blocks.				
3. Natural fi	requency of longitu	idinal vibration of	spring n	nass sys	stem.	
	ation of torsional v	-	•	-	or system	
-	d free vibration of		-	stem		
-	vibration of equiva	lent spring mass s	system			
	ugh Venturimeter					
	ough Orifice Meter on of Bernoulli's					
	ance test on air-co					
	ance test on vapou	•••		n syster	n	
	nsfer in natural/for		ingerution	i systen		
	nsfer through a con					
Mode of Ev		1	Continu	ous As	sessment inclu	des CAT I, CAT II,
			Assignm	nents/Q	uizzes, FAT	
Text Book (/					
, ,	aiput. (2010). The	1	T alzalara			
,	ujput, (2010), 111	rmal Engineering	, Laksnin	i Publie	cations	
1.R.K. RReference I	Books					
R.K. R Reference I 1. Roge	Books	Engineering Ther				at Transfer', Addisior
1. R.K. R Reference I 1. Roge Wesh	Books rs and Mayhew, '	Engineering Ther 99.	modynan	nics – Ť	Work and Hea	at Transfer', Addisior 98.
1.R.K. BReference I1.RogeWesle2.B.K.	Books rs and Mayhew, ' ey, New Delhi, 19	Engineering Ther 99. Enginerring', Tata	modynan McGraw	nics — ` ⁷ Hill, N	Work and Hea	98.



5.	R.K. Rajput, (2006), Strength of materials (Mechanics of solids),	S. Chand & Company Ltd.
6.	P.K. Nag, 'Basic and Applied Engineeri Delhi,2010.	ng Thermodynamics	', Tata McGraw Hill, New
7.	B.K. Sachdeva, 'Fundamentals of Engineer International (P) Limited (2009).	ing Heat and Mass Tr	ransfer (SI Units)', New Age
8.	C.P. Arora 'Refrigeration and Air Condition	iing', Tata McGraw H	Hill (2001).
	Recommended by Board of Studies	17.08.201	7
	Approved by Academic Council No. 47 ⁴	h AC Date	05.10.2017



ECE3501	(Deemed to be University under section 3 of UGC Act, 1956)	L	Т	P	J	С
	Job Role: SSC/Q8210	2	0	2	4	4
Pre-requisite	NIL		1		_	-
Tre requisite		Syllabus version v.1.0				
Course Objective	s:					
technologies 2. To analyse, d 3. To explore th	owledge on the infrastructure, sensor technologies and net of IoT. esign and develop IoT solutions. e entrepreneurial aspect of the Internet of Things concept of Internet of Things in the real world scenarios	wor	king			
Expected Course	Outcome: y completing the course the student should be able to					
	nain component of IoT					
	controller and sensor as part of IoT					
3. Assess differ	ent Internet of Things technologies and their applications					
Module:1	Introduction:			2 hou	r	
IT-ITeS/BPM Indu	Istry – An Introduction, the relevance of the IT-ITeS sector	or, F				_
	General overview of the Future Skills sub-sector	,				
Module:2	Internet of Things - An Introduction:		3	hou	irs	
Evolution of IoT a and applications a	nd the trends, Impact of IoT on businesses and society, E_{λ} cross industries.	kisti	ng Io	oT u	se ca	ases
Module:3	IoT Security and Privacy:		6	hou	irs	
	cy risks, analyze security risks, Technologies and methods tandards and regulations, Social and privacy impacts	s tha	at mi	tiga	te	
Module:4	IoT Solutions		6	hou	Irs	
Planning for IoT	opment, Need and Goals for IoT solution, Adoption of Io			ons,		
	ed for stakeholder buy-in					
			5	hou	irs	



		d to be University under section 3 of	UGC Act, 1956)			
Module:6	Scalability of IoT	Solutions:			5 hours	
	eloping complete IoT Solutions, Methods,					
Module:7	Build and Maintai Team Empowerm	-	at the Wor	·kplace,	3 hours	
	Total Lecture h	ours:			30 hours	
Text Book(s)						
-	Bahga, Vijay Madisetti Press, 2015.	, "Internet of Thir	igs: A han	ds-on Appr	roach",	
	Ewen & Hakim Cassin	nally, "Designing	the Interne	et of Thing	s", Wiley,Nov	
	land, Elizabeth Goodi Connected Products: U 15					
Reference Books	5					
Francis da	the Internet of things: Costa, Apress, 2014			_	verything by	
	nternet of Things by P					
Private Lin		-		Cassimally	, Wiley India	
	puting, Thomas Erl, H					
Stallings, A	s of Modern Network Addison-Wesley Profe	ssional; 1 edition			William	
1	cindia.org/sites/default %20Specialist_09.04.		210_V1.0_	_Io		
List of Experime	ents					
2. Control ye	he light intensity in th our home power outle eb based application to on	t from anywhere u	sing raspb	erry pi.		
0	water monitoring and	analytics, consists	of IoT dev	vice, cloud	, and mobile and	
	Healthcare applicatio		1			
 8. Traffic pa 9. Smart Street 	0	oring and weather	prediction			
10. Plant heal	th monitoring		Total Lab	oratory Us	ours 30 hours	
Recommended by	y Board of Studies		TOTAL Lab	oratory Ho	JUIS JUIIOUIS	
Approved by Aca			Date			
			Luit	1		



ECE3502	IoT Domain Analyst	L	Т	P J	C	
	Job Role: SSC/Q8210	2	0	2 4	4	
Pre-requisite		Syllabus version				
~ ~ ~ ~ ~ ~ ~				V	1.1.0	
Course Objectives						
-	ledge on the infrastructure, sensor technologies and net	tworki	ng te	chnolog	gies	
of IoT.	an and decode a Letter decision					
	gn and develop IoT solutions. ntrepreneurial aspect of the Internet of Things					
	acept of Internet of Things in the real world scenarios					
	teept of internet of Things in the fear world scenarios					
Expected Course (Jutcomo:					
	y completing the course the student should be able to					
	nain component of IoT					
	controller and sensor as part of IoT					
	ent Internet of Things technologies and their application	ns				
Module:1	IoT Solution Models:		3 ho	our		
Models applied in I	oT solutions, Semantic models for data models, Application	ation of	of sen	nantic		
	n models, information models to structure data, relations				a	
categories.		-				
Module:2	Data Models :		3 ho	urs		
Tags to organize da	ta, tag data to pre-process large datasets, predictive mod	dels fo	or fore	ecasting	g,	
Application of pred						
Module:3	Simulation Scenarios:		4 ho			
	real-world scenarios, Application of the models, stages	of dat	ta life	cycle,		
	olutions, reusability plan.					
Module:4	Use Case Development		4 ho	urs		
Approaches to gathe	er business requirements, defining problem statements,	busin	ess re	quirem	ients	
for use case develop	oment, Assets for development of IoT solutions.					
Module:5	Value engineering and Analysis:		4 ho	urs		
	es of Value Engineering and Analysis, Frameworks for		0		0	
	function analysis of IoT solution components, action	-		-		
	, Data modelling requirements, Development mode			-	gile,	
-	onetization models for IoT use cases - 'Outcomes As A	<u>A</u> Serv				
Module:6	Data Analytics for IoT Solutions:		6	hours		
	ta gathering, Data Pre-processing, data analyzation, ap	plicati	on of	analyti	ics,	
	orithms, Exploratory Data Analysis.	<u> </u>				
Module:7	Deployment of Analytics Solutions		6	hours		
	and Data Clustering, Predictive Analytics and Streami					
cloud/edge methods, integrating analytics models, performance of analytical models, Templates						
for data insights, deriving insights.						
				1		
	Total Lecture hours:		30	hours		
Text Book(s)						



	Arshdeep Bahga, Vijay Madisetti, "Internet of Things: A hands-on Approach", University Press, 2015.
	Adrian McEwen & Hakim Cassimally, "Designing the Internet of Things", Wiley, Nov
	2013, (1 st edition)
3.	Claire Rowland, Elizabeth Goodman, Martin Charlier, Ann Light, Algred Lui,"
	Designing Connected Products: UX for the consumer internet of things", O'Reilly, (1 st
	edition),2015
Referer	nce Books
1.	Rethinking the Internet of things: A Scalable Approach to Connecting Everything by
	Francis daCosta, Apress, 2014
	Learning Internet of Things by Peter Waher, Packt Publishing, 2015
	Designing the Internet of Things, by Adrian Mcewen, Hakin Cassimally, Wiley India
	Private Limited
	Cloud Computing, Thomas Erl, Pearson Education, 2014
5.	Foundations of Modern Networking: SDN, NFV, QoE, IoT, and Cloud, William
	Stallings, Addison-Wesley Professional; 1 edition
6.	https://nsdcindia.org/sites/default/files/MC_SSCQ8210_V1.0 IoT- Domain %20
	Specialist_09.04.2019.pdf
List of	Experiments
	Measure the light intensity in the room and output data to the web API.
2.	Control your home power outlet from anywhere using raspberry pi.
3.	Build a web based application to automate door that unlocks itself using facial
	recognition.
4.	Drinking water monitoring and analytics, consists of IoT device, cloud, and mobile and
	web app.
	Smart Parking System
	IoT based Healthcare application
	Real-time environmental monitoring and weather prediction
	Traffic pattern prediction
	Smart Street light
10.	Plant health monitoring
Deser	Total Laboratory Hours 30 hours
	nended by Board of Studies
Approv	ed by Academic Council Date